

500 SERIES

INSTALLATION & SERVICE MANUAL

PLEASE LEAVE ON VESSEL



HOLDS THE COURSE YOU GIVE IT

PRINTED IN U.S.A.



WOOD FREEMAN AUTOMATIC PILOTS

WOOD FREEMAN® AUTOMATIC PILOTS ******** 500 SERIES

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METAL MARINE PILOT, INC. 2119 MILDRED STREET WEST TACOMA, WASHINGTON 98466 (206) 564-5902



WARNING

A qualified MAN ON WATCH is LEGALLY REQUIRED whenever vessel is UNDERWAY.

WOOD FREEMAN Autopilots are NAVIGATIONAL AIDS designed (when installed in accordance with instructions furnished), to assist the man on watch to maintain the average course which he selects.

These Autopilots are NOT designed nor approved to replace the man on watch, nor relieve him of the responsibilities required by the Rules of the Road for maintaining a good lookout or for continual safe navigation of the vessel.

Activate autopilot only in open waters, well clear of other vessels or obstructions, and monitor heading at all times.

Be prepared to resume manual steering and inactivate autopilot immediately in the event that

- (a) Chosen heading is not maintained.
- (b) An unscheduled change of heading occurs. (See Par. VIII (3) of Limited Warranty)
- (c) Any situation arises wherein continuing set course might put vessel in jeopardy.

LIMITED WARRANTY

LIMITED WARRANTY APPLIES TO ALL PRODUCTS OF METAL MARINE PILOT, INC.

- I. The Warrantor is METAL MARINE PILOT, INC., of 2119 Mildred Street West, (67th Avenue West), Tacoma, Washington 98466: Telephone (206) 564-5902
- II. This warranty shall extend only to the original purchaser of the equipment.
- III. The warranty registration card must be returned to Warrantor at the address indicated above before there will be any warranty coverage service for the equipment
- IV. This warranty applies to all equipment manufactured by or bearing the nameplate of Metal Marine Pilot, Inc., and Warrantor warrants all such equipment to be free from defects in workmanship or material under normal use and service.
- V. This warranty is in effect for a period of twelve (12) months from the date the equipment is shipped from the factory.
- VI. 1. If any part of the equipment proves to be defective in workmanship or material, the Warrantor will examine said equipment after it is returned to Warrantor as hereinafter stated, and
- 2. If the returned equipment is found by the Warrantor to be defective in workmanship or material, the equipment will be repaired or replaced at the above address of Warrantor's place of business without charge, except for transportation charges as herein provided, and there will be no option for the purchaser to receive a refund of the purchase price until after a reasonable number of attempts to remedy the defect have been made by the Warrantor.
 - 3. Only persons expressly authorized by Warrantor shall be permitted to perform warranty service.

- VII. 1. If purchaser believes any part of the equipment is defective, he shall return said part within twelve (12) months of the date of purchase to the Metal Marine Pilot, Inc. factory at the address herein provided.
- 2. The expense of transporting the defective equipment to the Warrantor's factory and the expense of returning the repaired or replaced equipment shall be paid in advance by the purchaser.
- VIII. 1. There are no warranties which extend beyond the description on the face hereof. This warranty is expressly in lieu of all other warranties, guarantees, obligations or liabilities expressed or implied, by the Warrantor or its representatives. All statutory or implied warranties, other than title, are hereby expressly excluded. This warranty will not apply where the purchaser or others have misused or abused or failed to normally service the equipment and Warrantor will not be liable for any damages of any kind caused by such misuse, abuse or lack of service.
- There is no warranty coverage of any kind for defects or damage due to water immersion or salt spray, except for equipment which is designated as waterproof, and equipment so designated is warranted as set forth in Paragraph VI herein.
- 3. There is no warranty and Warrantor shall not be held liable for any damages incurred as a result of a malfunction of any part of Warrantor's products if said damages occur during or as a result of the autopilot being left unattended by the operator. Warrantor will not be liable for any damages arising from collisions with other vessels or objects. The autopilot product, including parts thereof, is designed to assist the operator or the man on watch to navigate accurately by maintaining an average course selected by the man on watch. The Warrantor's product is not designed to, and does not, replace the man on watch. Due to the potential of a collision with an object in the vessel's path or of an electrical, mechanical, or hydraulic malfunction of the parts of the autopilot or the associated equipment of the vessel, the energized pilot should never be left unattended when the vessel is moving.
 - 4. There is no warranty for model Nos. 11, 15, 150 and 420 if they are used on any hydraulic steering gear.
- 5. The sole remedy available to the purchaser if there is a defect in material or workmanship of the equipment is as set forth in Paragraph VI.
 - 6. The Warrantor assumes no liability for incidental or consequential damages of any kind.
- IX. The Purchaser's obligation in the event of defect are to:
 - 1. Prepare a written detailed statement of the defect;
 - 2. Deliver the written statement to Warrantor's factory at the above indicated address;
 - 3. Deliver or arrange for the delivery of the equipment to Warrantor's factory; and
- 4. Arrange for the return of the equipment from Warrantor to purchaser by either agreeing to pick up the equipment at Warrantor's factory or by depositing with Warrantor sufficient funds to pay to have the equipment delivered to purchaser by means of commercial transportation.
- X. Purchaser hereby agrees that he has read the above and understands that the above Warranty sets forth the exclusive warranty for this equipment.

January, 1978

METAL MARINE PILOT, INC.

2119 Mildred Street West (67th Ave. West)
Tacoma, Washington 98466
Telephone: Area Code 206 564-5902
R. M. Freeman, President

RETURN TO: METAL MARINE PILOT, INC. 2119 MILDRED STREET WEST TACOMA, WASHINGTON 98466 (206) 564-5902

WOOD FREEMANS AUTOMATIC PILOTS

VESSEL EVALUATION DATA

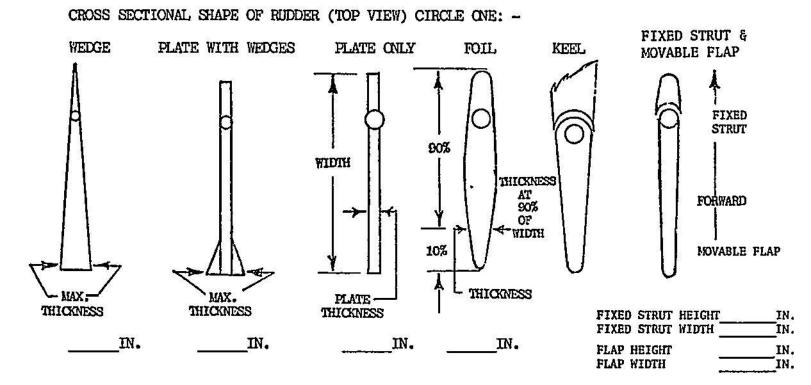
	SECTIONS REQUIRED				SECTIONS OPTIONAL
ALL PILOT ORDERS	A		D	E	C
ALL HYDRAULIC STEERING	A	B*	D*	E*	C
RUDDER STEERING EVALUATION	A	B	D	E	C

* ON REPEAT ORDERS FOR STOCK VESSELS FOR WHICH MANUFACTURER'S SPECIFICATIONS HAVE BEEN FURNISHED, THESE ITEMS MAY BE OMITTED BY GIVING NAME OF MANUFACTURER, MODEL NAME, AND HULL NUMBER IN SECTION A.

	ECTION A FOR ALL PILOTS
MODEL REQUIRED	DATE
DEALER'S NAME:	CITY, STATE:
PO #:	
	CITY, STATE & ZIP
VESSEL'S LENGTHFT. BEAMFT. DRAFT	FT. TOP SPEED KNOTS POWER SAIL
VESSEL'S NAME OR MFG. HULL NUMBER	MANUFACTURER
	ABLE: 12V DC 24V DC 32V DC 115V AC
TYPE OF STEERING: MECHANICAL: HYDRAULIC:	(COMPLETE SEC. B) OTHER (SPECIFY):
HARDOVER - WHEEL TURNS DEGRE	SES OF RUDDER TRAVEL
CHECK IP FIXED KORT NOZZLENOZ	ZZLE DIAMETER (INCHES)
<u>s</u>	SECTION B
HYDRAULIC STEERING SYSTEM.	OR ALL HYDRAULIC STEERING. (X) NUMBER OF CYLINDERS:
COMPLETE THE FOLLOWING - IP SYSTEM IS CUSTOM OR I	
	METER:IN. STROKE:IN. ROD DIAMETER:IN.
TILLER ARM - FROM CENTER OF RUDDER STOCK TO CYLIN	
HELM UNIT - MFG.	\$5:8:100.000000000000000000000000000000000
	INIT - GPM MIN. GPM MAX.
	SECTION C
	COMPLETE OUR RECORDS:
IS REMOTE COURSE CHANGE REQUIRED? YES	100
IS 500 SERIES AUTOPILOT COMPASS WANTED FOR A STEE	ERING COMPASS? YESNO
NEW VESSEL EXISTING VESSEL VESSEL'S USE: COMMERCIAL PLEASURE VESSEL'S MATERIAL: WOOD GLASS STEEL PILOT HOUSE MATERIAL: WOOD GLASS STEEL	
PRIMARY REQUIREMENT FOR AUTOPILOT: CRUISING COURSE HOLDING RAPID MANEUVERING DRAGGING LONGLINING LOBSTERING OTHER	G CRABBING GILLNETTING SEILING TROLLING (SPECIFY)
MAKE AND MODEL OF EXISTING AUTOPILOT	NONE

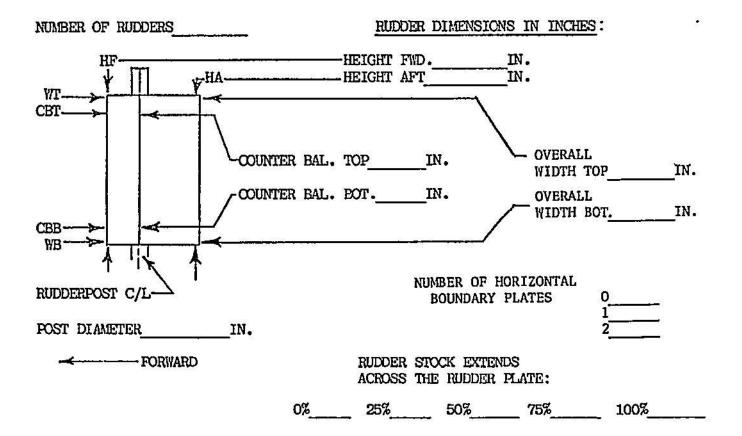
SECTION D

REQUIRED FOR ALL PILOT ORDERS OR IF RUDDER EVALUATION IS DESIRED.



SECTION E

REQUIRED FOR ALL PILOT ORDERS OR IF RUDDER EVALUATION IS DESIRED.



PAGE 1

DESCRIPTION OF WOOD FREEMAN® 500 SERIES AUTOMATIC PILOTS

SECTION B

Reference Block Diagram 5006008

The Model 500 WCOD FREEMAN® AUTOMATIC PILOT is steered by a magnetic compass. Magnetically sensitive Hall-Effect crystals are used for sensing a vessel's deviation from the set course on the magnetic compass, and also, for detecting movement of the rudder from the center line position. There is no reaction of the sensing system to disturb the compass magnets. The information sensed by Hall-Effect crystal HGC-1 passes through course error amplifier I.C.401. Crystal HGC-2 information passes through Rudder Angle amplifier I.C.201. Outputs of I.C.401 and I.C.201 are compared in a two-channel amplifier (Left-Right Rudder Servo Driver) which triggers steering engine to produce Right or Left Rudder movements until rudder signal matches the compass signal.

A "RUDDER DIAL" system on the Console and remotes allows direct dialing of rudder position for power steering. The final output drive to the steering engine gives a Left-Stop-Right signal from mercury relays L-5 and L-6 capable of handling 20 amps D.C. Automatic provision is made for sensing and correcting for vessel's turn rate. Sensitivity, permanent helm, rudder follow-up ratio, and "anti-hunt" controls allow operator adjustments of these features when required.

VESSEL HEADING CIRCUITS

Turns of the vessel from the pre-set compass course (compass magnets) develop in HGC-1 a D.C. voltage which is proportionate to the course error angle. The polarity of the voltage is determined by the direction of turn from the course. This signal is linearly amplified by course error amplifier.

A portion of I.C.401 output passes to the rate of change of the vessel's heading with respect to the set course (the rate of the vessel's swing). The amplified course error information from I.C.401 passes through "Rudder" Amplitude Control (RV803) and this is combined with the rate information from I.C.402 through "Counter Rudder" Amplitude Control (RV804) and fed to the two-channel amplifier as a compass control signal. The combined position and rate command signal from the compass circuits provide automatic course correction without overswing, even in a following sea. "RUDDER" amplitude control proportions the compass signal to produce a variable coupling ratio between the compass and the rudder. "COUNTER RUDDER" amplitude control proportions the rate signal. The rate signal then recombines with error signal to produce the compass command signal.

RUDDER POSITION CIRCUITS

A voltage corresponding to rudder angle is generated by HCC-2 in the Encoder. This voltage is amplified by the rudder angle amplifier and enters the feedback input of the two-channel Amplifier (Left-Right Rudder Servo Driver and NULL DAMPER). A portion of the output from the rudder angle amplifier is fed through a resistor to an optional Rudder Angle Indicator which provides a continuous, accurate indicator of the rudder position.

Rudder Position Circuits - continued

When compass command voltage exceeds the rudder feedback voltage by more than the "NULL" voltage (set by "NULL" control), a "left rudder" signal is sent through L-1 and L-6 to steering engine. Conversely, if command signal is positive, a "right rudder" signal occurs. In this manner a control of the rudder position which is a function of vessel's course error and rate and direction of swing is obtained.

"RUDDER DIAL" POWER STEERING

A "RUDDER DIAL" potentiometer (RV802) is furnished on the Console for a manually controlled "command" input thus producing full-followup power steering. The Control Console function switch provides this change of function and also allows transfer of control to a remote "RUDDER DIAL".

NULL DAMPER Steering Engine "Anti-Hunt"

Since no steering engine stops immediately on signal, and "coasting" will increase as speed increases, a circuit called a "NULL DAMPER", which ordinarily is adjusted at the time of installation, provides compensation for the speed of the steering engine so that fast steering engines are prevented from "hunting" (overtravelling the 'NULL" and continually oscillating from side to side). With proper steering engines of adequate horsepower, it is possible to obtain speeds of 15 degrees to 18 degrees per second in rudder rotation with excellent control - both for direct rudder dialing and automatic control from the compass.

PERMANENT HELM ADJUSTMENT

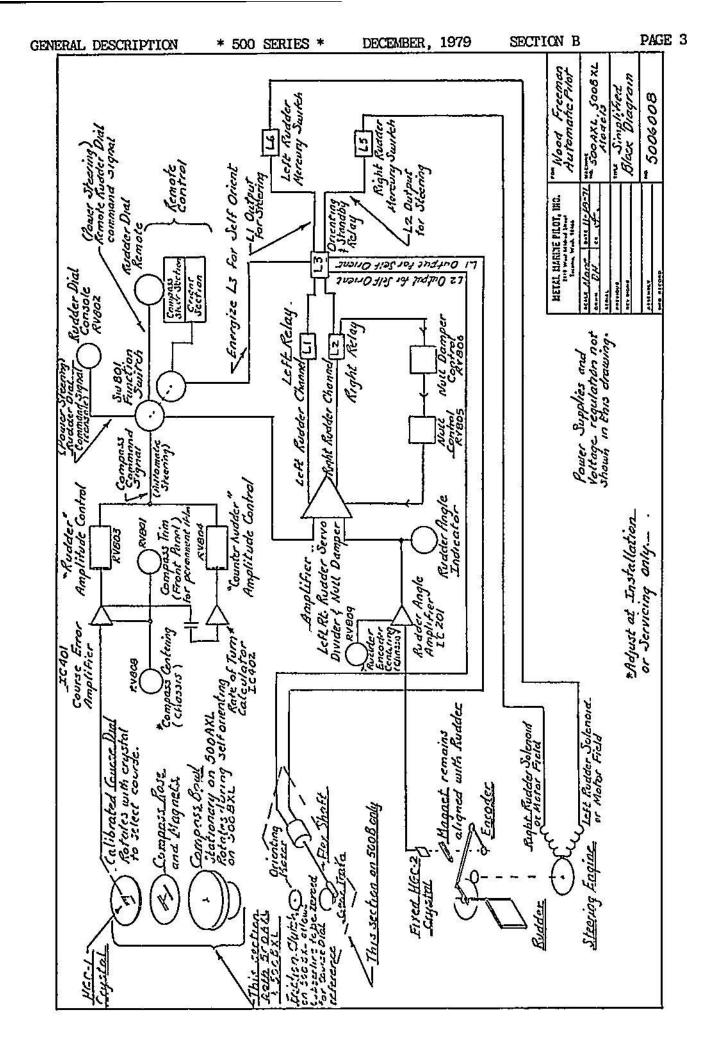
On the front panel of the Console, "COMPASS TRIM" Control (RV801) trims the compass course for permanent helm effect.

ADJUSTMENTS FOR WIDE RANGE OF VESSEL SPEEDS

"RUDDER" Amplitude Control (RV803) for adjusting the rudder throw for a given amount of course displacement allows the operator to immediately adjust for a continuous range of vessel speeds from 2 knots to 30 knots.

VARIABLE RATE COUPLING

"COUNTER RUDDER" Amplitude Control (RV804) or rate coupling on the front panel is adjustable to suit the needs of the particular vessel or the sea conditions existing. The "COUNTER RUDDER" allows the Pilot to "anticipate" future actions of the vessel by sensing rate of turn and making corrections as necessary.



DIFFERENCES BETWEEN 500-A-XL & 500-B-XL MODELS

The 500-A-XL Model Pilot uses a compass on which the course is dialed directly. 500-B-XL Model uses an identical system with the addition of a gear-driven compass base and gear-motor which allows crienting of the compass bowl by the electric motor to permit a permanent change of course from a remote station.

B-1 Compasses having a 4 1/2" card are used on A-1 and B-1 models. These are best used as standby or remote compasses because the size of their card and the necessity for reading the actual heading from above the compass limits their utility for primary steering compasses. Compasses having a 6" card are used on the A-2 and B-2 models. These compasses are suitable for primary steering compasses or master compass, having an easily read card, with excellent stability and accuracy. The B-2 model, in addition to its remote course changing capability, has a locking feature which locks the lubber line in the reference (dead ahead) position when using the compass for navigation or direct course dialing.

Remote controls are available for both units. In the case of the 500-A-XL model, the remote control will allow "RUDDER DIAL" power steering function and switching between power steering and compass steering. It is not possible to make a permanent compass course change by remote control, but it is necessary to dial the compass directly each time a permanent course change is desired. The "STANDBY" - "SELF-ORIENT" position of the remote gives only "STANDBY" on this model. (Vessel may be steered by wheel without autopilot interference.)

The remote control of the 500-B-XL model, on the other hand, allows not only the "RUDDER DIAL" power steering function and return to the pre-set compass course; but also, allows a change in the permanent course by means of the self-orienting feature. "SELF-ORIENTING" for new course occurs when function switch is in "STANDBY" -"SELF-ORIENT" position, during which time vessel may be steered by wheel. course dialing at the compass top is also possible.

While the 500-B-XL compass is quite useful as secondary steering compass, use of the "B-1" model compass as a master steering compass is not recommended because the "lubber line" is rotated through 360 degrees while self-orienting. friction clutch in the gear train allows the compass bowl to be rotated manually to a preset reference point when "lubber line" steering is required.

On radar equipped vessels locating the 500 Compasses adjacent to the radar console (unless the magnetron is in the console) is recommended to allow direct course dialing when navigating by radar. The accurate course holding of the 500 Series pilot stabilizes the heading of the vessel and thus provides a sharp picture free of the scope "smudging" which occurs with the heading variations of hand steering. The course dial feature then allows the operator to make exact heading changes while watching the radar.

REMOTE CONTROLS

All models incorporate the "RUDDER DIAL" on the Console and in the remote control. This "RUDDER DIAL" allows full follow-up power steering and causes the steering engine to match the rudder to the angular position dialed, either on the Console or the remote rudder dial. Remote is standard on 500-B1-XL, optional on 500-A1-XL.

REMOTE CONTROLS - continued

A lever steering accessory is available for both models. This lever steering accessory is in a cast brass case, is waterproof, and can be mounted in any exposed location such as a trolling hatch, at the rail of the vessel, or at the flying Multiple remote controls are also possible by using the suitable junction box. In going from one remote control to another, it is necessary to leave each remote in the "COMPASS STEFR" position when going to the next remote, then full control is obtained at the next remote station. When the function switch on the front panel is set to "REMOTE", then any one of the remotes can function in the manner noted above. However, when the function switch is turned to any other position besides "REMOTE", all of the remotes are inoperative.

> Metal Marine Pilot, Inc. 2119 Mildred Street West Tacoma, Washington 98466 Phone - Area 206 564-5902

WOOD FREEMAN AUTOMATIC PILOTS

SECTION C

WOOD FREEMAN® AUTOMATIC PILOTS ************* 500 SERIES

INSTALLATION INSTRUCTIONS

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COMPONENT MOUNTING DIMENSIONS		37 • 3			•	(4)	•	•	•			•	•	•	•	•	(. •)	5001000B-1
CABLE CONNECTIONS																		
COMPASS INSTALLATION* COMPASS ADJUSTMENT - MAGNETIC * .				•	•	•	•	•	•	•	•	•	•	•	٠	٠		3
CONSOLE MOUNTING			•	•	٠	•	•	•	•	•	•	٠	•	•	•	•	•	5
RUDDER ANGLE INDICATOR MOUNTING	•	٠		•	٠		•		•	ě	٠	٠	•	•	•	•	÷	6
XL POWER SUPPLY MOUNTING		•	•	•	•	٠		89.6	0. *	٠	•	•	٠	٠	٠	•		7
CABLE CONNECTIONS AND PIN CONNECTIONS	*:	*	٠	•	•	•	٠	•	•	•	•	•	٠	٠	•	•	•	5000012-1R
SILENT SWITCHER CONNECTIONS		•	•	•	•	•	•	•		•	•	•	•	•	٠	٠	•	5006123-1A
PUSH BUTTON CRIENT INSTALLATION		•	•	٠	٠	()			•	-	٠	•	٠	٠	٠		•	5008253-1

^{*} ADDITIONAL INFORMATION ON SELECTION OF COMPASS MOUNTING LOCATION AND COMPASS ADJUSTMENT AVAILABLE ON REQUEST FROM FACTORY.... "NAUTICAL - COMPASSES, 1978"

^{**} SEE APPENDIX FOR ADDITIONAL CABLING INFORMATION.

Cutting or splicing connecting cables of this system (except as noted below), is an improper installation procedure, voids the limited warranty, and makes the installer liable to the owner for subsequent cable replacement. Splices corrode, are subject to moisture leakage, R.F.I., shorts, opens and misconnections that can damage components.

EXCEPTIONS:

Encoder cable plug (8-pin) may be unsoldered in order to pull cable forward from rudder post area and then resoldered carefully and correctly. DO NOT REMOVE SOCKET, (potted) from aft end of cable.

2-conductor power cable from ship's power to XL Power Supply may be extended in accordance with wire sizes and lengths shown on Table 1 - below.

3-conductor motor cord on power pack (or limit switch assembly on -511LS units) may be extended in accordance with sizes and lengths shown on Table 1.

FOR #12 MOTOR WIRE EXTENSIONS - (In stock)

Voltage	-531 (A Motor)	-531 (Std.Motor)	-521 (Std.Motor)	-531 (D, S, T or K Motor)
12	61	8.5'	13'	_
24		32'	50'	8.51
32	-	551	851	8.51
	FOR #10 MOTO	R WIRE EXTENSI	ONS - (Custon	er Furnished)
12	91	13'	201	s -
12 24		13' 48'	20† 75†	13.5
12 24 32		470.731.c.		13.5' 13.5'
24	91	481	75' 128'	13.5
24 32	9' - - FOR #8 MOTOR	48' 82' R WIRE EXTENSION	75' 128'	13.5
24	91	48† 82†	75' 128' <u>ONS</u> - (Custome	13.5

April 1978

Metal Marine Pilot Inc. 2119 West Mildred Street, Tacoma, Washington 98466 Telephone (206) 564-5902

WOOD FREEMAN® AUTOMATIC PILOTS

* 500 SERIES *

INSTALLATION INSTRUCTIONS

* GENERAL NOTES *

Consect all cables to components as shown on Component Layout Drawing #5006010-B-2. If longer cables are required, be certain to use shielded cables where specified on Drawing #5006010-B-2, or use standard WOOD FREEMAN® extension cables. DO NOT CUT, SPLICE, or OTHERWISE MODIFY, including use of terminal connectors: ENCODER, COMPASS, 12 CONDUCTOR, RUDDER ANGLE INDICATOR or REMOTE CONTROL cables. Failure to use shielded cables may cause temporary malfunction of the AUTOPILOT when strong radio-frequency fields are present, such as transmitting on the vessel's radio phone.

If it is necessary to remove the PLUG end of any cable in order to pass the cable through conduit or a bulkhead, be sure to reattach the wires to the correct pins on the plug. Incorrect connections or cold solder joints may cause malfunctions and may cause component failure.

NOTE: CUTTING, SPLICING, OR OTHERWISE MODIFYING CONNECTING CABLES IS CONSIDERED ABUSE OF THE SYSTEM AND VOIDS THE LIMITED WARRANTY.

Although grounding of components is not generally required, when strong radio - frequency fields are present the following should be followed:

Allow a minimum mounting distance of 3 feet between the radio and any of the autopilot components.

Route all connecting cables for the Autopilot at least 12 inches from the radio's antenna cable and the radio's power cable.

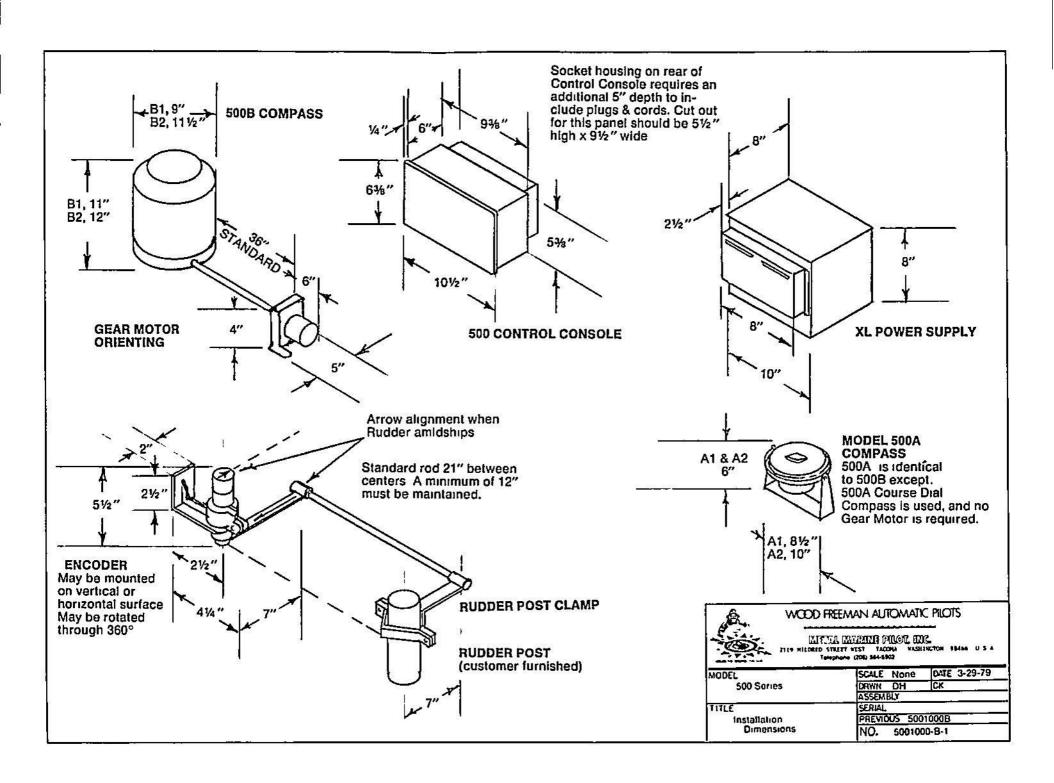
Connect a separate ground, #8 cable or 1 inch or wider bonding strap, to the back of the Control Console and to the XL Power Supply.

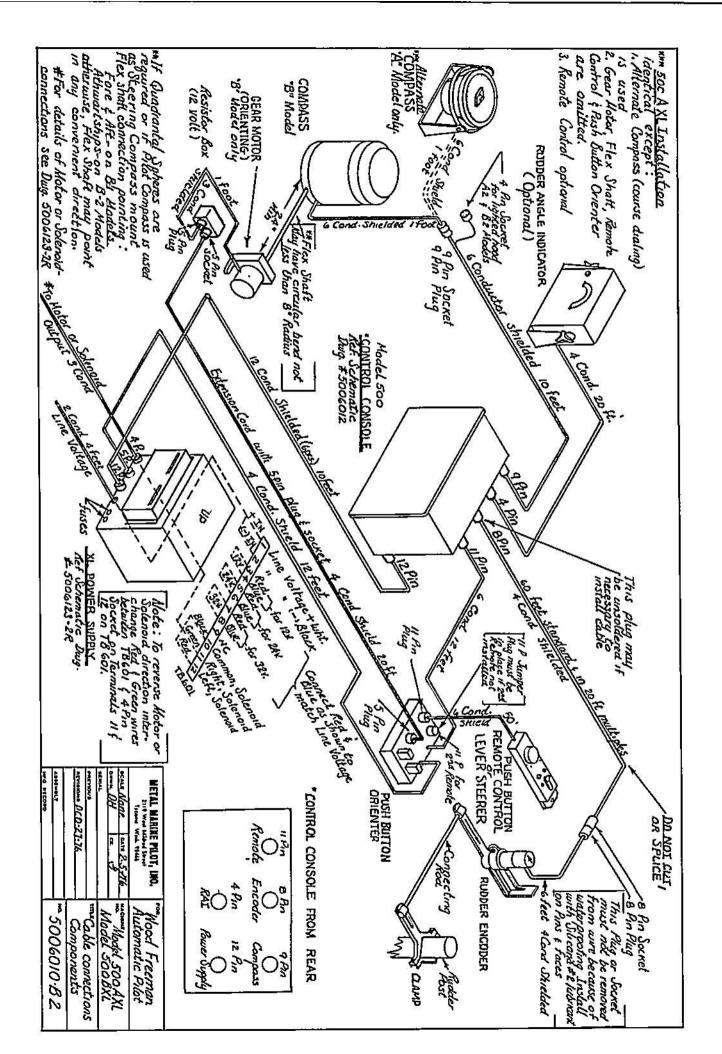
The XL Power Supply will accommodate 12, 24, or 32 volts DC primary inputs (32 volts up to 37 volts maximum), switching the primary input voltage through 20 amp mercury relays to the split field series motor or solenoid valve of the steering engine (Power Pack). All computer voltages are automatically regulated at 14 volts or less.

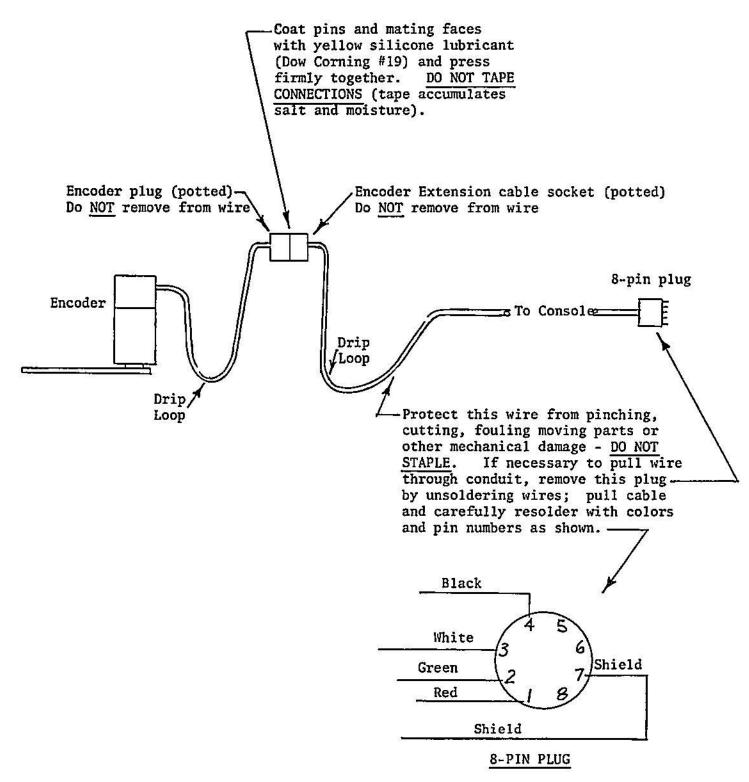
Adjustment for the primary input voltage is accomplished by shifting two (2) taps on the input terminal strip of the power supply. Proper connections are shown both on the XL Power Supply nameplate and on the terminal strip label.

If 115 volts AC single phase power is required as the primary source, the Model 35-B Rectifier (available as an extra cost accessory), must be used to provide a suitable DC input to the XL Power Supply.

IF ANY QUESTIONS ARISE AS TO THE PROPER INSTALLATION PROCEDURE, PLEASE CALL THE FACTORY FOR A SPECIFIC RECOMMENDATION.







October, 1972

MODEL 500 SERIES Section C - Page 1-A

VOOD FREEMAN®AUTOMATIC PILOTS

* SPECIAL INSTRUCTIONS FOR COMPASS ADJUSTMENT *

BEST STEERING IS OBTAINED WITH A COMPENSATED COMPASS !!!

ON STEEL VESSELS the Pilot compass MUST be adjusted within 5 degrees of correct magnetic heading on North, South, East and West, and must have any heeling error compensated.

TURN ON PILOT - Models 11, 15

- clutch disengaged.

Models 11, 15 - clutch disengaged.

Models 420, 4210 - clutch disengaged with selector on

"Automatic".

Model 500 series

Models 423, 423-B - selector on "Change Course".

- function switch either 'OFF" or

"RUDDER INDICATOR ONLY".

Bring the boat on a known magnetic East or West course using either landmarks or corrected steering compass. If the Pilot compass is more than 5 degrees out of agreement, place a magnet on either side of compass, red end forward if compass reads to the North, and red end aft if compass reads to the South of what it should. the magnet near or far until compass reads correct course.

Bring the boat on the known magnetic North or South course. Place a magnet in front or back of compass with red end to right if compass reads to the West of the course, and red end to left if it is to the East. Move near or far until correct adjustment is obtained. This compass need not be adjusted within the same degree of precision necessary for the steering compass, but in any case it should not be more than 5 Often, when the Pilot is installed and the compass has not been degrees out. properly compensated, the Pilot will operate and hold the boat perfectly on certain courses, but on other courses the steering will be erratic. This is due to lack of compensation of the Pilot compass.

ADEQUATE COMPENSATION OF THE COMPASS IS USUALLY IMPOSSIBLE IF THERE ARE HORIZONTAL OR VERTICAL STEEL RODS, PIPES OR STACKS ENDING WITHIN 24 INCHES OF THE COMPASS. (See diagram on reverse side of this sheet)

Poor compass adjustment is usually shown by failure of the Pilot to maintain some headings while steering well on others.

STEEL VESSELS

Compass compensation on steel vessels, while more exacting, is usually not difficult if simple rules are observed:

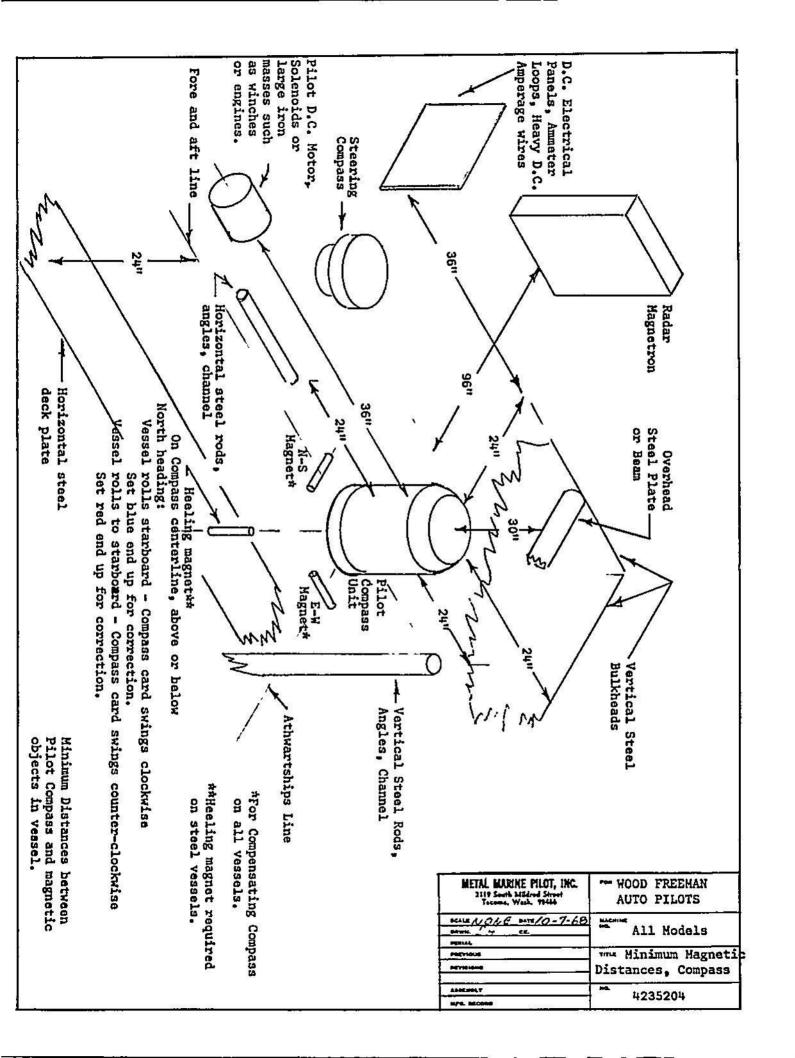
(1) The distance between the compass and steel portions of the vessel is at least 24 inches and preferably 36 inches.

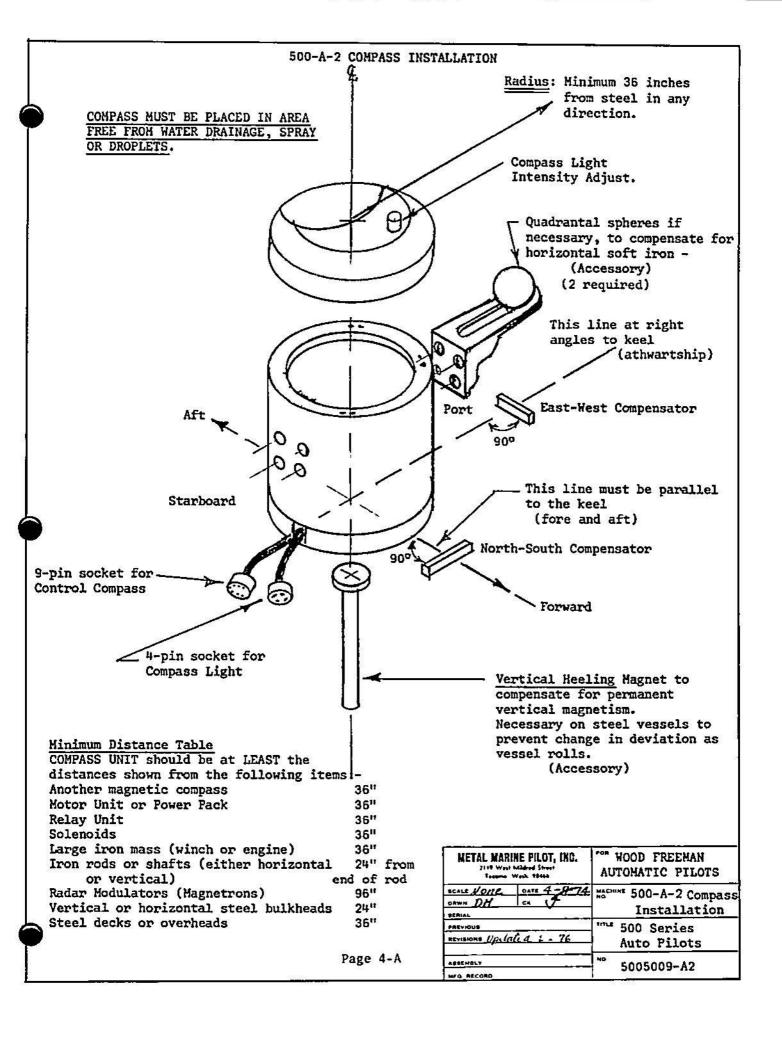
North, South and East, West compensation is done as above.

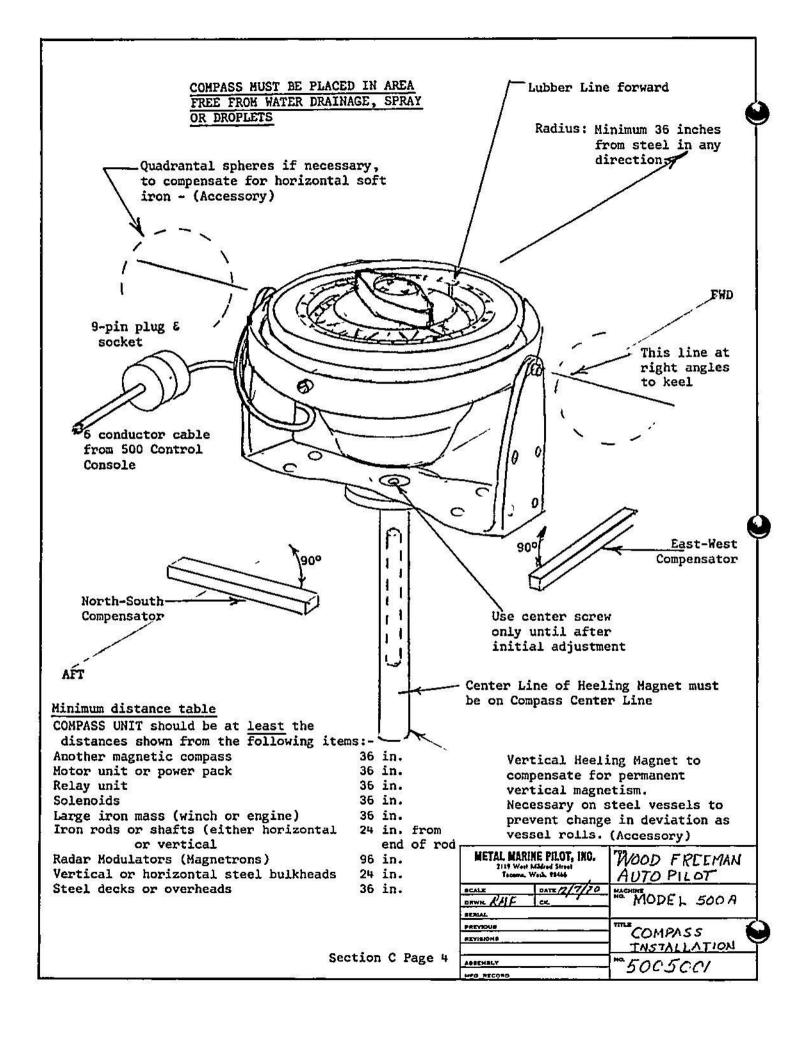
(3) The vertical magnetism of the ship is compensated by a "heeling" magnet, placed above or below the exact center of the compass. The "red end" of the magnet is usually up in the Northern Hemisphere and down in the Southern Hemisphere, but welded steel vessels may have residual vertical magnetism in either direction.

The vertical position of the magnet is selected to neutralize swinging of the compass card as the vessel rolls while on northerly headings (Northern Hemisphere) or southerly headings (Southern Hemisphere). It is usually desirable to "overcorrect" the normal dip of the earth's magnetic field.

The compass is best mounted above decks or in a house with glass windows. However it may be mounted below decks if the above three rules are observed.







MODEL 500 B

COMPASS INSTALLATION

COMPASS MUST BE PLACED IN AREA FREE FROM WATER DRAINAGE, SPRAY OR DROPLETS

from steel in any direction. Quadrantal spheres if necessary, to compensate for horizontal soft Gear Motor iron - (Accessory) 24"~ Orienting Minimum Shaft 6-Conductor cable from 500 Control Console. This line at right angles to keel. (athwartship) This line parallel to keel East-West (fore and aft) Compensator. 900 Center Line of Heeling Magnet must North-South Compensator be on Compass Center Line.

Minimum Distance Table

COMPASS UNIT should be at LEAST the

distances shown from the following items:-

Another magnetic compass	36"
Motor Unit or Power Pack	36"
Relay Unit	36" *
Solenoids	3611
Large iron mass (winch or engine)	36"
Iron rods or shafts (either horizontal	24" from and of rod
Radar Hodulators (Hagnetrons)	96"
Vertical or horizontal steel bulkheads	2411
Steel decks or overheads	36"

Vertical Heeling Magnet to compensate for permanent vertical magnetism. Necessary on steel vessels to prevent change in deviation as vessel rolls. (Accessory).

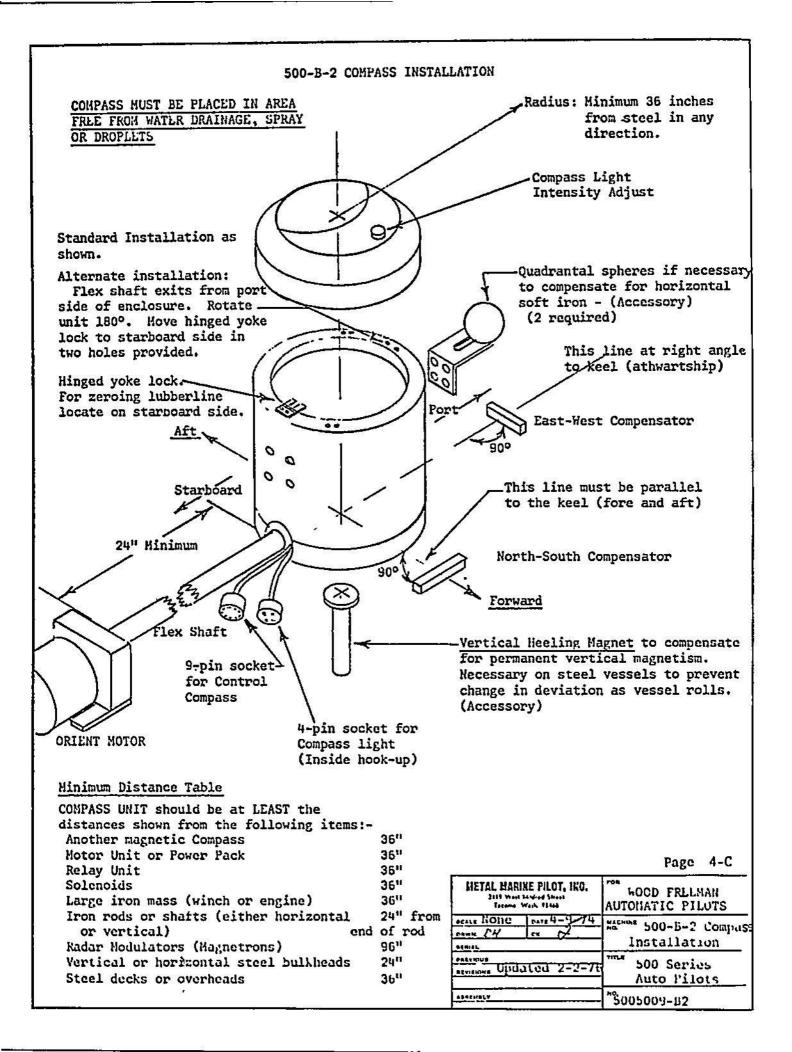
* IF - Quadrantal spheres are required (steel vessels only), mount flex
shaft connection pointing FWD or
AFT. Otherwise compass unit may
be mounted with flex shaft connection
in any convenient direction.

Radius: Minimum 36 inches

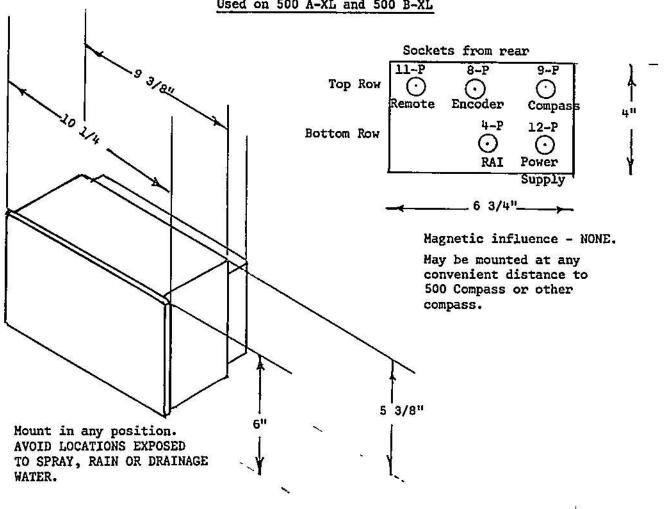
Drawing #5005001-B Section C - Page 4-B

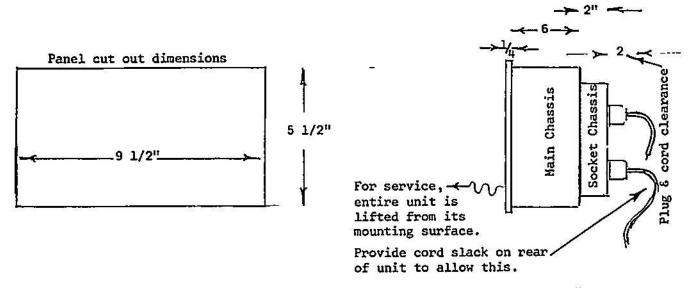
August, 1971

(Revised January 1976)





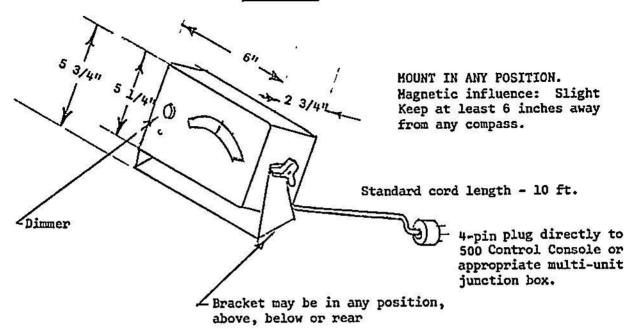




October 1972

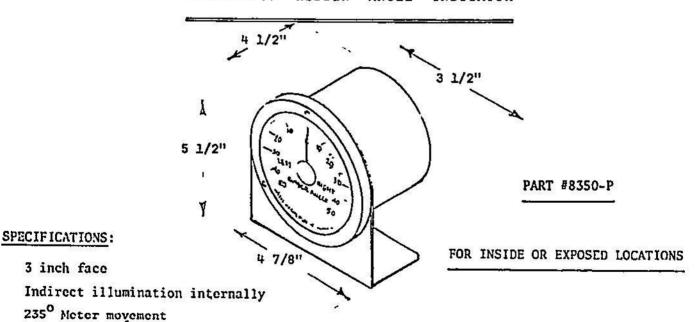
Section C - Page 5

RUDDER ANGLE INDICATOR Part #8350



RUDDER ANGLE INDICATOR
For unexposed locations (Part #8350)
Non-waterproof, lighted with dimmer.

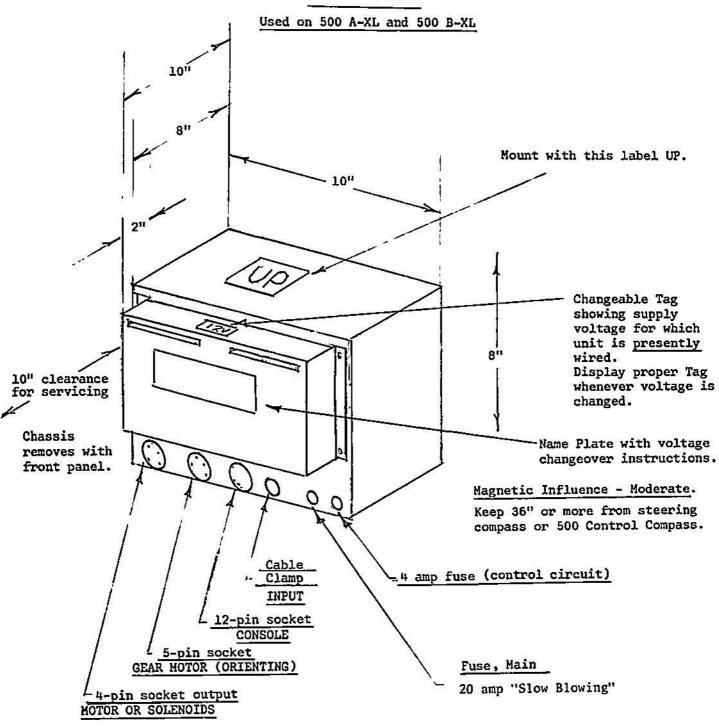
WATERPROOF RUDDER ANGLE INDICATOR



Does not affect steering compass if more than 12 inches distant Flush mounts from front or back of panel or on free standing bracket

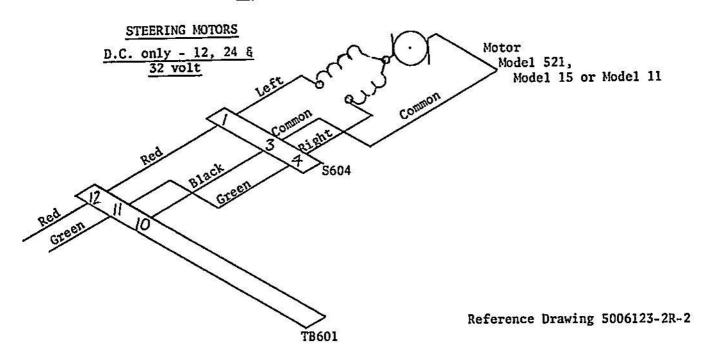
MODEL 500 SERIES
Section C Page 6

XL POWER SUPPLY



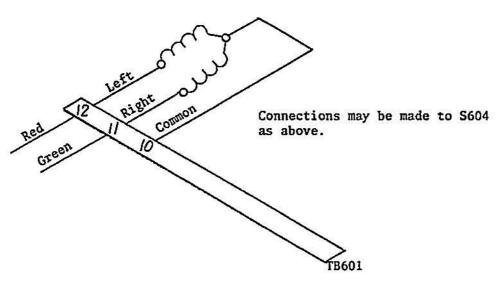
August, 1971 (Revised January, 1980) Section C - Page 7

XL POWER SUPPLY OUTPUT Used on 500 A-XL and 500 B-XL



INTERNALLY POWERED SOLENOIDS (*DC only)

Rated at primary input voltage to Power Supply. (12, 24 or 32 volt D.C.)

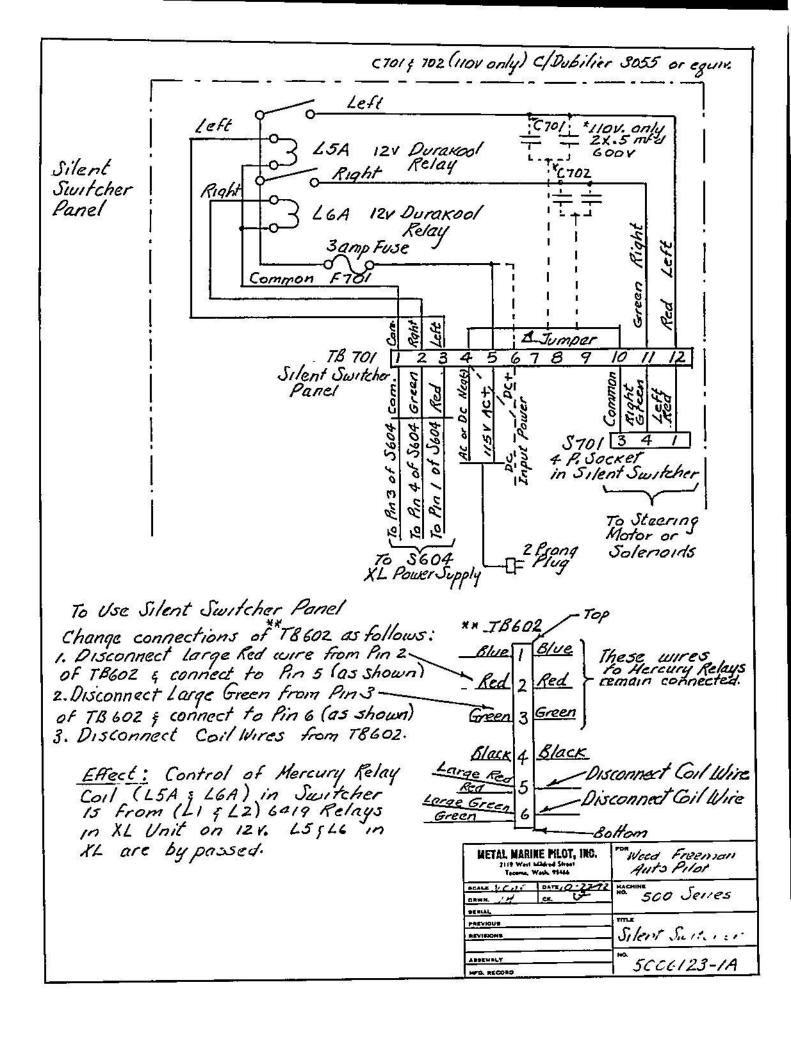


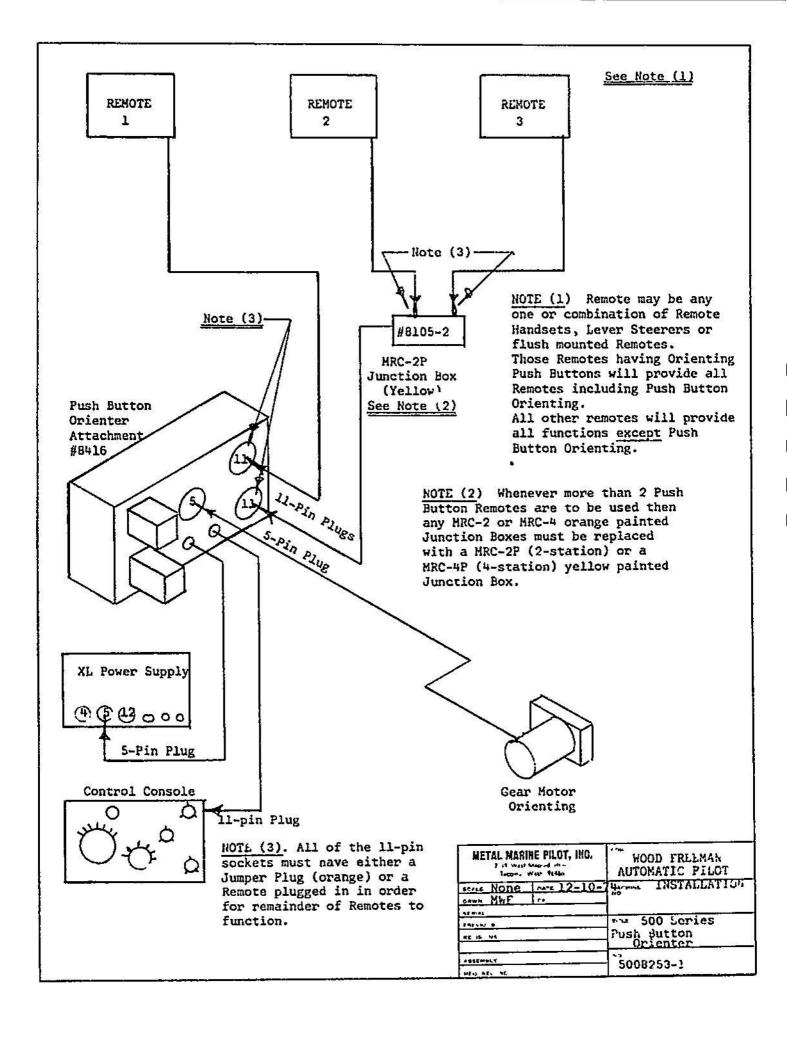
* IMPORTANT NOTE:

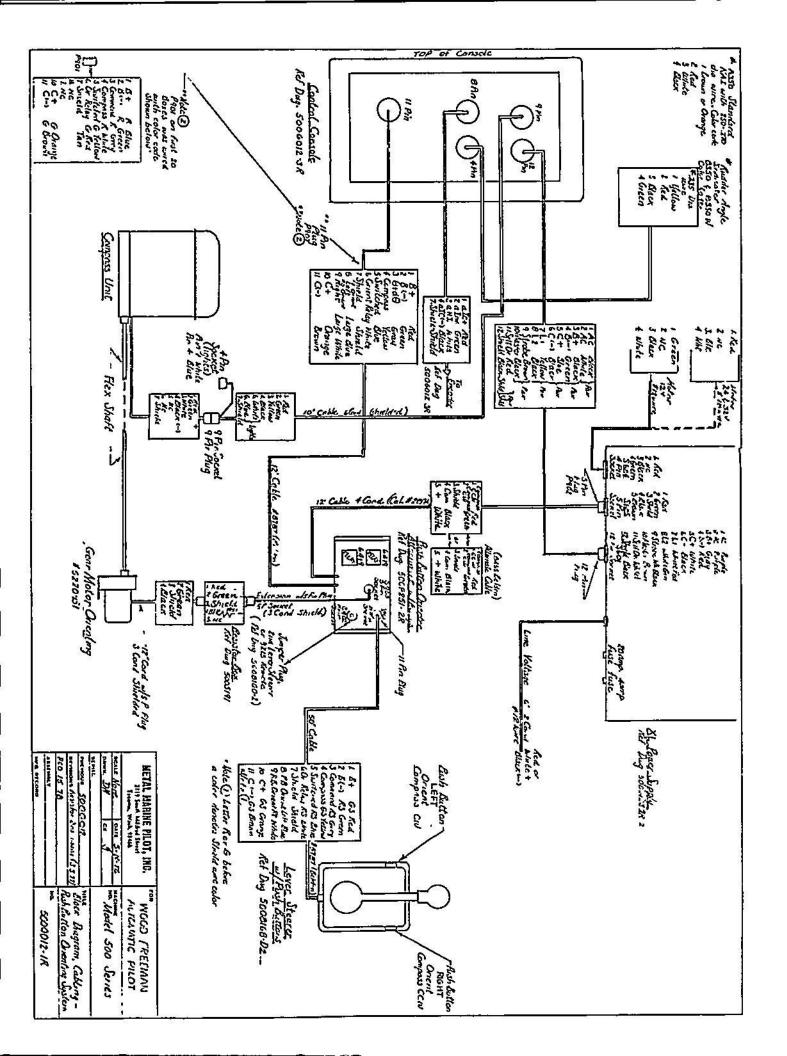
For AC Solenoids and all externally powered Solenoid Units use additional Silent Switcher Unit to insure isolation of computer circuits from destructive voltages.

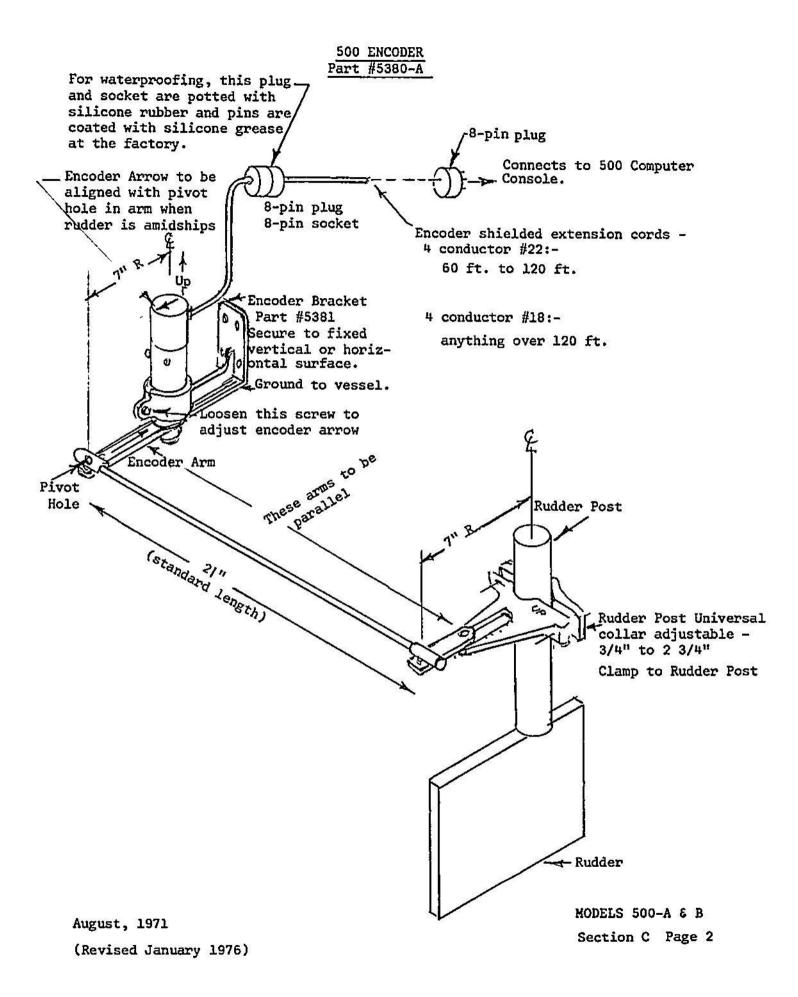
October 1972

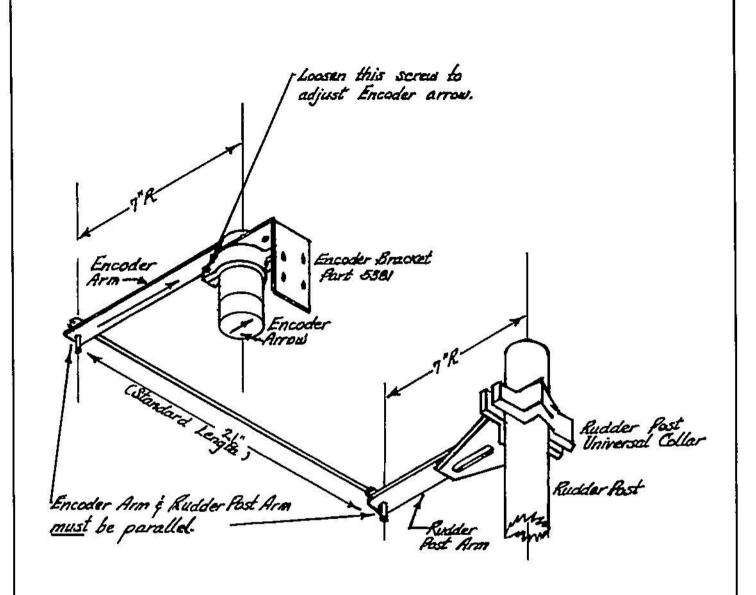
SECTION C - Page 8











If absolutely necessary because of space limitations, Encoder may be mounted inverted. In this case, the point of the arrow on the cap must point away (180°) from the Encoder arm, when rudder is amidships (centered rudder).

per RHF 6-8-72

METAL MARINE PILOT, 1910. 2119 West Mildred Steam Treams, West, 18466	"Wood Freeman Automatic Pilot
DRIVE DH. CK. 4	MACHINE 500 Jories
SERIAL PREVIOUS SEVERONS	" Mounting Encode
ASSEMBLY	"Sec. C- Page 2A

Model 500-B

* COMPASS INSTALLATION *

Locate Compass in best possible magnetic location so IT IS NOT EXPOSED to RAIN, SALT SPRAY OR DRAINAGE WATER. If Compass is to be used for standby steering Compass, pick best possible magnetic location ahead of normal helmsman position, but at least three feet from primary steering compass.

OBSERVE TABLE OF MINIMUM DISTANCES FROM OTHER MAGNETIC OBJECTS (See Drawing #4235204)

Move Compass in circle of about 1 foot radius from selected location and watch compass card. If card swings less than 15 degrees, compass location selected is satisfactory. However, larger swings indicate some trouble may be encountered in compensating the compass, and another site should be selected if possible.

The Compass must be carefully compensated, so that maximum error is 2 degrees or less on N, S, E and W headings. If compass is always compensated to steering compass standards, it will also give best performance for Autopilot steering. Optional Quadrantal Spheres may be added if large errors are present on inter-cardinal points (NW, NE, SW, SE) and a heeling tube is available to compensate for the "heeling" effect of vertical permanent magnetism in steel ships that develops as a horizontal magnetic effect as the ship rolls.

See separate sheet for compass compensating instructions.

Connect compass cable to console, 9-pin socket, as shown on Component Layout Drawing #5006010-B-2.

* POWER PACK INSTALLATIONS * * * 500 SERIES * *

DRAWING NUMBER PAGE
GENERAL INFORMATION (LIMIT SWITCHES)
MECHANICAL.
-511LS POWER PACK MOUNTING AND INSTALLATION
HYDRAULIC
GENERAL INFORMATION FITTINGS, HOSES & PIPING
MOUNTING OF HYDRAULIC POWER PACKS -531 POWER PACK
-531 FOWER PACK CONNECTION TO: HYNAUTIC SERIES (ALL)
-521 POWER PACK & 555-1 ENGINE DRIVEN PUMP CONNECTION TO: CAPILANO with SERIES 50 UNIFLOW VALVE
-521 POWER PACK & CUSTOMER FURNISHED POWER SOURCE CAPILANO with 1000 SERIES HELM
-00 CUSTOMER FURNISHED POWER PACKS SOLENOID VALVES
* * For systems not listed contact the factory . * *
BLEEDING INSTRUCTIONS: CAPILANO 1000 SERIES with -521 POWER PACK
SERVICING531 FILTER SCREENS

GENERAL INFORMATION

* 500 SERIES - LIMIT SWITCHES *

The 500 SERIES AUTOPILOTS have rudder movements proportional to the command signal under "COMPASS DIAL" control and movements equal to dial movements under "RUDDER DIAL" control. There is no provision for unmetered rudder movements under the operator's command. Under normal operation, therefore, no additional limit switches are required. In the event of an electronic malfunction, it is possible for the steering engine to put the rudder hardover at maximum steering engine force. This second situation, emergency in nature, is handled by one of the following provisions in the steering engine: -

* MECHANICAL STEERING *

Power Pack Code -511LS

- Factory installed limit switches in motor circuit. Limit Switches must be adjusted after installation and before operation underway. Refer to page 4.

* HYDRAULIC STEERING *

FOR SAFETY, WE RECOMMEND THAT ONLY CONTINUOUS-PUMP MECHANICAL TYPE HELM UNITS HE USED THIS PREVENTS THE HELM UNIT FROM "BOTTOMING", AND WHEN THE PILOT IS INSTALLED. INSURES THAT EMERGENCY OVERRIDE OF THE AUTOPILOT WILL BE AVAILABLE AT THE HELM.

- Power Pack Code -521-MC Has built-in pressure relief, thermal pressure and "make up" valves. May be used on manual or power hydraulic systems with or without existing relief valves.
- Power Pack Code -531 - Used on manual hydraulic systems; this unit has built-in relief valves that act as limit switches.
- Power Pack Code -00 - For use with customer's hydraulic system and solenoid valves - customer to furnish suitable relief valves.

When used to convert Model 11 and Model 15 on mechanical steering systems, use existing limit switches.

POWER PACK 511LS (LIMIT SWITCH)

REVERSING POWER PACK MODEL

CLUTCH AND CHAIN DRIVE TO WHEEL

Similar to Model 11 Motor Unit, but has 521 motor (split field series wound) of approximately 1/6 H.P.

1) FASTEN THE LARGE SPROCKET (usually 8") to the steering wheel shaft. Use pins or keys, but do not depend on set screws. When necessary, split sprockets can be supplied (at additional cost). When split sprockets are required, exact shaft size (to closest .001") must be given.

The large sprocket should be placed so that the driving sprocket on motor unit can be lined up with it. If that is impossible, a countershaft may be used and the motor unit may be placed at some other location. Standard sprockets have a 1" minus .050 (approximately) "as cast" bore to allow for final boring to fit 1" shaft or larger. Other sizes may be furnished on special order.

The DRIVING SPROCKET ON MOTOR UNIT is on the CLUTCH DRUM, is of steel, and is 5 inches from one end and 7 inches from the other end of motor unit. The thin sprocket on clutch drum drives limit switch only.

- 2) MOTOR UNIT. Mount the Motor Unit on the floor so that the wide sprocket closest to the clutch drum will align properly with sprocket on steering wheel assembly (or intermediate countershaft). There are four holes molded in the glass-reinforced nylon base of motor unit for convenience. No other holes should be drilled. If mounting surface is irregular, put a pad of plywood, at least 3/4 inch thick under base.
- 3) Before making fast, place the #41 Chain around the sprockets, letting ends meet on large sprocket, and move Motor Unit until chain comes to about the right degree of tightness. Do not have chain too tight, as it will cause excessive wear. With a little care, Motor Unit can be placed so that it will not be necessary to use an offset or half-link.
- 4) GROUND MOTOR UNIT TO VESSEL'S GROUND.

 (This is to prevent electrical shocks from suppressors in motor.)

SECTION D

* LIMIT SWITCH ADJUSTMENT (-511LS POWER PACK) *

Used on Mechanical steering gear only. Do not use Limit Switch with hydraulic steering as it will cause a malfunction.

- Remove limit switch cover. 1)
- 2) Disengage pilot clutch.
- Turn steering wheel hardover to the left as far as it will go, then 3) back off from the hardover position in the amount as shown in the table below:

37 1
Number of turns to be
Backed off from Hardover
1/4
1/3
1/2
1/2
2/3
3/4
3/4
3/4
1
1
1
1 1/4
1 1/2

Note the direction the limit switch cams turn when the wheel is being turned hardover to left.

- 4) Turn Function Switch on Console to "RUDDER DIAL", set Rudder Dial at 35 degrees Left. Motor unit will now commence to rotate Left and will continue to do so. While motor is rotating, depress each limit switch tongue in turn to determine the switch which breaks the circuit when motor is rotating to the left.
- 5) The set screw on the cam which operates this switch is loosened and the cam is rotated in the direction that it was turning when the wheel was rotated to the left until the micro-switch tongue is depressed sufficiently to cause the switch to click. Now tighten the set screw to lock the cam in this position.
- 6) Rotate the steering wheel hardover to the right and back off from hardover the number of turns shown in the table above. Loosen the set screw of the other cam and rotate cam in the direction it was turning when the wheel was rotated to the right until the micro-switch tongue is depressed sufficiently to cause the switch to click. Now lock the cam in this position.
- 7) Replace the cover on the micro-switch.

Limit switch cams may be set for wheel turns less than the actual hardover to hardover turns if desired, but in any case, the cam must not be set forward to where it releases the micro-switch tongue before the wheel comes hardover.

GENERAL INFORMATION

* 500 SERIES *

* FITTINGS, HOSES & PIPING *

* * WARNING * *

Use WCOD FREEMAN® hydraulic power packs only with hydraulic steering systems employing METALLIC connecting lines, fittings and components having minimum working pressure ratings of at least 900 PSI, except for short lengths of connecting hose (see HOSES specified below).

* STANDARD FITTINGS *

All WOOD FREEMAND hydraulic components are furnished with standard JIC #8-37 degree flare fittings (3/4" -16 thread). Reducer fittings are supplied with -531 units which allow connection with #6-37 degree flare fittings.

* HOSES *

Power packs should be connected to steering systems with double steel braided hose (3500 PSI rating)- 2' minimum, 6' maximum. The hoses must have JIC #8-37 degree swivel nuts, on one end, to match the power pack fittings. The fittings on the other end of the hose should match up to the shut off valves. (JIC #6-37 degree fittings may be used with -531 units.)

* SHUT OFF VALVES *

Shut off valves shown in the drawings are ball valves rated at least 1500 PSI (Worcester 3/8"-411YB-SE or equivalent).

* BLEED VALVES *

Bleed valves shown in the drawings are 1/4" needle valves rated at least 1500 PSI (Hoke 3722 M4B or equivalent).

* COPPER TUBING *

We recommend 3/8" TYPE K copper tubing (1/2 inch OD .049 inch wall). Larger tubing sizes may be used if it is comparable to the 3/8" tubing in pressure ratings. The larger tubing will reduce steering efforts in long runs.

Sweated fittings are unsatisfactory and should not be used.

* STEEL PIPE *

In installations where steel pipe is to be used, the pipe should be rated as schedule 80 and must be "pickled".

***** DO NOT USE TEFLON TAPE *****

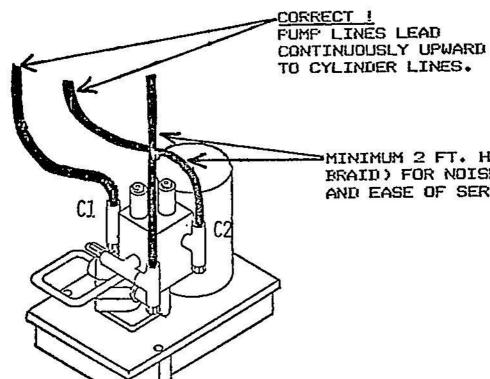
* * * * NOTICE * * * *

ALL HYDRAULIC UNITS BEFORE INSTALLING:

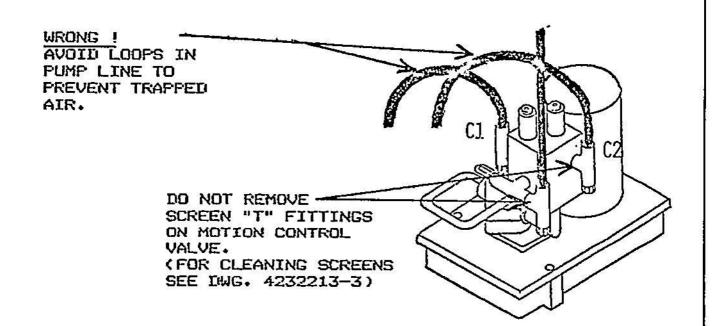
- 1) Be certain that all hydraulic lines are clean and free of debris.
- 2) If in doubt, purge system well with hydraulic fluid and discard fluid (or run through a filter of 40 micron mesh or less).
- 3) Be careful that no foreign material such as sand, wood chips, gasket material, thread sealer, rust, water, or copper cuttings from tube ends enters the system.

DO NOT USE TEFLON TAPE



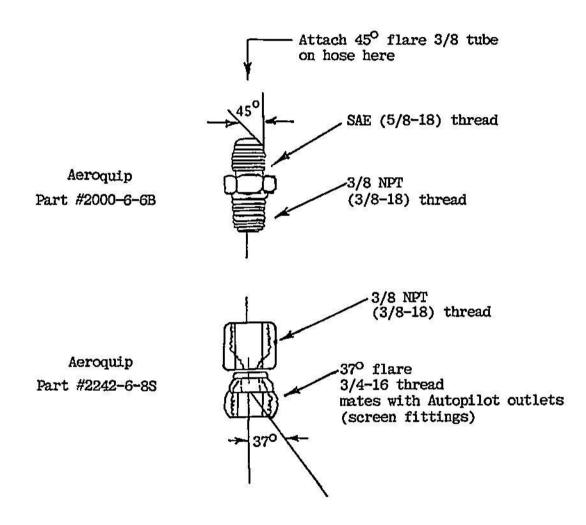


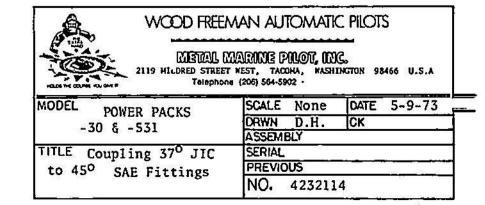
MINIMUM 2 FT. HOSE (DOUBLE BRAID) FOR NOISE ISOLATION AND EASE OF SERVICING.



ADAPTERS FOR COUPLING 370 JIC FITTINGS TO 45° SAE FITTINGS ON

POWER PACKS CODE -30 & -531





TECHNICAL TIP

There seems to be some confusion about 'Light Oil' Hynautic Steering systems Since 1961 Hynautic has recently, especially when interfacing some autopilots. recommended Light Oil in ALL our steering systems.

Why a light oil? Very simply, reduced wheel effort. A heavy, viscous oil resists flowing through the system's piping, ports and fittings. This resistance increases with cooler temperatures.

A wide range of suitable fluids are available. The points to remember in selecting a fluid are:

- 1. Petroleum Base Compatible with our Buna N and Nitrile seals.
- 2. Viscosity Index The higher the number, the better. High viscosity index fluids change less with temperature change.
- 3. Flash Point Higher flash point fluids are preferred for safety. The USCG specifies 200 degrees F. (open cup) minimum.
- 4. Color Some of the clear fluids have the necessary requirements above, but they are hard to see in the sight buttons which makes it difficult to ascertain fluid level in the reservoir.
- 5. An anti-foam ingredient will reduce the amount of air that can be saturated into the fluid.

BEST CHOICE MIL-H-5606A aviation hydraulic fluid.

It is available wherever aircraft are serviced, from most petroleum distributors, and from Hynautic (Part #MOO-02). Savings can be effected by purchasing in bulk (55 gal. drums) from your local petroleum supplier if your usage It is red in color, has an anti-foam ingredient, viscosity is low (66 SUS at 100 degrees F.), viscosity index is 226, and flash point (open cup) is 220 degrees Also, it is compatible with ATF, Dexron approved type A, should an emergency Dexron ATF is carried aboard most boats for their hydraulic transmissions, and it is available almost everywhere fuel is sold.

^{*} INDICATES A MODIFICATION OF ORIGINAL TEXT

ALTERNATIVES ARE:

BRAND	VISCOSITY SUS at 100 deg. F.
SHELL TELLUS OILS 15 21	60 105
MOBILE DTE 10 SERIES DTE 4 DTE 13	90 150
CASTROL HYSPIN (UNITED KINGDOM) AWS 10 AWS 15 AWS 22	55 80 110
GULF HARMONY AW 41 AW 43	105 150
AMERICAN OIL CO. RYKON 11 RYKON 15	105 150
SAE 5W MOTOR OIL	100
SAE 10W MOTOR OIL	150
AUTOMATIC TRANSMISSION FLUID, DEXRON APPROVED, TYPE A (ATF)	180200

TYPE F (FORD) AUTOMATIC TRANSMISSION FLUIDS SHOULD NOT BE USED.

We have recorded decreases in dockside rim effort of 20% to 50% by simply draining heavy fluids and refilling and purging with MIL-H-5606A.

* POWER PACK - 531 *

REVERSING PUMP MODEL

Direct reversing gear pump unit, using -521 split field series wound motor.

- 1) Locate pump unit in any convenient location, free of possible bilge water immersion so that:
 - (A) The motion control valve is below the level of the highest bleeding point in the system.
 - (B) The unit is on horizontal surface with motion control valve uppermost.
 - (C) The connecting lines from ports C2 "LEFT RUDDER PRESSURF" and C1 "RIGHT RUDDER PRESSURE" of Motion Control valve to steering system lines, lead continuously upward without loops or dips.
- 2) Secure unit to vessel with shock mounts provided.

* HYDRAULIC CONNECTIONS (Power Pack -531) *

- 1) The Pump Unit may be used with reservoirs either vented or pressurized at not over 50 psi.
- 2) Connect ports C1 (labelled "Right Rudder Pressure") and C2 (labelled "Left Rudder Pressure") with 2 to 6 feet of 1/2" or 3/8" double steel braided hose (3500 PSI min.) to tee connections in steering system as shown in appropriate drawing. (See table of contents)
- 3) Connect "T" port of Motion Control valve with 2 to 6 feet of 3/8" or 1/2" hose to bottom of system reservoir with at least one quart capacity. Usually the helm pump is used as a reservoir, such as Wagner and Capilano.
 - IN CONNECTING DIRECTLY TO THE HELM UNIT RESERVOIR, IT IS ADVISABLE TO PROVIDE A SURGE TANK OF CAPACITY AT LEAST TWICE THE DISPLACEMENT OF THE RUDDER RAM, CONNECTED TO THE UPPER FITTING OF THE RESERVOIR, VENTED, AND LOCATED WITH BOTTOM OF RESERVOIR AT OR ABOVE LEVEL OF TOP OF HELM UNIT. The surge tank decreases tendency of the helm seal to leak. A clear vinyl line between surge tank and top helm may serve as low oil warning indicator.
- 4) Shut off valves are recommended in all three hydraulic lines to facilitate trouble shooting and servicing. (Refer to FITTINGS, HOSES, AND PIPING)

POWER PACK -521 *

TORQUE BOOST METERING PUMP MODEL

* INSTALLATION *

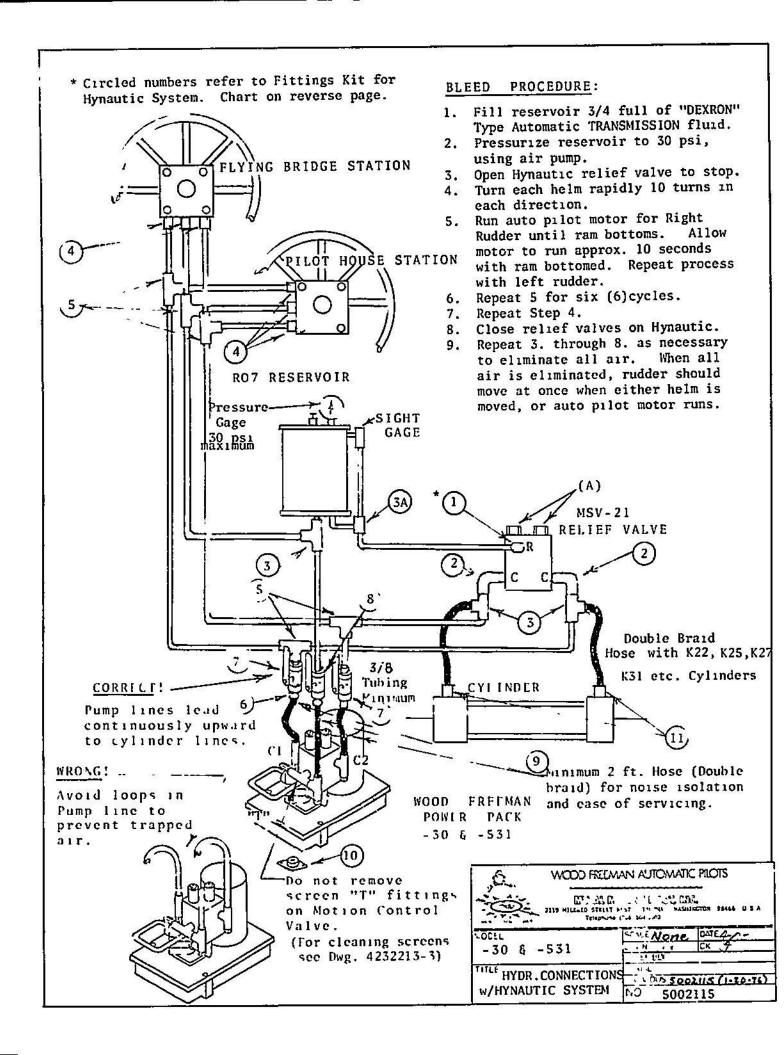
- 1) Type A "Dexron" Automatic transmission fluid is recommended with this unit. It is readily available at automobile service stations as well as marine oil dealers. (Refer to recommended oils)
- 2) Locate -521 unit in an area free of water submersion danger so that the left and right pressure lines from the motion control valve lead continuously upward to the rudder cylinder lines. The engine room is frequently the best place.
- 3) Mount unit on horizontal surface, gear case down, by 3 point suspension, using standoffs and the 3 mounting lugs on gear case.
- 4) Replace the red plastic plug in the gear case with the vented plastic plug provided.
- 5) Connect the five ports of the -521 in accordance with the appropriate drawing (see table of contents) using 2 to 6 feet of 1/2" double steel braided hose.

Shut-off valves in the left and right pressure lines and the "T" port line are desirable to enable removal of -521 unit for servicing without disabling the hydraulic steering system or causing excessive oil loss.

The Emergency bypass provision in pressure line is required to isolate a damaged unit, while maintaining pressure on other power steering stations.

6) The full flow filter, provided, must be used between the hydraulic pressure source and the -521 "IN" port.

FOR: REFER TO:		DRAWING #
ELECTRICAL CONNECTIONS	Cable connecting Components	5006010-B-2
	"XL" Power Supply	5006123-2R-2



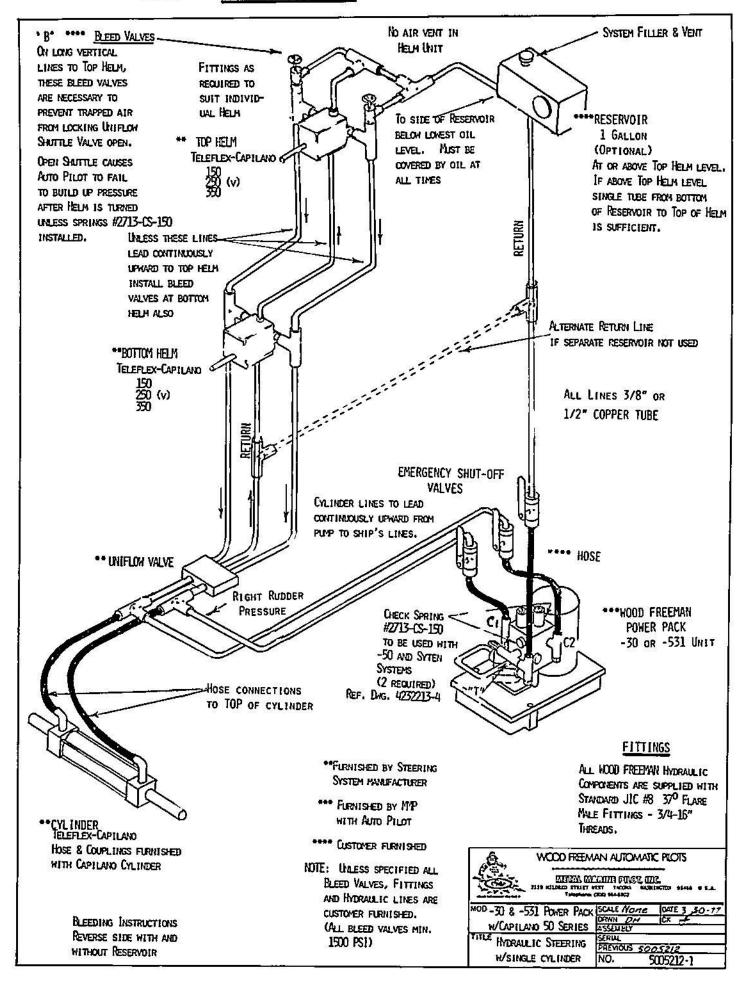
POWER PACK INSTALLATIONS * 500 SERIES * MAY, 1979 SECTION D

STANDARD FITTINGS FOR HYNAUTIC SYSTEM

SINGLE HELM INSTALLATION

- 1) 90 Degree elbow (4-4CBTXS)# 1/4 NPT 1/4 Tube
- 2) Street L (C3409X4# Cad. Pltd.) (2 required)
- 3) Running Tee (6RBTX-S)# 1/4 NPT x 3/8 Tube x 3/8 Tube (3 required)
- 3A) Straight Brass Connector
- Connectors (6FBTX-S)# 1/4 NPT x 3/8 Tube (3 required) 4)
- Union Tee (6JBTX-S)# 3/8 Tube x 3/8 Tube x 3/8 Tube (2 required) 5)
 - 6) Tube Connector (6FBTX-S)# 3/8 NPT x 3/8 Tube (6 required) (1 on each side of Worcester Valve)
 - 7) Worcester Shut-Off Valve (3/8-411YBB) 3000 psi (2 required)
 - Shut Off Valve (CBC-3/8) 400 psi (1 required) (Apollo Ball Valve or equivalent)
 - 9) 3/8 Double Braided 3500 psi Hose, Female swivel nut each end
 - 10) Noise Isolation Mounts (3 required) furnished with -531
 - 11) Straight Connector 3/8 Pipe to 1/2 Hose
 - * For each additional Helm, add Items (4) and (5) NOTE: If "B" is in the part number, mut and sleeve are included.
 - # Refers to Parker fitting number. Equivalent fitting of other manufacturers may be used.

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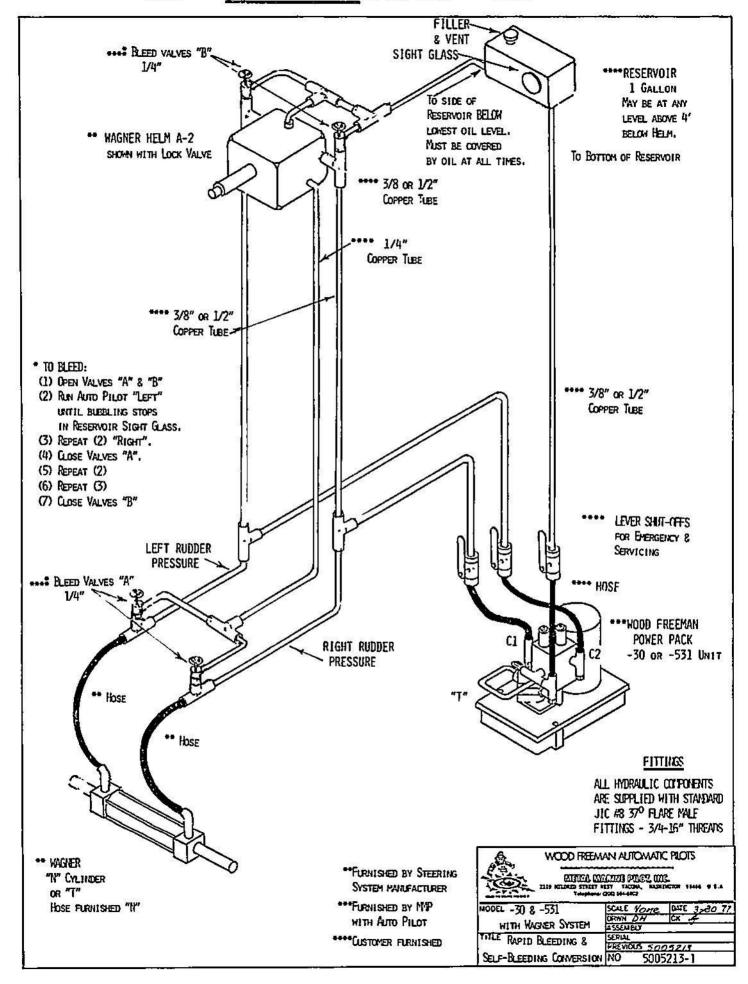
WOOD FREEMAND -30 & -531 POWER PACKS WITH CAPILANO 50 SERIES

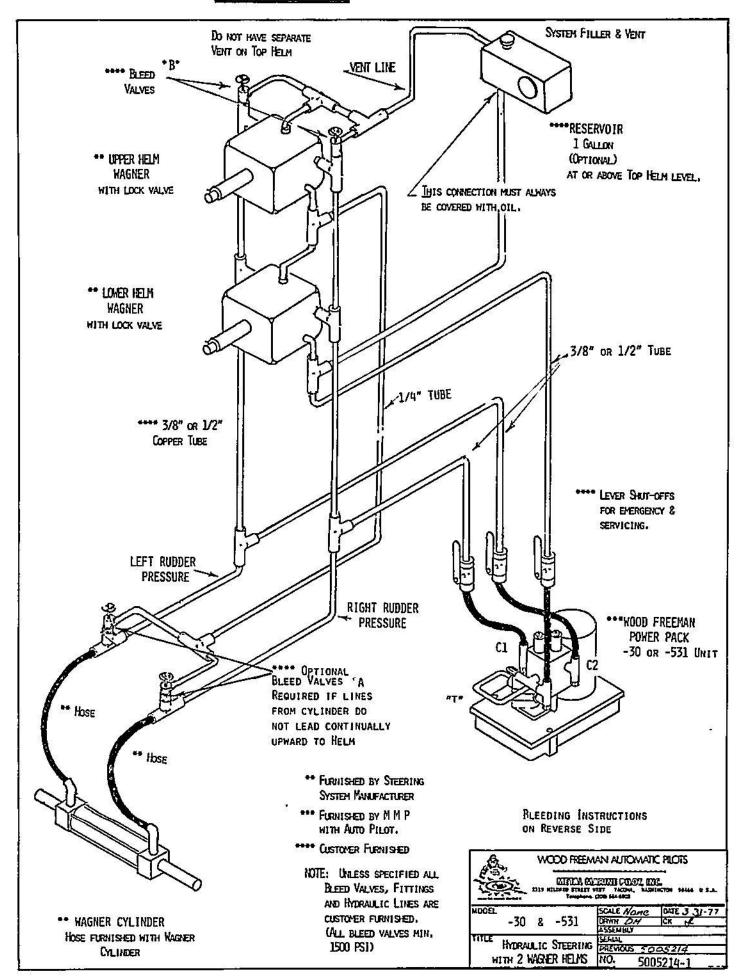
FILLING SYSTEM WITH OIL & PURGING AIR - USE AUTOMATIC TRANSMISSION FLUID "DEXRON" TYPE "A"

- 1) Fill Reservoir 3/4 full of proper oil "Dexron" Type A.
- 2) Open Bleed Valves "B" and Emergency shut-off valves (at Autopilot).
- 3) Run Autopilot "left" until bubbling stops in reservoir sight glass.
- 4) Repeat (3) "Right".
- 5) Rotate lower helm clockwise 10 turns.
- Repeat (5) counterclockwise.
- 7) Repeat (5) and (6) with upper helm.
- 8) Close Bleed Valves "B"; then open one turn.
- 9) Repeat Steps (5) through (7).
- 10) Close Bleed Valves "B".
- 11) After one week of operating, open Bleed Valves "B" one turn and repeat Steps (5) through (7).
- 12) Close Bleed Valves "B".

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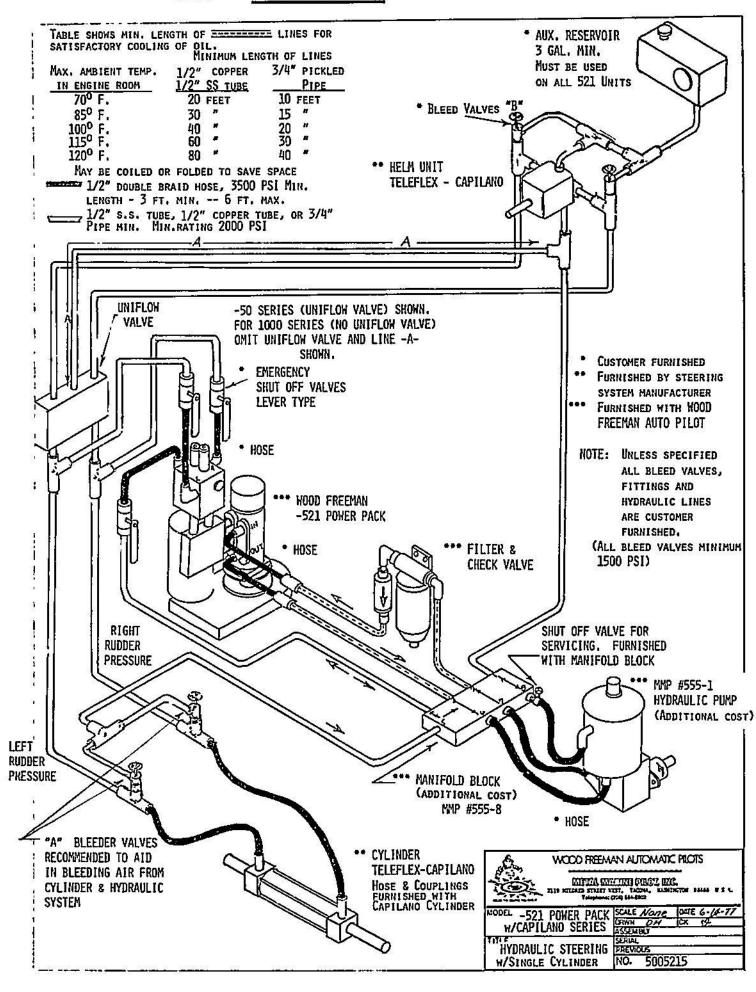
INSTRUCTIONS FOR PURGING AIR FROM SYSTEM DRAWING 5005214-1 WAGNER - DUAL HILM -30 OR -531 POWER PACK

* 500 SERIES *

- 1) Fill reservoir to top of sight gage with either #9 Turbine oil; or Type A "Dexron" Automatic Transmission Fluid.
- 2) Open Bleed valves "A" and "B" (if fitted).
- 3) Open shut off valves to power pack.
- 4) Rotate lower helm slowly to right for at least 20 turns or until resistance is felt.
- 5) Repeat (4) to left.
- 6) Repeat (4) and (5) with upper helm. Refill Reservoir to upper level of sight gage.
- 7) Run Autopilot power pack for right rudder for 30 seconds.
- 8) Repeat (7) to left.
- 9) Close Valves "B".
- 10) Rapidly rotate bottom helm alternately hardover left and right until no more bubbles appear in reservoir sight gage.
- 11) Repeat (10) with top helm.
- 12) Close bleed valves "A".
- 13) Refill reservoir as necessary.
- 14) System should now be ready for service.
- 15) Within the next 10 days, operate the system for about an hour underway, hand steering with bleed valves "A" opened 1/4 turn -Close bleed valves.
- 16) Repeat (15) whenever system appears "spongy" or if work has been done on the hydraulic system.

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WOOD FREEMAN® -521 POWER PACK WITH TELEFLEX-CAPILANO -50 SERIES HYDRAULIC STEERING GEAR

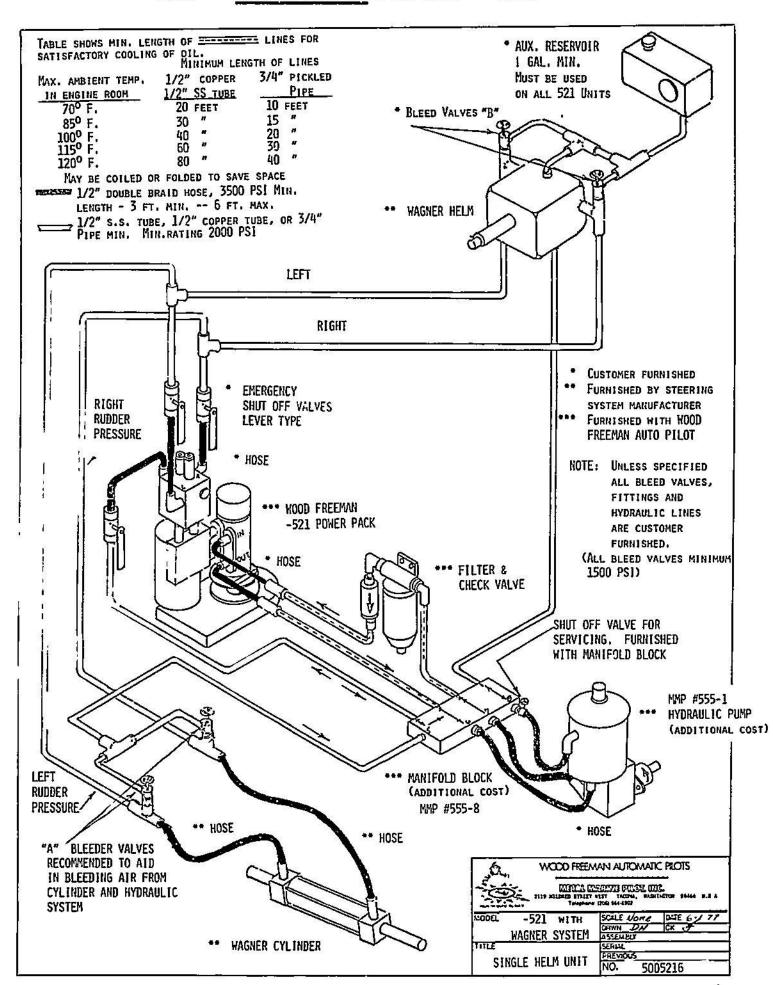
FILLING SYSTEM WITH OIL AND PURGING AIR - USE AUTOMATIC TRANSMISSION FLUID "DEXRON" TYPE A.

- 1) Remove cover from hydraulic pump reservoir (WCOD FREEMAN® 555-1 Pump only) - Fill Reservoir to top and replace cover.
- 2) Fill Auxiliary reservoir.
- 3) Open manifold block valve at position #8 to allow flow between Helm Pump (or reservoir) and hydraulic pump.
- 4) Open all emergency shut-off valves on -521 Power Pack.
- 5) Open Bypass and bleeder valves at rudder cylinder and bleed valves at helm. On -50 and Syten Series Teleflex-Capilano helms, external bleed valves shown are recommended to prevent air trapping in helm lines.
- 6) Operate engine (or electric motor drive) to run hydraulic pump.
- 7) Selector Switch on 500 Console on "RUDDER DIAL".
- 8) Dial 35 Degrees left rudder on Console, and hold for 30 sconds, then 35 Degrees right rudder for 30 seconds.
- 9) Repeat Step (8) 4 times.
- 10) Close Bleed and Bypass valves at cylinder.
- 11) Turn helm pump hardover port and continue turning for 10 extra turns.
- 12) Repeat (7) to starboard.
- 13) Replenish oil level in reservoir as necessary.

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Telephone (206) 564-5902

MAY 1979



* FILLING AND AIR PURGING INSTRUCTIONS *

WOOD FREEMAN -521 POWER PACK WITH WAGNER HYDRAULIC SYSTEM AND CAPILANO 1000 SERIES SINGLE HELM SYSTEMS

For rapid and complete purging of air without loss of fluid, component connections and the use of bleed valves and auxiliary reservoir (customer furnished), shown on Drawing 5005216 are recommended.

The following procedure is based on the configuration of Drawing 5005216, using MMP #555-1 engine driven pump.

The recommended fluid for maximum pump and ~521 Power Pack life is A.T.F. (Automatic Transmission Fluid), Dexron Type A, available at all service and marine stations.

FILLING AND PURGING MANUAL STEERING (HELM) SYSTEM (Engine not running)

- 1 Open bypass and bleeder valves at cylinder.
- 2 Fill auxiliary reservoir to 3/4 mark, and add oil to maintain this level during filling and purging.
- 3 Rotate helm right 30 turns rapidly (Bottom helm followed by top helm on dual helm).
- 4 Repeat (3) for helm left (Bottom helm followed by top helm on Dual helm).
- 5 Repeat (4) and (5) until oil level in reservoir remains constant.
- 6 Close bleeder valves at cylinder.
- 7 Open bleed valves at helm one turn.
- 8 Slowly rotate helm right 30 turns.
- 9 Slowly rotate helm left 30 turns.
- 10 Close belm bleed valves.
- 11 Bring oil level in auxiliary reservoir to full level.

Continued on next page.

FILLING AND AIR PURGING INSTRUCTIONS * CONTINUED

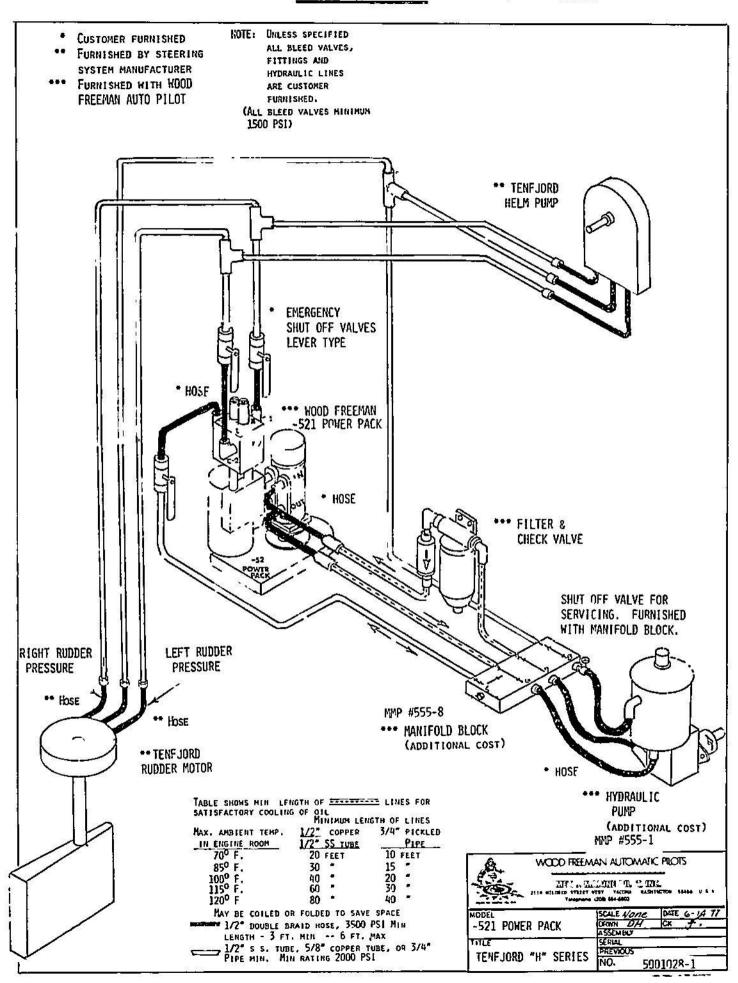
FILLING AND PURGING POWER STEERING (-521) SYSTEM

- 12 Close reservoir shut off valve on manifold block.
- 13 Remove cover from pump reservoir and fill reservoir.
- 14 Open bleed valves "A" at cylinder.
- 15 Start engine and operate at idle speed.
- 16 Add oil to hydraulic pump reservoir as needed to maintain oil level at vent hole in side of reservoir.
- 17 When oil level remains steady, increase engine speed to 1000 R.P.M. adding oil to reservoir as necessary to maintain level.
- 18 Open emergency shutoff valves on -521 Power Pack, if closed.
- 19 Unplug 500 encoder plug (8 pin) from rear of 500 control console.
- 20 Turn 500 Autopilot Function Selector to "RUDDER DIAL".
- 21 Turn "RUDDER DIAL" full left.
- 22 Replenish oil in pump reservoir as necessary.
- 23 Repeat (21), and (22), but with "RUDDER DIAL" full right
- 24 Repeat (21), (22) and (23) until oil level remains constant in pump reservoir.
- 25 Replace cap on pump reservoir.
- 26 Open shutoff valve on Manifold Block.
- 27 Close bleed valves "A" at cylinder.
- 28 Plug 500 Encoder cable (8 pin) into rear of 500 Control Console.

FOLLOW UP PURGING FOLLOWING INITIAL PURGE

- 29 After 10 to 30 hours of underway operation, purge manual system by:
 - (A) Stop engine.
 - (B) Open top helm bleed valves.
 - (C) Turn helm right 5 turns, then left 5 turns.
 - (D) Repeat (C) 3 times.
 - (E) Close helm bleed valves.
 - (F) Fill auxiliary reservoir to 3/4 full level.

CAUTION: DO NOT RUN ENGINE DRIVEN PUMP WITH HELM BLEED VALVES OPEN.



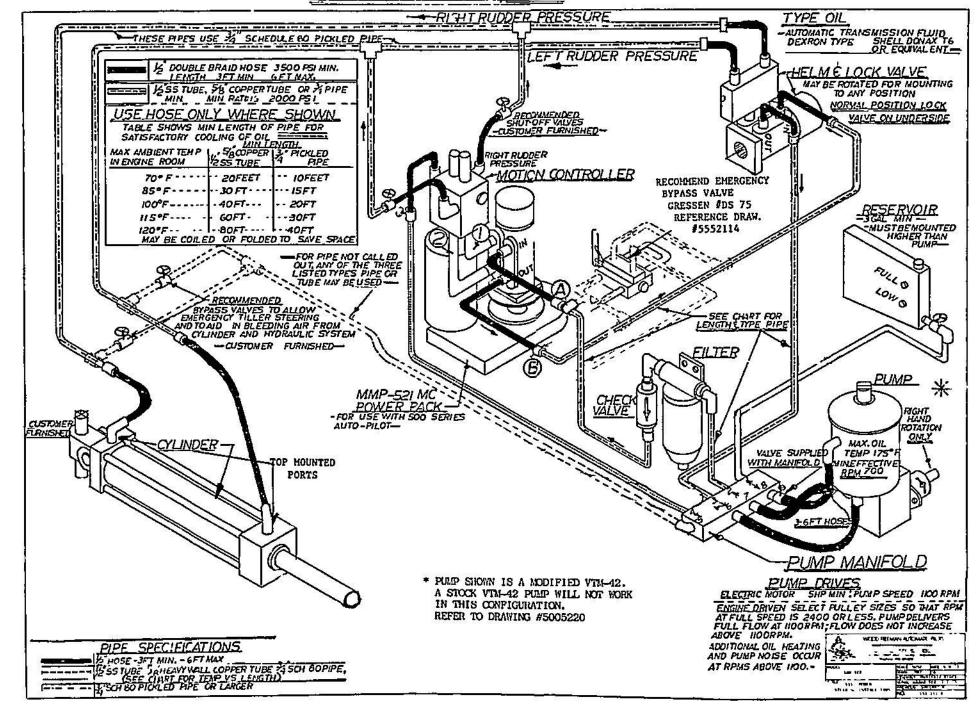
WOOD FREEMAN® -521 POWER PACK WITH TENFJORD "H" SERIES

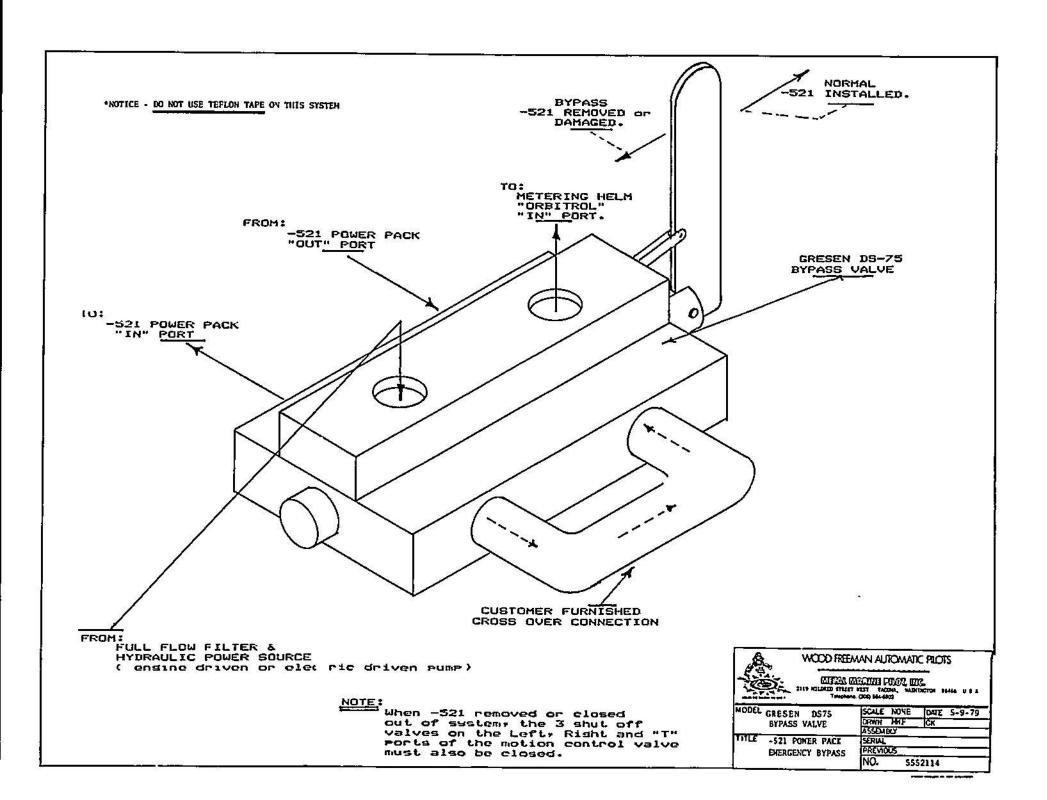
FILLING SYSTEM WITH OIL AND PURGING AIR - USE AUTOMATIC TRANSMISSION FLUID "DEXRON" TYPE A.

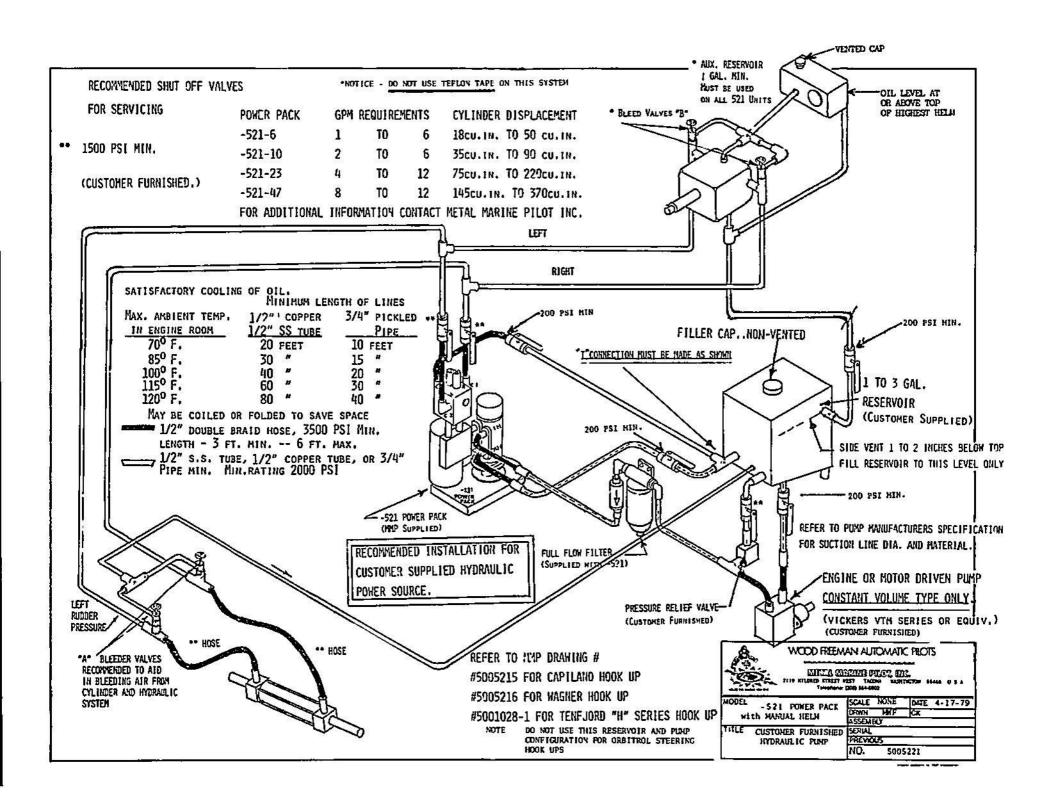
- 1) Remove cover from hydraulic pump reservoir (WOOD FRFFMAN® 555-1 Pump Only) - Fill Reservoir to top and replace cover.
- 2) Fill Tenfjord Helm pump.
- 3) Open manifold block valve at position #8 to allow flow between Helm pump and Hydraulic pump (engine-driven).
- 4) Open all emergency shut-off vlaves on -521 Power Pack.
- 5) Operate engine (or electric motor drive) to run adraulic pump.
- 6) Turn helm pump hardover port and continue turning for 10 extra turns.
- 7) Repeat (6) to starboard.
- 8) Replenish oil level in helm pump to maintain high level.
- 9) With Pilot Console selecting "RUDDER DIAL", move RUDDER DIAL full right. Crank helm to left as rapidly as possible for 20 turns.
- 10) Repeat (9), but with RUDDER DIAL full left and helm cranked to right.
- 11) Replenish oil level in helm pump as necessary.
- 12) Remove encoder cable plug (8-pin) from back of 500 Pilot Console.
- 13) RUDDER DIAL 35 degrees right for 20 seconds.
- 14) Repeat (13) to left.
- 15) Replace encoder cable plug in back of Console (8-pin)
- 16) Replenish oil in Helm pump as necessary.
- 17) Repeat Steps (12) through (16) whenever system feels "spongy" on hand steering or autopilot appears to be continually oscillating or "hunting".
- Repeat Steps (1) through (16) whenever componenets are relaced or piping connections are disconnected in the hydraulic circuit.

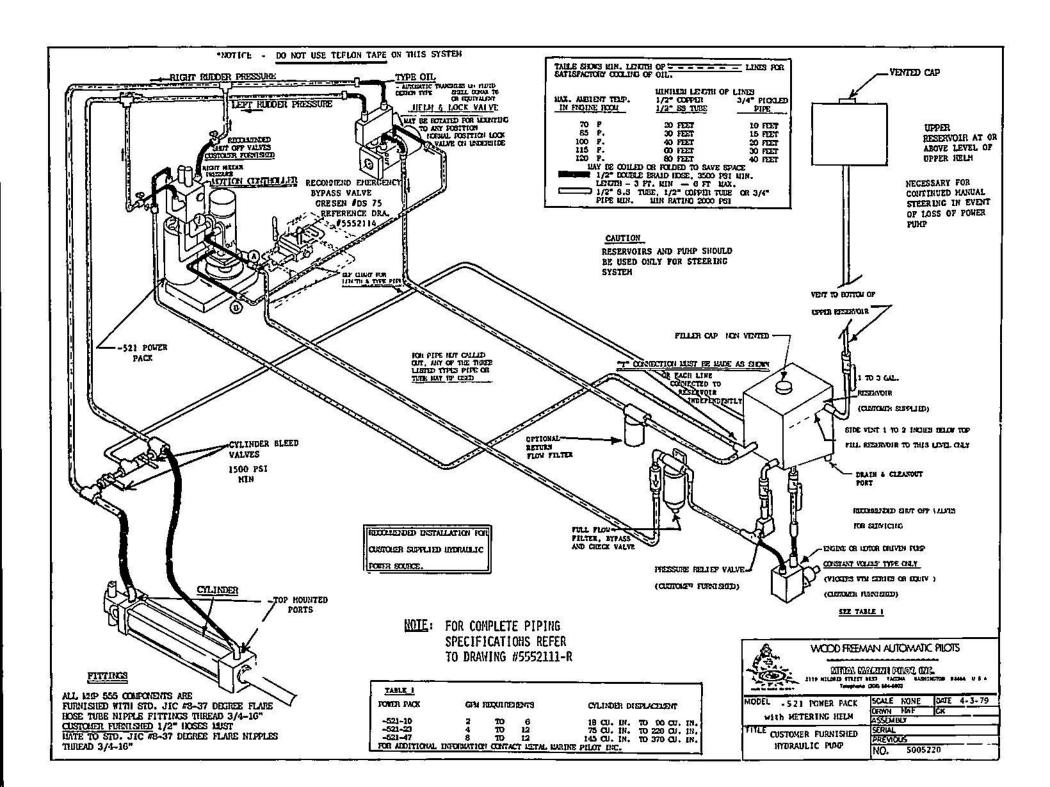
METAL MARINE PILOT, INC. 2119 West Mildred Street Tacoma, Washington 98466

Telephone (206) 564-5902









J[®]AUTOMATIC PILOTS COOD FREEMAN

LIMITATION OF SOLENOID VALVES

WHEN USED WITH AUTOPILOT CONTROLS

An 8 second hardover time for 90 degrees of rudder is within the control capability of the 500 Series WOOD FREEMAN AUTOMATIC PILOT when using continuous duty solenoid valves.

Provided:

- 1 All entrapped air is removed from the steering system.
- 2 The steering linkage is tight, without slack in pin or mountings.
- 3 No internal leakage is present in components.

However, our experience has been that hardover to hardover times of 12 seconds or less produce unwanted noise and shock loads in the hydraulic system. If intermittent duty solenoids are used, a hardover to hardover time of 13 seconds or more should be The rudder should not be allowed to continually oscillate if over-heating and failure of the solenoid valves is to be prevented.

The following should be observed when using solenoid valves for best service and performance:

- 1 Use continuous duty, oil immersed, D.C. solenoids.
- 2 Limit the maximum rudder rotation rate to 7 degrees per second or less. Generally 12 to 16 seconds hardover to hardover.
- 3 A three (3) port pressure compensated flow control valve must be used with engine driven pumps to regulate the rudder rotation rate.
- 4 If solenoid valves are controlled by devices other than the autopilot, such as a "jog" control, an isolation switch must be installed. Refer to drawing #5006135.
- 5 Each helm unit must be connected with a lock valve.

If hardover to hardover times desired are less than 13 seconds, we recommend our Code -521 Power Pack in place of solenoid valves and flow control valves. Under the control of the 500 Series Auto Pilot, the -521 Power Pack meters the oil from an external hydraulic source to the rudder cylinders silently and without shock loads.

In addition, the -521 Power Pack features pressure relief to the tank and across the line, thermal expansion and contraction relief, and dual Auto Pilot lock valves.

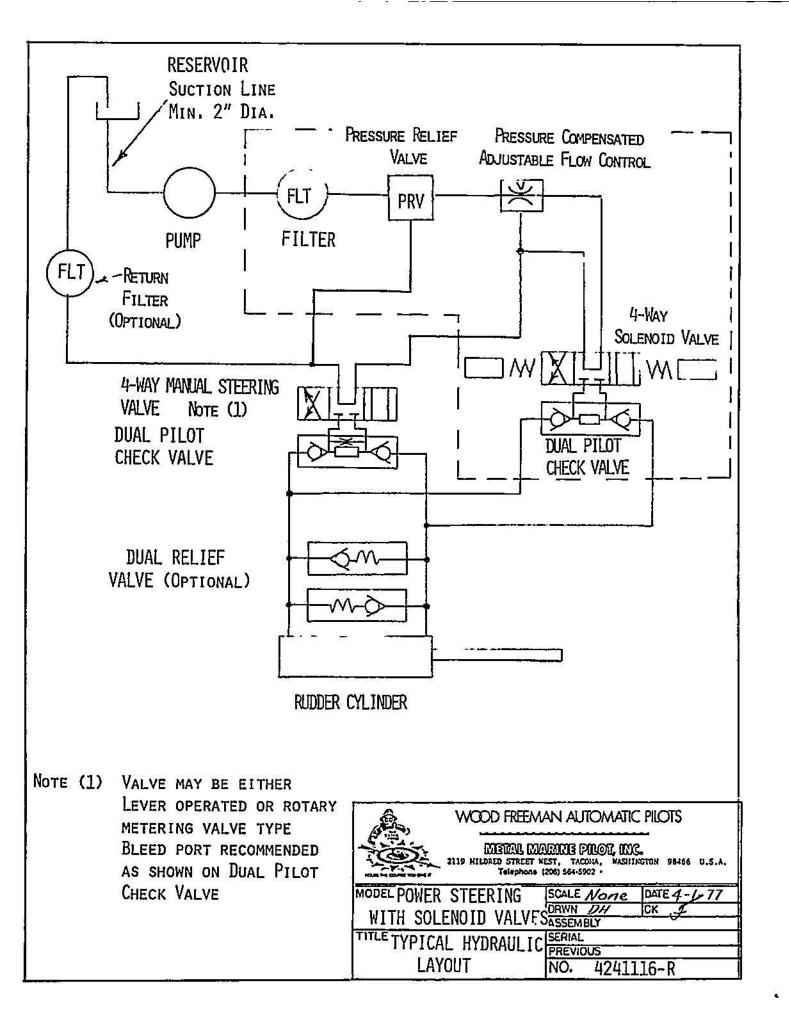
Requirements for external hydraulic source are:

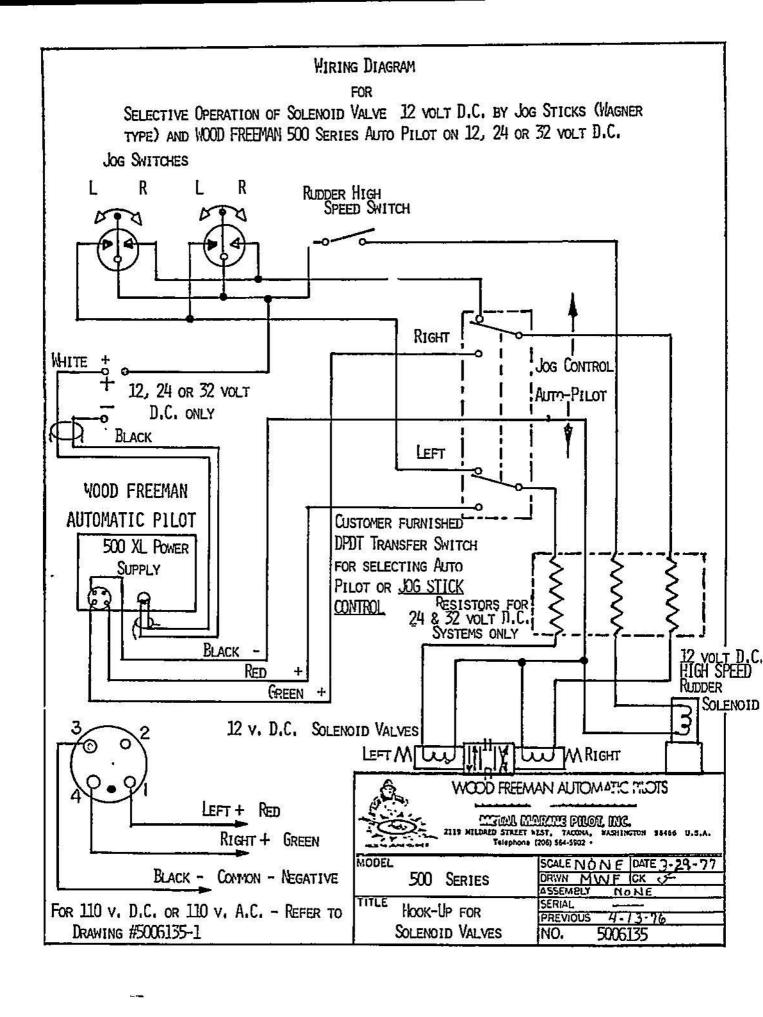
	Rudder Cyl.	Displacement GPM Flow *		
Time h.o h.o.	6 seconds	16 seconds	min.	max.
500-B XL-521-10MC	18 cu. in.	90 cu. in.	2	6
500-B XL-521-23MC	75 cu. in.	220 cu. in.	4	12
500-B XL-521-47MC	145 cu. in.	370 cu. in.	8	12

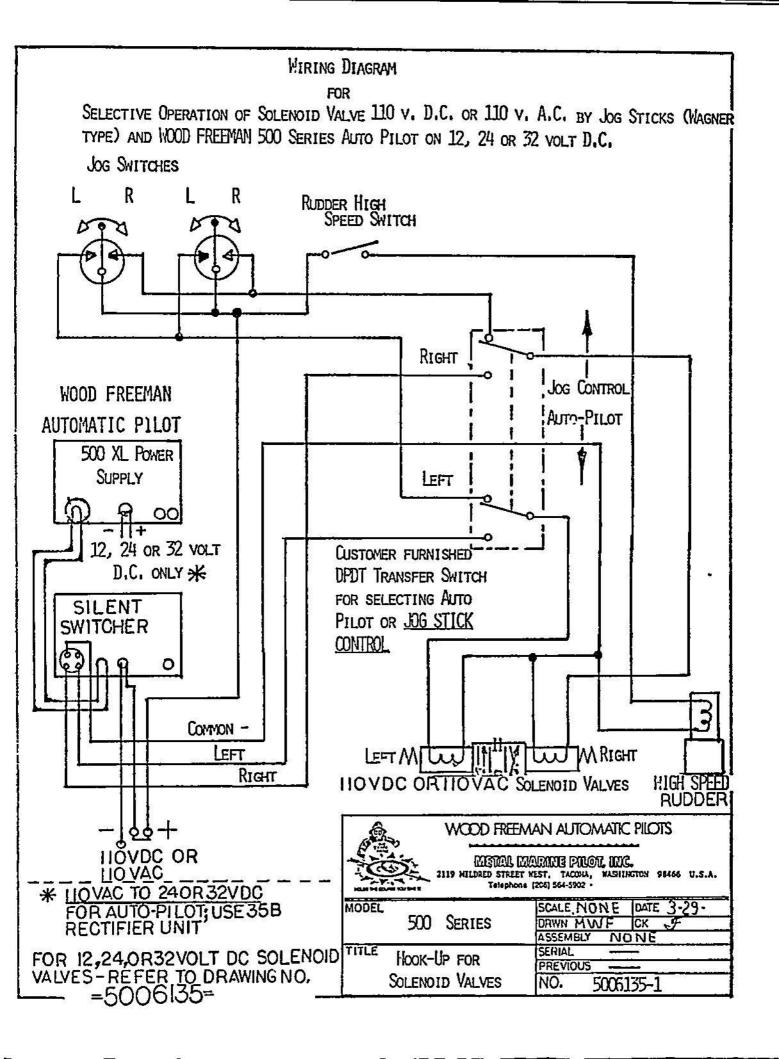
^{*} Pump pressure relief valve required - 1000 PSI Min. 1500 PSI Max.

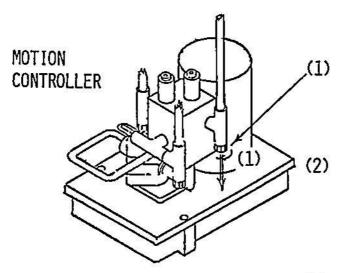
METAL MARINE PILOT, INC.

2119 MILDRED STREET WEST, TACOMA, WA., 98466 (206) 564-5902









REMOVE CAP NUT ON LOWER SIDE OF "T" FITTING

HOOK SMALL PIECE OF WIRE INSIDE SCREEN AND WITHDRAW SCREEN

(3) FLUSH SCREEN WITH
KEROSENE OR CLEANING
SOLVENT

(4) REPLACE SCREEN*
AND CAP NUT

*NOTE: With screens having a single Flange, install with flange on Bottom.

WITH SCREENS HAVING A FERRULE ON BOTH ENDS, EITHER END MAY

BE INSERTED.

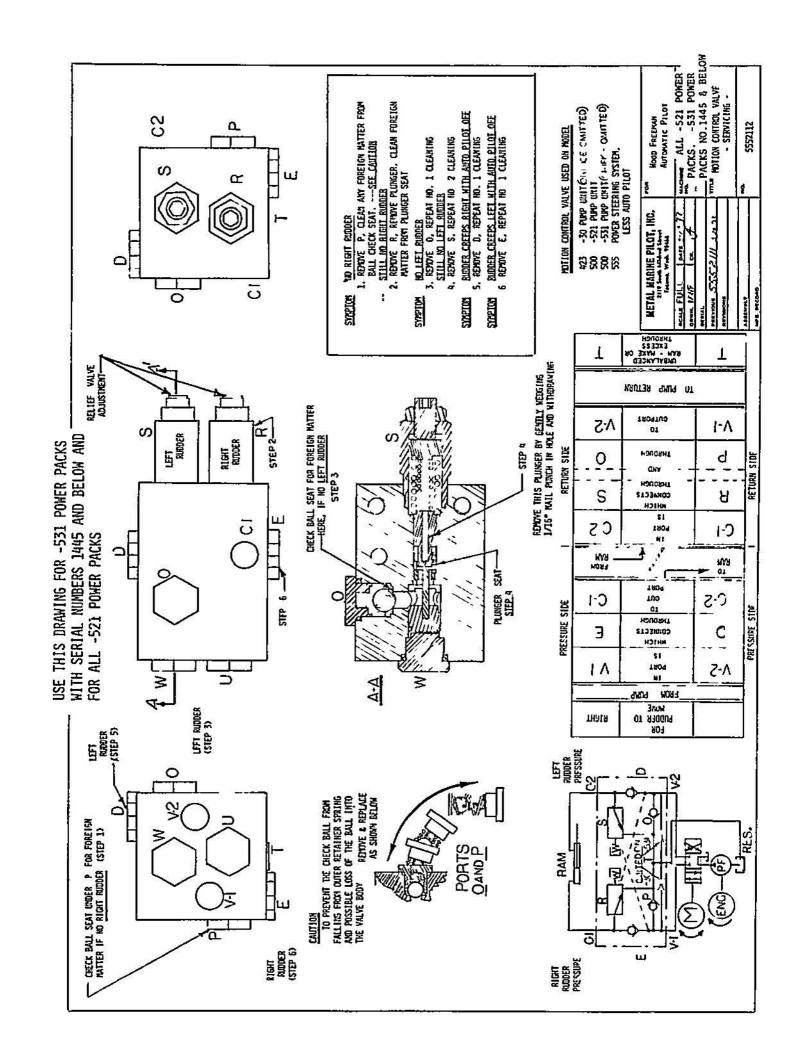


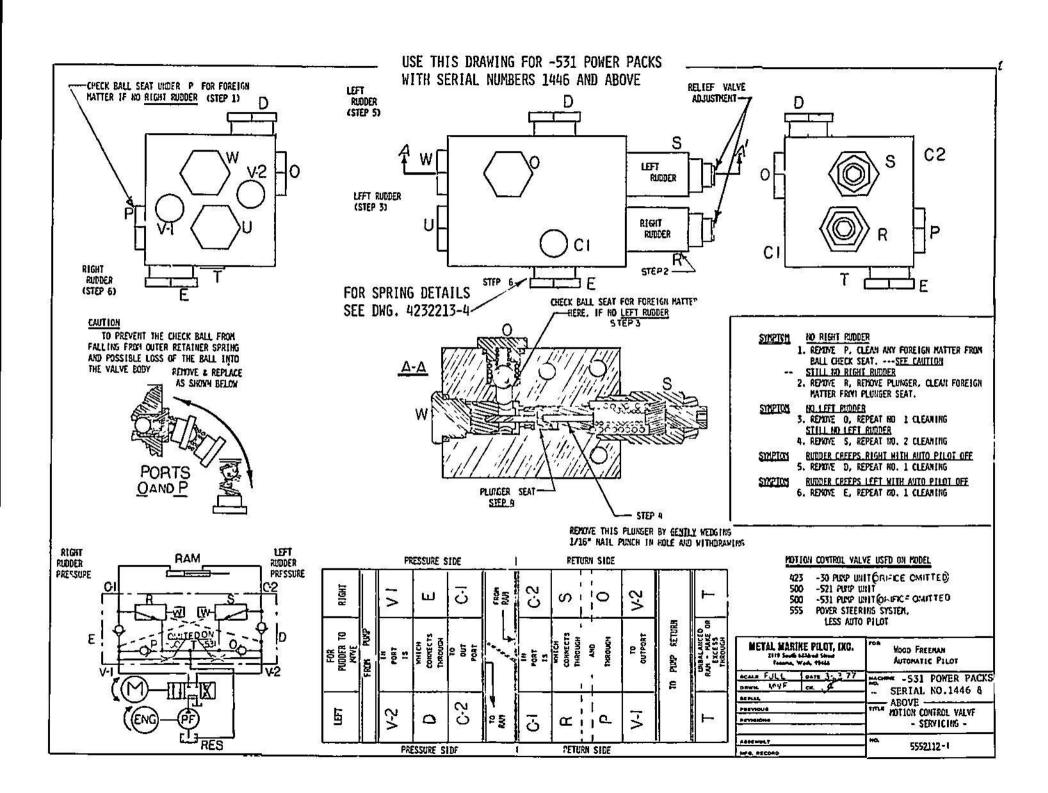


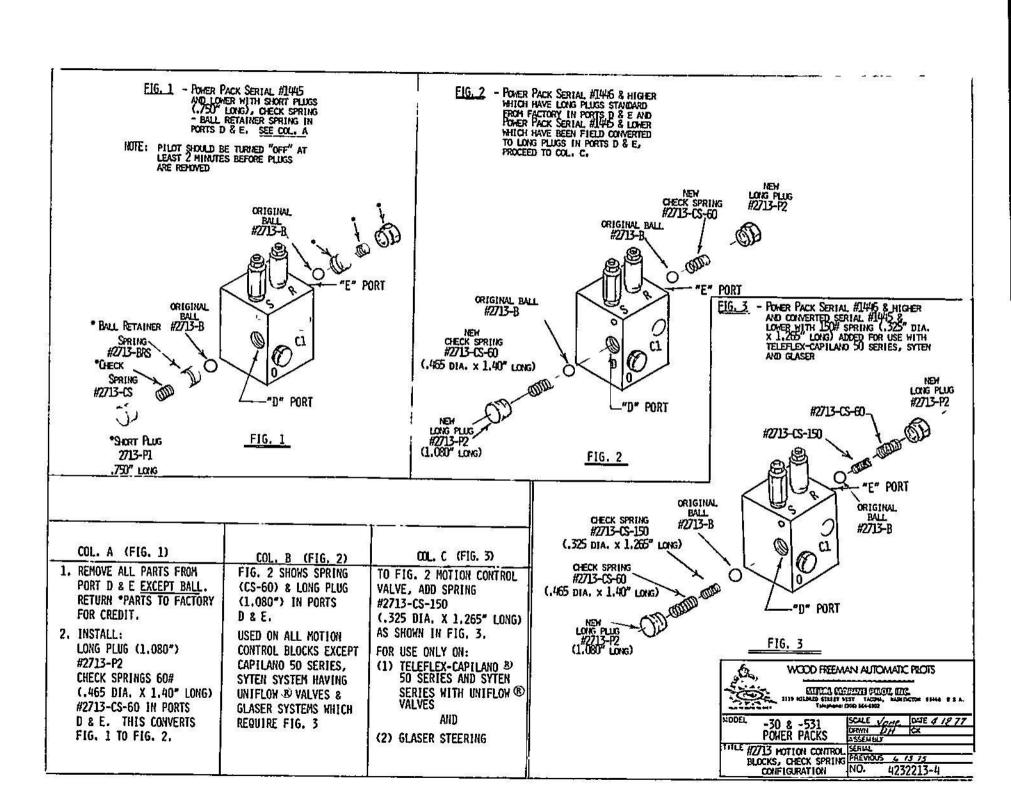
WOOD FREEMAN AUTOMATIC PILOTS

MINIAL MARKET PROT, INC.
2119 HILDRED STREET NEST, TACORA, WASHINGTON 98466 U.S A.
Telephone (206) 564 5902

MODEL	POWER PACKS	SCALE None	DATE 4-12 77
-30 & -531	DRWN DH	CK .	
	ASSEMBLY	al al kons	
FILTER SCREEN REYOVAL	SERIAL		
	PREVIOUS 10-20-72		
	NO. 423	2213-3	







SERVICE INSTRUCTIONS

555-2 FULL FLOW FILTER * REPLACING FILTER ELEMENT *

WHEN TO REPLACE FILTER ELEMENT

The filter element should be replaced after the first 25 to 50 hours of operation of a new system. Then every 2000 hours thereafter.

The process should be repeated each time the steering system is opened for service or repair.

TOOLS REQUIRED:

1 - Adjustable wrench up to 1-3/4 inch.

PARTS REQUIRED:

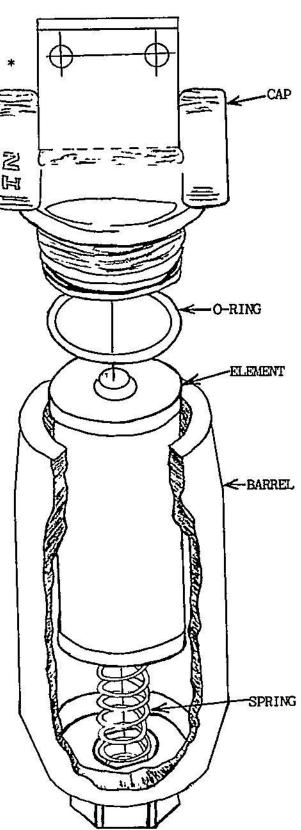
1 - Filter element kit #2756-1.

PROCEDURE:

- 1 Rotate barrel clockwise using wrench on hex at bottom of housing.
- 2 Spring will push element upward for easy removal.
- 3 Replace O-ring.
- 4 Empty all oil from the barrel. Flush barrel with clean oil to clean out any debris from inside the barrel.

DO NOT USE CLOTH OR PAPER TOWEL CAUTION: TO WIPE OUT BARREL.

- 5 Insert new element into the barrel.
- 6 Screw barrel back onto cap.



WOOD FREEMAN® AUTOMATIC PILOTS

* 500 SERIES *

DOCKSIDE AND UNDERWAY CHECKOUT

TO USE:

The following steps are in numerical order. Proceed with each step in sequence, DO NOT JUMP STEPS unless instructed to do so. Faults and corrective measures will be indented from the margin and preceded by a number and followed by a letter. i.e. 9A.

IN CASE OF DIFFICULTIES:

If you should encounter difficulties during the checkout procedure,

Review and Recheck component installation.

Repeat all previous checkout steps.

If difficulties persist,

Go to STEPS IN TROUBLE-SHOOTING *
SERVICE II OR SERVICE III

NOTE: SERVICE III is available from factory upon request.

You may also contact the factory for telephone assistance -Monday through Friday - between 8:30 AM and 5:00 PM. (Pacific local time). (206) 564-5902 - (Please - no collect calls)

NOTE:

The DOCKSIDE CHECKOUT and UNDERWAY CHECKOUT must be used to complete an initial installation.

They should also be used after completing the trouble shooting guides, SERVICE II or SERVICE III.

TOOLS REQUIRED:

The following tools are required to do the DOCKSIDE and UNDERWAY CHECKOUT:

- 1 Small to medium size bit, flat blade, screw driver.
- 1 Set of Jumper Plugs 1, 8-pin & 1, 9-pin with pins 2 & 3 jumpered together (supplied with the AUTOPILOT).
- 1 WOOD FREEMAN® Rudder Angle Indicator,

or

1 - WOOD FREEMAND 500 SERIES Field Test Meter,

or

a volt/ohm meter with a 3 to 5 volt scale,

OI

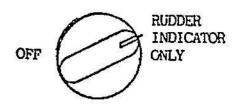
a 500-0-500 micro amp meter.

(These instructions do not detail the use of the last 2 types of meters.)

METAL MARINE PILOT, INC. 2119 MILDRED STREET WEST TACOMA, WASHINGTON, 98466 TELEPHONE (206) 564-5902 STEP 1 - Set the Control Console FUNCTION SWITCH to: "RUDDER INDICATOR CNLY".

NOTF:

For initial installations or replacement of the XL POWER SUPPLY. complete STEPS 2 and 3. For subsequent checkouts go to STEP 4.



FUNCTION SWITCH

SECTION E

* XL POWER SUPPLY CHECKOUT *

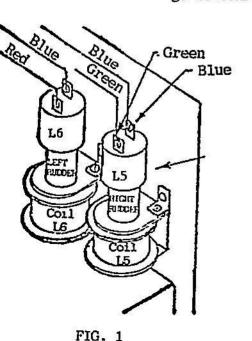
STEP 2 - Remove the 4 corner screws from the front panel of the XL POWER SUPPLY. Remove the chassis from the housing.

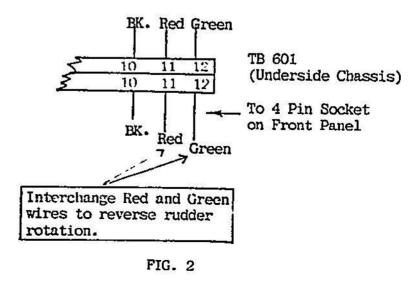
> CAUTION: DO NOT TILT CHASSIS OR HOUSING MORE THAN 30 DEGREES to prevent mercury relays from energizing.

STEP 3 - Locate the two mercury contactors, 15 & L6, mounted side by side on the inside of the front plate. (FIG. 1) Both contactors have a BLUE common wire. L5, (RIGHT rudder), has a GREEN wire. L6, (LEFT rudder), has a RED wire.

> Using a short piece of insulated wire, (at least #14) or an insulated screw driver, momentarily jumper across the GREEN and BLUE wires on top of mercury contactor L5.

- If the POWER PACK energizes to the RIGHT, then go to STEP 4.
- If the POWER PACK energizes to the LEFT, then go to STEPS 3A through 3D.
 - 3A Remove the 20 amp fuse from the XL POWER SUPPLY front panel.
 - 3B Turn the XL POWER SUPPLY upside down
 - 3C Interchange the RED and GREEN wires (#11 & #12) on the 4 pin socket side of the 12 pin terminal strip, TB 601, (FIG. 2).
 - 3D Turn unit right side up replace 20 amp. fuse go to STEP 3

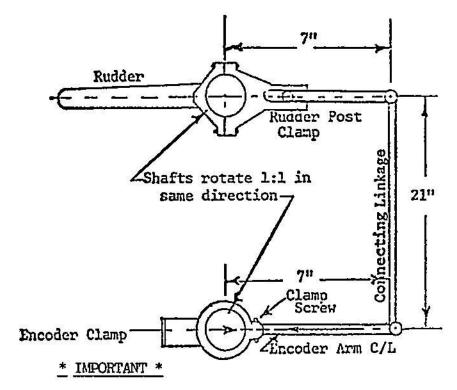




* ENCODER CHECKOUT *

STEP 4 - Center the rudder with the wheel or tiller.

STEP 5 - Inspect the mounting configuration of the ENCODER and CONNECTING LINKAGE. Opposite sides must be equal and parallel. (FIG. 3) Adjust RUDDER POST CLAMP and LINKAGE ROD as necessary.



OPPOSITE SIDES MUST BE OF EQUAL LENGTH (+/- 1/8") OPPOSITE SIDES MUST BE PARALLEL

FIG. 3

STEP 6 - Loosen Encoder Clamp Screw (7/16 hex head). Rotate Encoder body to align ARROW on top of Encoder with the CENTER LINE of the ARM (arrow on encoder points at arrow in arm).

This is a preliminary adjustment. Final adjustment will be made in the UNDERWAY CHECKOUT section.

FIG. 3 shows a standard mounting configuration. NOTE:

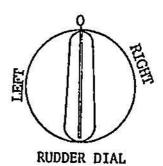
If Encoder is mounted inverted, the Arrows must point AWAY from each other. For any other Encoder mounting refer to ENCODER Installation Instructions for correct configuration of components.

* RUDDER DIAL CHECKOUT *

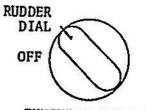
STEP 7 - Set the NULL knob to: Straight up "AVERAGE".



STEP 8 - Set the "RUDDER DIAL" pointer (knob) to: "0" (zero).



STEP 9 - Set the FUNCTION SWITCH to: "RUDDER DIAL".



FUNCTION SWITCH

If the rudder remains centered, go to to STEP 10.

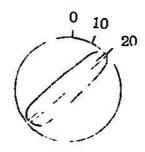
Disregard any "hunting", (continual oscillation of the rudder), NOTE: which may occur now.

If the Rudder goes hardover left or right, go to STEPS 9A through 9B.

9A - Go to ENCODER INSTALLATION Instruction for proper component configuration.

9B - Go to STEPS 1 through 6 inclusive.

STEP 10 - Set "RUDDER DIAL" pointer to: "20" degrees RIGHT.



- If the Rudder moves to approximately 20 degrees RIGHT, go to STEP 11.
- If the Rudder moves hardover LEFT, go to STEPS 10A through 10C.

10A - Go to Cable Installation Instructions for proper connections.

10B - Inspect ALL CABLING for cuts, splices or other modifications.

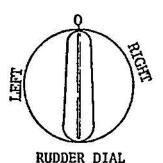
10C - Go to STEP 2 & STEP 3.

* DAMPER & NULL ADJUSTMENTS *

Note: If a WOOD FREEMAN® RUDDER ANGLE INDICATOR is not installed. connect one of the alternative meters. See appendix for meter connections.

* 500 SERIES *

STEP 11 - Set "RUDDER DIAL" pointer to: "0" (zero).



STEP 12 - Remove the black cover plug from the DAMPER. Rotate the DAMPER control full COUNTERCLOCKWISE. Slowly rotate the DAMPER control clockwise until the continual oscillation of the rudder, ("hunting"), stops.



DAMPER

If the "hunting" of the rudder stops before the DAMPER is full clockwise, go to STEP 13.

If the Damper is rotated fully clockwise and the rudder "hunting" does not stop, go to STEPS 12A through 12D.

12A - Recheck STEP 5 - then go to STEP 12.

12B - Check Steering system for "mechanical slack" and correct as required to eliminate slack - go to STFP 12.

12C - On hydraulic steering, bleed steering system, (refer to steering system TROUBLE-SHOOTING GUIDE) - go to STEP 12

12D - Rotate NULL knob to the 9 o'clock, "BROAD" position go to STEP 12.

NOTE: If "hunting" persists, review the installation. Check for any connecting cables that may be CUT, SPLICED, BROKEN, OR OTHERWISE MODIFIED. If there are no apparent modifications, go to TROUBLE-SHOOTING * SERVICE II or SERVICE III.

- STEP 13 Rotate the RUDDER DIAL pointer (knob) in 10 separate increments to 10 degrees RIGHT. (1 increment is approximately the width of the white line on the pointer knob.)
 - If the rudder responds to each increment of RUDDER DIAL pointer motion with equal travel and comes to rest at 10 degrees right, go to STEP 14.
 - If the RUDDER DIAL pointer must be rotated several increments before the rudder will respond, go to STEP 12.
 - NOTE: If STEP 12 appears to be correct and there is still a "sensitivity" problem in STEP 13, refer to the APPENDIX -COMPONENT SENSITIVITY TESTS.

* COMPASS CHECKOUT * (ALL MODELS)

* 500 SERIES *

STEP 14 - Set TRIM knob (Compass Course) to: straight up.



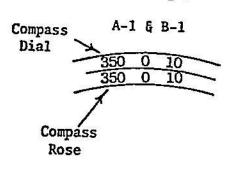
COMPASS TRIM

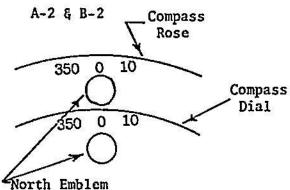
STEP 15 - Set RUDDER knob to: straight up - "AVERAGE".



STEP 16 - Rotate the COMPASS COURSE DIAL (on the top of the compass unit) 5 complete turns to be sure of good slip ring contact. (On "B" units also rotate the YOKE 5 turns.)

STEP 17 - Rotate the COMPASS COURSE DIAL so the COURSE DIAL numbers match with the COMPASS ROSE: "O" aligned with "O".





STEP 18 - Set the FUNCTION SWITCH to: "COMPASS STEER".

If the Rudder Angle Indicator needle centers

If the rudder centers to the same position as in STEP 4, go to STEP 19.

FUNCTION SWITCH If the RAI needle does not center (or rudder does not center), go to STEPS 18A & 18B.

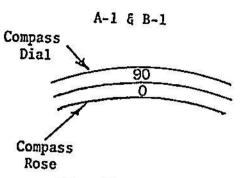
18A - Reset the TRIM knob (Compass course) to: "straight up" -

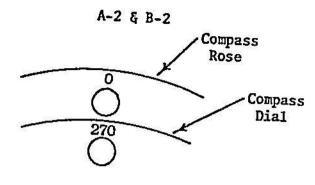
go to STEP 18.

18B - Go to TROUBLE-SHOOTING * SERVICE II or SERVICE III.

COMPASS STEER **OFF**

STEP 19 - Rotate COMPASS COURSE DIAL disk 90 degrees counterclockwise.



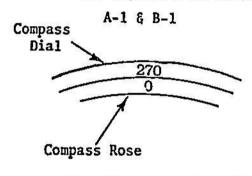


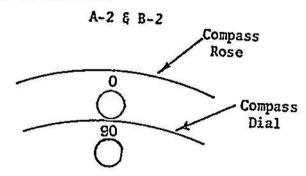
SECTION E

If rudder moves RIGHT 15 to 20 degrees, go to STEP 20.

If rudder moves LEFT or rudder does not move, go to TROUBLE-SHOOTING * SERVICE II or SERVICE III.

STEP 20 - Rotate COMPASS COURSE DIAL disk 180 degrees. (90 degrees from original matching position)





If rudder moves LEFT 15 to 20 degrees, go to STEP 21.

If rudder does not move LEFT, go to TROUBLE-SHOOTING * SERVICE II or SERVICE III.

STEP 21 - Set the RUDDER knob to: "2 KNOTS" - full clockwise.

> If the rudder moves further LEFT approximately 30 to 45 degrees, go to STEP 22.



If rudder travel is not increased, go to TROUBLE-SHOOTING * SERVICE II or SERVICE III.

STEP 22 -

If you have an "A" series pilot - (Compass not self-orienting), go to STEP 31 UNDERWAY CHECKOUT.

If you have a "B" series pilot - (Compass self-orienting). go to STEP 23.

* STANDBY-Self Orient CHECKOUT * (B1 & B2 SERIES CNLY)

- STEP 23 Remove the 8-pin ENCODER plug and cable from the rear of the CONTROL CONSOLE (top center position).

 Insert the 8-pin RED coded JUMPER PLUG.
- STEP 24 Set the TRIM knob (Compass Course) to: straight up.

COMPASS TRIM

STANDBY

(Self Orient)

STEP 25 - Set the RUDDER knob to:
"2 KNOTS" - full clockwise.



STEP 26 - Rotate COMPASS COURSE DIAL so the numbers on the COMPASS COURSE DIAL and the COMPASS ROSE differ 90 degrees.

(Unlock Compass Yoke on B2 models.)

STEP 27 - Set FUNCTION SWITCH to: "STANDBY-self orient".

FUNCTION SWITCH

If the orient motor rotates the compass bowl so the COMPASS COURSE DIAL and the COMPASS ROSE match * (some "hunting", up to 1 to 2 degrees may be present), go to STEP 28.

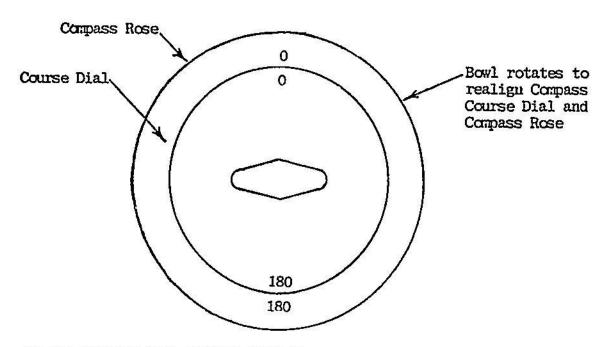
If Orienting occurs but COMPASS COURSE DIAL and COMPASS ROSE do not match *, then go to TROUBLE-SHOOTING * SERVICE II or SERVICE III.

If Orient Motor does not run, go to STEPS 27A through 27D.

- 27A Inspect compass base and yoke for compass wire stuck in gears SEE NOTE.
- 27B Inspect flex shaft for tight bends or kinks correct as necessary go to STEP 27.
- 27C Inspect orient motor pinion gear and drive gear for binding correct as necessary go to STEP 27.
- 27D Go to GEAR MOTOR Installation Instructions.

NOTE: IF COMPASS CABLE INSULATION HAS BEEN BROKEN THEN CONTACT FACTORY FOR A REPLACEMENT COMPASS, or send Compass, doubly packed, to the factory for repair.

* - On B1 models + or (-) 3 degrees. On B2 models + or (-) 2 degrees. STEP 28 - Rotate COMPASS COURSE DIAL clockwise 90 degrees and release.



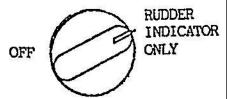
If the Compass bowl rotates back to matching position within 15 seconds, repeat STEP 28 4 to 5 times. Go to STEP 29.

If the response time to realign the COMPASS COURSE DIAL & COMPASS ROSE is longer than 15 seconds, go to STEPS 27A through 27D.

- STEP 29 Repeat STEP 28 rotating COMPASS COURSE DIAL counterclockwise, go to STEP 30.
- STEP 30 Remove 8-pin JUMPER PLUG from back of the CONTROL CONSOLE. Plug in the 8-pin ENCODER plug and cable (top center socket). Go to STEP 31 - UNDERWAY CHECKOUT.

* UNDERWAY CHECKOUT *

- STEP 31 Set FUNCTION SWITCH to: "RUDDER INDICATOR ONLY".
- STEP 32 Steer the vessel in a normal manner with the steering wheel or tiller. Hold a steady course with all engines ahead equally (perform this operation with as little wind or tide acting against the vessel as possible).

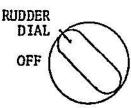


FUNCTION SWITCH

- STEP 33 Bring the vessel to a full stop. DO NOT MOVE THE RUDDER from the dead ahead underway position.
 - If the vessel is equipped with a WOOD FREFMAN® Rudder Angle Indicator,
 - If a WOOD FREEMAND Field Test Meter is available,
 - If a volt/ohm meter is available (with a qualified user), go to STEP 34.
 - If NO meter is available, go to STEP 36.
- STEP 34 Connect available meter to 4-pin RAI socket on the back of the CONTROL CONSOLE (bottom center socket). (To use a volt/ohm meter, set the meter to a scale range between 3 and 6 volts DC.) (Connect the meter leads to pins 1 and 2 of the RAI socket.)
- STEP 35 Loosen the ENCODER CLAMP SCREW (7/16 hex head) (Fig. 3 Page 2). Rotate the ENCODER BODY to center the meter. (On a volt/ohm meter rotate ENCODER BODY to indicate "zero" voltage.)

Tighten ENCODER CLAMP SCREW (This is the Final ENCODER adjustment) go to STEP 38.

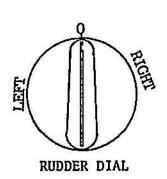
STEP 36 - Mark position of rudder or rudder actuating mechanism. Set the RUDDER DIAL pointer knob to: "0" - (zero).



FUNCTION SWITCH

Set FUNCTION SWITCH to: "RUDDER DIAL".

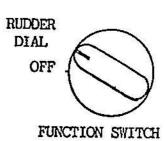
STEP 37 - Loosen the ENCODER CLAMP SCREW (7/16 hex head). Rotate the ENCODER BODY until the rudder or actuating mechanism returns to mark made in STEP 36. Tighten ENCODER CLAMP SCREW.



SFCTION E

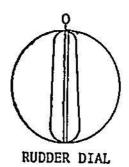
* RUDDER DIAL OPERATION *

STEP 38 - Set FUNCTION SWITCH to: "RUDDER DIAL". This will allow direct control of the rudder position with the RUDDER DIAL pointer (NON-AUTOMATIC).



STEP 39 - Set the RUDDER DIAL pointer to: "0" - (zero).

> Bring the vessel underway -Ahead - 2 to 4 knots.



If the vessel steers a straight course (not turning), go to STEP 40.

If the vessel starts to turn even slightly, go to STEP 31 (alignment).

STEP 40 - Steer the vessel with the RUDDER DIAL pointer. Set the RUDDER DIAL pointer to a desired rudder angle. The rudder will maintain the selected angle shown by the pointer. Set the pointer to "0" for amidships rudder.

* COMPASS STEERING * (ALL MODELS)

* 500 SERIES *

NOTE: Adjusting the CONTROL COMPASS is advised for all vessels before beginning this section. Adjustment of the CONTROL COMPASS will probably be required for steel vessels. Without proper compass adjustment, surrounding magnetic influences may cause the compass card to be unstable. This unstable condition will cause erratic COMPASS STEER operation.

STEP 41 - Adjust the vessel's speed to between 3 and 8 knots.

STEP 42 - Set TRIM (Compass Course) to: Straight up.



COMPASS TRIM

STEP 43 - Set the RUDDER knob to: "2 KNOTS" - full clockwise.



STEP 44 - Set the COUNTER RUDDER knob to: "AVERAGE" - straight up.



COUNTER RUDDER

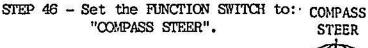
If the CONTROL COMPASS is accessible to the operator, A or B series, go to STEP 45.

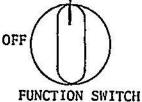
If the CONTROL COMPASS is not accessible to the operator, go to STEP 52.

UNDERWAY CHECKOUT

* COMPASS STEERING * (When compass is accessible to operator)

STEP 45 - Rotate COMPASS COURSE DIAL to a CARDINAL heading i.e. N, E, S, or W. ("B" Models will require Compass bowl to be manually rotated. Align center of compass with lubber line to a line parallel to the keel.)





STEP 47 - Allow the vessel to steady down on course.

If the COMPASS COURSE DIAL and the COMPASS ROSE match, go to STEP 48.

If the COMPASS COURSE DIAL and the COMPASS ROSE do not match, BUT are not more than 10 degrees different, go to STEPS 47A and 47B.

47A - Rotate the TRIM (Compass course) knob slowly left or right until the COMPASS COURSE DIAL and the COMPASS ROSE match. Go to STEP 48.

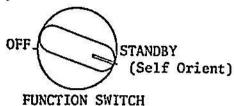
47B - Go to STEPS IN TROUBLE-SHOOTING * SERVICE II or SERVICE III.

NOTE: Step 47B will only be necessary if the internal trim controls have been readjusted since leaving factory.

STEP 48 - Repeat STEPS 46 and 47 for each CARDINAL heading -N, E, S, and W.

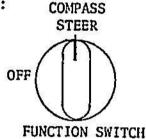
* COMPASS STEERING * (When compass is not accessible to operator) (B SERIES ONLY)

STEP 49 - Set the FUNCTION SWITCH to: "STANDBY - self orient".



STEP 50 - Steer the vessel to one of the CARDINAL headings, i.e. N. E. S. or W.

STEP 51 - Set the FUNCTION SWITCH to: "COMPASS STEER".



STEP 52 - Repeat STEPS 50 and 51 for each CARDINAL heading, i.e. N, E, S, and W.

> If difficulties arise in holding some courses, go to STEP 52A and 52B.

52A - Go to Compass Installation Instructions. 52B - Recheck CONTROL COMPASS magnetic adjustment, refer to Compass Adjustment section.

* REMOTE CONTROL FUNCTIONS * O (For all Series Pilots with Remote Controls)

STEP 53 - Set COMPASS COURSE as described in: Underway Checkout - * COMPASS STEERING *

STEP 54 - Set ALL Remote Control Units to: "COMPASS STEER".

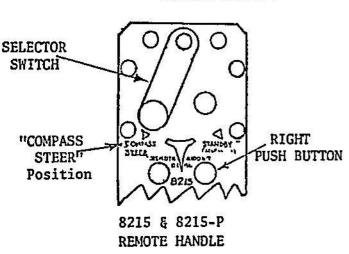
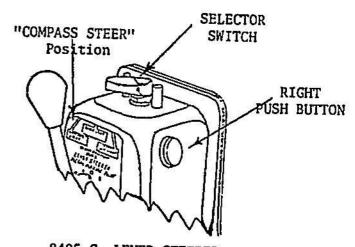


FIG. 4

STEP 55 - Set the Control Console FUNCTION SWITCH to: "REMOTE".



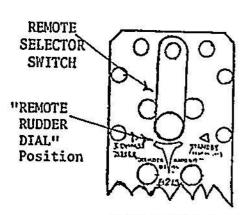
8405-C LEVER STEERER

FIG. 5

REMOTE OFF

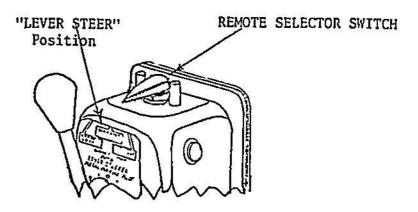
FUNCTION SWITCH

STEP 56 - Set the REMOTE SELECTOR SWITCH to: "RUDDER DIAL" (on a Lever Steerer "LEVER STEER").



8215 & 8215-P REMOTE HANDLE

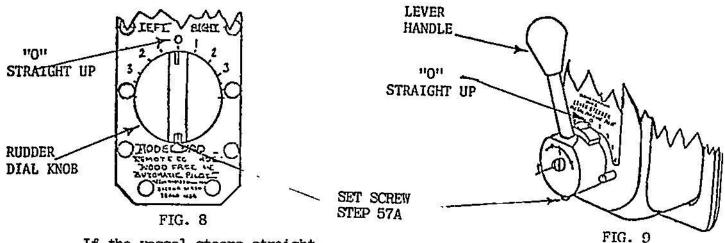
FIG. 6



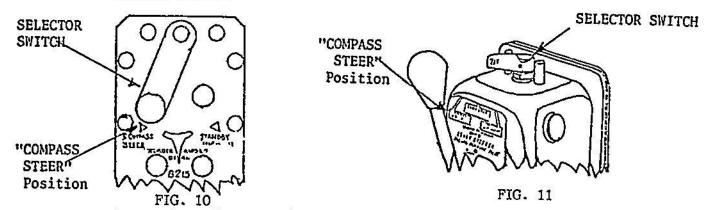
8405-C LEVER STEERER

FIG. 7

STEP 57 - Set the Remote RUDDER DIAL or (LEVER STEERER) to: "0" - straight up.



If the vessel steers straight, set the Remote SELECTOR SWITCH to: "COMPASS STEER".



Repeat STEP 57 for each Remote unit installed.

If the vessel does not steer straight, go to STEP 57A & 57B.

57A - Rotate Remote RUDDER DIAL until vessel steers straight. Loosen the knob screw on the remote (Fig 8 and Fig 9). Rotate the knob to "0" (zero). Tighten the knob screw.

57B - Go to STEP 60.

STEP 58 -

If this is an A SERIES PILOT (Non Orienting Compass), go to STEP 63.

If this is a B SERIES PILOT (Orienting Compass), go to SDEP 59.

STEP 59 - Test Remote RUDDER DIAL functions as described in STEP 39 & STEP 40.

STEP 60 - Test Remote COMPASS STEER and STANDBY - self orient functions as described in STEPS 49 through 52.

* PUSH BUTTON ORIENTING * (B SERIES ONLY)

8215 & 8215P REMOTE HANDLES 8405-C LEVER STEFRER

STEP 61 - Set the Remote SELECTOR SWITCH to: "COMPASS STEER".

STEP 62 - Depress the RIGHT push button for 2 seconds.

If the vessel changes course 14 to 16 degrees to the RIGHT, go to STEP 62 (depress LEFT button).
Go to STEP 63.

If vessel does not change course, go to Component Installation Instructions (Push Button Orienter connections).

* 8530 STEERING STATIONS * (flush mounted)

STANDBY - self orient: Same as above. COMPASS STEER: Same as above. RUDDER CENTERING:

Selector Switch on "RUDDER DIAL" -

Rudder centers.

Depressing RIGHT or LEFT push button will now produce 15 degrees to 20 degrees rudder in selected direction.

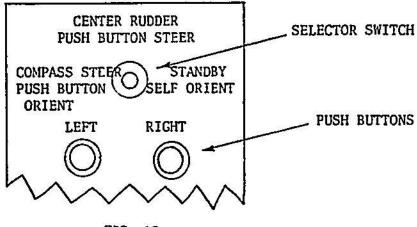


FIG. 12

STEP 63 - Fill out and MAIL the LIMITED WARRANTY CARD.

STFP 64 - Leave on board:

1 - Operator's manual.

1 - Complete Installation and Service manual.

1 - Compass cleaning kit and jumper plugs.

STEP 65 - Initial installation checkouts complete.

Complete operating instructions will be found in the:

* OPERATOR'S MANUAL *

* APPENDIX *

* 500 SERIES *

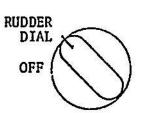
SENSITIVITY TEST FOR CONTROL CIRCUIT

- STEP 1 Unplug the 5 pin plug (ORIENTER) from the XL Power Supply.
- STEP 2 Unplug all cables from the back of the Control Console. EXCEPT the 12 pin cable to the XL Power Supply.
- STEP 3 Plug the RED 8-pin jumper plug and the GREEN 9-pin jumper plug into the Control Console.
- STEP 4 Rotate the DAMPER control to: Full counterclockwise.



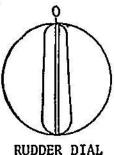
DAMPER

STEP 5 - Set the Control Console FUNCTION SWITCH to: "RUDDER DIAL".



FUNCTION SWITCH

STEP 6 - Set the RUDDER DIAL pointer to: "0" (zero).



STEP 7 - Slowly rotate the RUDDER DIAL pointer clockwise (RIGHT) until the Power Pack energizes.

Power Pack may pulse to the right, NOTE: full "on" should occur after 5 degrees.

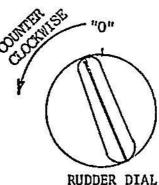
- If the Power Pack energizes within 1 to 2 degrees of pointer travel, go to STEP 8.
- If the Power Pack DOES NOT energize within 1 to 2 degrees of pointer travel, go to STEPS 7A through 7C.
 - 7A Recheck DAMPER for full counterclockwise rotation.
 - 7B Replace the 300 board in Control Console.
 - 7C Go to STEPS IN TROUBLE-SHOOTING * SERVICE III

* APPENDIX *

* 500 SERIES *

SENSITIVITY TEST FOR CONTROL CIRCUIT (cont'd)

STEP 8 - Slowly rotate the RUDDER DIAL pointer counterclockwise (LEFT) until the Power Pack energizes.



SECTION E

If the Power Pack energizes within 1 to 2 degrees of pointer travel, Basic Control Circuit is O.K.

NOTE: Power Pack may pulse to the LEFT, full "on" should occur after 5 degrees.

> If the Power pack DOES NOT energize within 1 to 2 degrees of pointer travel, go to STEP 7B and 7C.

Any problem with uncontrollable "hunting" could be due to one of the following:

- 1) Wet or grounded (+ or -) Encoder or Encoder cable.
- 2) Wet or grounded Compass cable, or Compass base.
- 3) Wet or grounded Remote Control or Junction box.

If the above are found to be in good condition, the problem is caused by the steering system.

Some additional telephone assistance may be obtained by calling the Factory.

8:30 A.M. to 5:00 P.M. Monday - Friday: Pacific Local time. (Please - No collect calls.)

> METAL MARINE PILOT, INC. 2119 MILDRED STREET WEST TACOMA, WASHINGTON 98466 TELEPHONE (206) 564-5902

WOOD FREEMAN® AUTOMATIC PILOTS

* 500 SERIES *

TROUBLE-SHOOTING * SERVICE II

TO USE:

The following steps are in numerical order. Proceed with each step in sequence, NOT JUMP STEPS unless instructed to do so. Faults and corrective measures will be indented from the margin and preceded by a number followed by a letter. i.e. 9A.

IN CASE OF DIFFICULTIES:

If you should encounter difficulties during the service procedure, Review and Recheck component installation. Repeat all previous checkout steps.

If difficulties persist, Go to STEPS IN TROUBLE-SHOOTING * SERVICE III.

Note:

SERVICE III is available from factory upon request.

You may also contact the factory for telephone assistance -Monday through Friday - between 8:30 AM and 5:00 PM. (Pacific local time). (206) 564-5902 - (Please - no collect calls)

Please have vessel name and serial number of pilot when contacting the factory for assistance.

NOTE:

The DOCKSIDE CHECKOUT and UNDERWAY CHECKOUT, Feb. 1979, should be used after completing the trouble-shooting guides.

TOOLS REQUIRED:

The following tools are required to do SERVICE II:

- 1 Small to medium size bit, flat blade, screw driver.
- 1 Set of Jumper Plugs 1, 8-pin & 1, 9-pin with pins 2 & 3 jumpered together (Supplied with the Autopilot).
- 1 Pair Snap Ring Pliers (#2) (Supplied with the Autopilot)
- 1 WOOD FREEMAND 500 SERIES Field Test Meter, (Optional Accessory) (See Appendix, page 11)

or

a volt/ohm meter with a 3 to 5 volt scale.

a 500-0-500 micro amp meter. (See Appendix, page 9, for alternate meter connections.)

> METAL MARINE PILOT, INC. 2119 MILDRED STREET WEST TACOMA, WASHINGTON 98466 (206) 564-5902

GENERAL INSPECTION OF INSTALLATION

Before trouble-shooting the pilot, it is important to inspect the physical installation of the components. ALL COMPONENTS MUST BE INSTALLED ACCORDING TO FACTORY RECOMMENDATIONS. Any deviation from recommended procedures should be noted and corrected. Special attention should be given to the following:

Non-waterproof components mounted in exposed locations.

Cut, spliced, or otherwise modified cables, including plug ends that have been removed and replaced.

Hydraulic POWER PACKS connected directly with copper tubing or pipe, or without shut off valves.

Mechanical POWER PACKS mounted other than horizontally having the Gear Case higher than the motor.

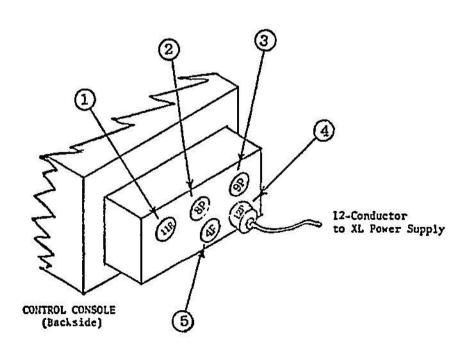
Long power leads from the battery to the XL POWER SUPPLY.

XL POWER SUPPLY mounted with labels other than 'UP'.

CONTROL COMPASS mounted within three (3) feet of anything magnetic or that will deflect a compass card.

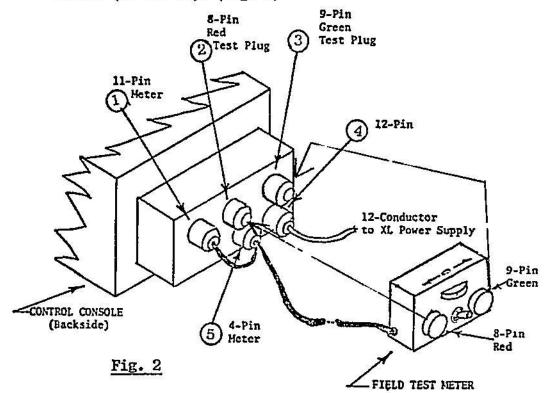
* INITIAL SET UP FOR ALL TESTING *

STEP 1 - Unplug all cables from back of the CONTROL CONSOLE, leaving only the 12 conductor cable in place (socket #4). (Fig. 1)



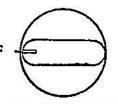
SECTION G

STEP 3 - Plug the FIELD TEST METER (or connect equivalent meter) into the 4-pin RUDDER ANGLE INDICATOR socket and the 11-pin REMOTE CONTROL socket (#1 and #5). (Fig. 2)



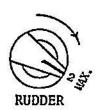
CAUTION .. The FIELD TEST METER is sensitive to magnetic fields <u>DO NOT</u> place the meter near magnets or magnetized tools when using the meter.

STEP 4 - Set the FUNCTION SWITCH to: "OFF". OFF



FUNCTION SWITCH

STEP 5 - Set the RUDDER knob to: "2 KNOTS" - Full Clockwise.



STEP 6 - Set all other knobs on the CONTROL CONSOLE: straight up.

* XL POWER SUPPLY TESTS *

STEP 7 - Unplug the 4-pin POWER PACK plug from the XL POWER SUPPLY. Unplug the 5-pin "ORIENTER" plug from the XL POWER SUPPLY.

> (Front Plate) XL POWER SUPPLY

> > POWER PACK 4-pin-

> > ORIENTER 5-pin

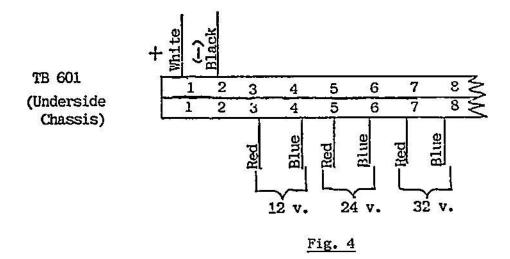
STEP 8 - Remove the four outermost screws on the XL POWFR SUPPLY front plate and remove XL POWER SUPPLY from chassis box. Turn the unit upside down. Locate TB 601 (a 12 position terminal strip). (Fig. 4)

STEP 9 - INPUT VOLTAGES

If the RED and BLUE voltage taps are on the correct terminals to match the ship's supply voltage (12,24 or 32 VDC), go to STEP 10.

If the voltage taps are not on the correct terminals, move the taps to correct terminals as shown in table below.

	TB 601 TERMINAL #	
SHIP'S		
VOLTAGE	RED	BLUE
12	3	4
24	5	6
32	7	8



>>> Tighten all unused screws on terminal strip <<<

STEP 10 - Return the unit to the RIGHT SIDE UP position and reconnect cables.

STEP 11 - Set the FUNCTION SWITCH to: "RUDDER DIAL".



FUNCTION SWITCH

If a click and a low 1200 to 1300 cycle tone are heard in the XL POWER SUPPLY, go to STEP 12.

If no click or tone is heard in the XL POWER SUPPLY, go to STEPS 11A - 11C.

- 11A Check the power cable from the XL POWER SUPPLY to the Ship's D.C. supply for splices and wire size (see manual).
- 11B Check the polarity of the XL Power Cable connection. (white is positive and connects to pin 1 of TB601).

11C - Replace the fuses on the XL POWER SUPPLY front panel.

(4 amp (4AGC) - 20 amp (20MDL)) go to STEP 11.

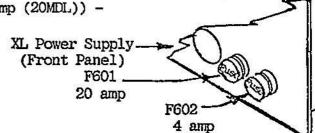


Fig. 5

PAGE 5

STEP 12 - Unplug the three (3) 6419 RELAYS from the XL POWER SUPPLY.

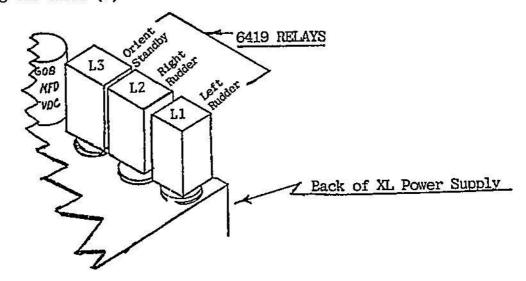
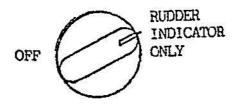


Fig. 6

STEP 13 - Set the FUNCTION SWITCH to: "RUDDER INDICATOR ONLY".



FUNCTION SWITCH

STEP 14 - Plug the 4-pin POWER PACK plug into the XL POWER SUPPLY. (See Fig. 3, Page 4)

> If the POWER PACK does not energize, go to STEP 15.

If the POWER PACK energizes to the RIGHT or LEFT, go to STEPS 14A and 14B.

14A - Locate the two mercury contactors (black tubes) mounted to the inside of the front panel plate.

14B - Remove the green wire from contactor L5. (Fig. 7)

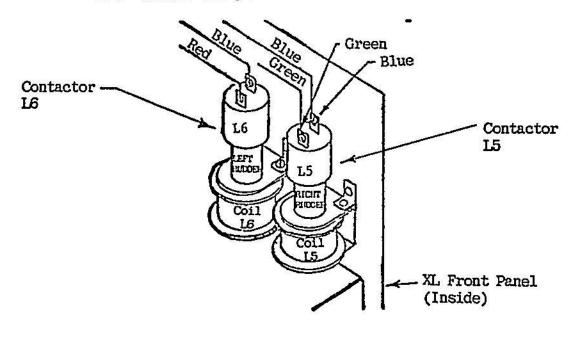


Fig. 7

If the POWER PACK stops running, go to STEPS 14C and 14D.

14C - Replace mercury contactor L5.

14D - Go to STEP 14.

If the POWER PACK continues to run, go to STEPS 14E and 14F.

14E - Replace mercury contactor L6. 14F - Go to STEP 14.

NOTE: IN AN EMERGENCY, INTERCHANGE THE DEFECTIVE CONTACTOR WITH THE MASTER RELAY CONTACTOR. (SEE APPENDIX FOR LOCATION)

STFP 15 - Plug all 6419 relays into their sockets. (Fig. 6)

> If POWER PACK does not energize, go to STEP 16.

If POWER PACK energizes to the LEFT, go to STEP 15A.

15A - Interchange relays L1 and L3.

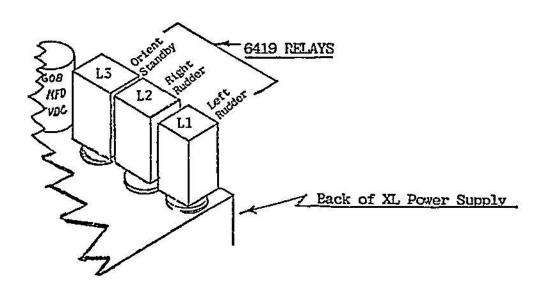
If the POWER PACK continues to run, go to STEP 15B.

If the POWER PACK stops running, replace the 6419 relay now in the L3 position. Go to STEP 15.

15B - Interchange relays L2 and L3.

If the POWER PACK stops running, replace the 6419 relay now in the L3 position. Go to STFP 15.

If the POWTR PACK continues to run, replace the 6419 relays in both the L2 and L3 position.



STEP 16 - Jumper across the GREEN and BLUE wires on top of mercury contactor L5. (Fig. 7, Page 6)

> If the POWER PACK energizes to the RIGHT, go to STEP 17.

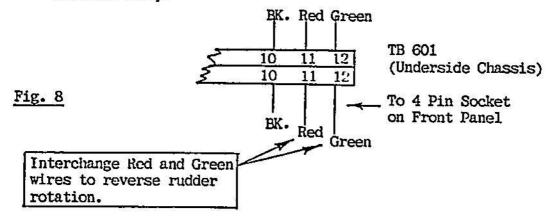
If the POWER PACK energizes to the LEFT, go to STEPS 16A - 16D.

16A - Unplug the 4-pin POWER PACK plug from the XL POWER SUPPLY (Fig. 3, Page 4)

16B - Turn the XL POWER SUPPLY upside down.

16C - Interchange the RED and GREEN wires (#11 & #12) on TB 601, the 12 position terminal strip. (Fig. 8)

NOTE: Interchange only the leads on the 4-pin socket side of the terminal strip.



16D - Turn unit right side up - plug in 4-pin POWER PACK plug, go to STEP 16.

If POWER PACK does not energize, go to STEPS 16E - 16G.

16E - Check the motor leads and brushes.

16F - If a solenoid valve is used, check for a stuck or defective solenoid.

16G - Recheck line voltage connections go to STEP 16.

STEP 17 - Jumper RED and BLUE wires on mercury contactor L6. (Fig. 7, Page 6)

If the POWER PACK energizes to the LEFT, unplug 4-pin POWER PACK plug. go to STEP 18.

If the POWER PACK does not energize, go to STEPS 17A - 17C.

17A - Check the motor leads and brushes.

17B - If a solenoid valve is used, check for a stuck or defective solenoid.

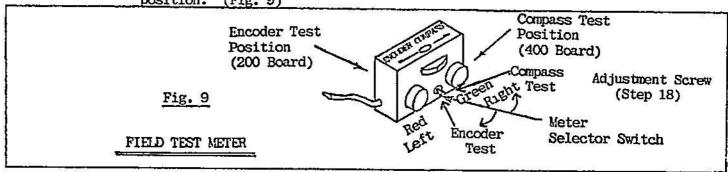
17C - Recheck line voltage connections. Go to STEP 17.

* CONTROL CONSOLE TESTS *

CAUTION .. The FIELD TEST METER is sensitive to magnetic fields DO NOT place the meter near magnets or magnetized tools when using the meter.

STEP 18 - Place the FTM Meter selector switch in the middle position.
Using a coin, (not a steel screw driver) adjust the meter for "ZERO".

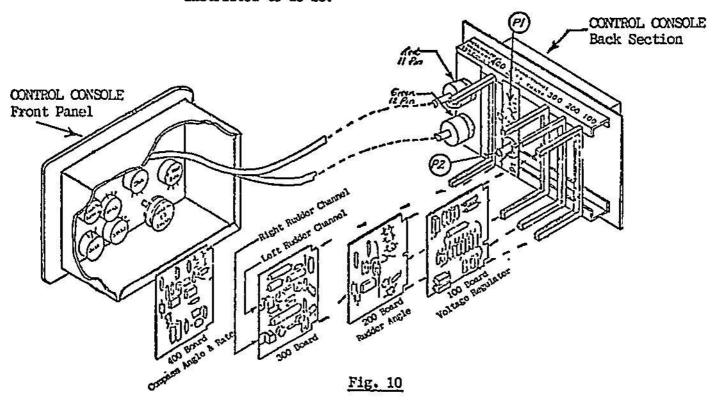
STEP 19 - Place the METER SELECTOR SWITCH to the "left" or ENCODER TEST position. (Fig. 9)



STEP 20 - Remove the 4 outermost screws on the back of the CONTROL CONSOLE.

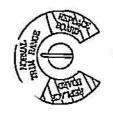
Slide the back section of the unit from the front panel. (Fig. 10)

NOTE: Boards are shown removed for clarity. Do not remove unless instructed to do so.



* 200 BOARD *

STEP 21 - Rotate the ENCODER TRIMMER adjustment, P2, clockwise and counterclockwise for the full travel of the adjustment. (Fig. 11). This test can also be done with RUDDER ANGLE INDICATOR only if installed.



PI 400 BOARD TRUMER

Fig. 11



P2 200 BOARD TRUKSER

If the Meter needle swings smoothly to full scale deflection in both directions, go to STEP 22.

If the Meter needle does not move, replace the 200 board. (Fig. 10, Page 9) Go to STEP 21.

If the Meter needle does not swing smoothly to full deflection on both sides of ZERO or is erratic, replace the 200 board.

Go to STEP 21.

If replacing the 200 board does not correct fault, refer to IN CASE OF DIFFICULTIES, Page 1.

STEP 22 - Rotate ENCODER TRIMMER adjustment, P2, as required to ZERO the Meter needle. (Fig. 11)

If the Trimmer adjustment is within the middle 50% of travel marked on the plate as 'NORMAL TRIM RANGE' (for units without the labeled plate refer to the appendix.), go to STEP 23.

If the Meter needle will not ZERO, replace the 200 board. (Fig. 10, Page 9) Go to STEP 21.

If the Meter needle zeros but, the Trimmer adjustment is cutside of 'NORMAL TRIM RANGE', replace the 200 board.

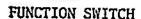
Go to STEP 21.

If replacing the 200 board does not correct fault, refer to IN CASE OF DIFFICULTIES, Page 1.

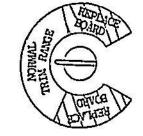
* 400 BOARD *

STEP 23 - Place the FIELD TEST METER selector switch to the "right" side - COMPASS TEST position. (Fig. 9. Page 9)
Set FUNCTION SWITCH to:
"REMOTE".

OFF



STEP 24 - Rotate the COMPASS TRIMMER adjustment, P1, clockwise and counterclockwise slowly, for the full travel of the adjustment. (Fig. 12)

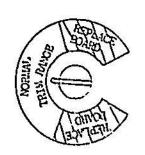


P1 400 BOARD TRIBUER

Fig. 12

If the Meter needle swings smoothly to full scale deflection, go to STEP 25.

If the Meter needle does not move, replace the 400 board. (Fig. 10, Page 9) Go to STEP 24.



P2 200 BOARD TRIMEN

If the Meter needle does not swing to full deflection on both sides of ZERO or is erratic, replace the 400 board.

Go to STEP 24.

STEP 25 - Rotate Trimmer adjustment, P1, as required to ZERO the Meter needle. (Fig. 12)

If the Trimmer adjustment falls within the middle 50% of travel marked on the plate as 'NORMAL TRIM RANGE' (for units without the labeled plate refer to the appendix.), go to STEP 26.

If the Meter needle will not ZERO, replace the 400 board. (Fig. 10) Go to STEP 24.

If the Meter needle zeros, but the Trimmer adjustment is outside of the 'NORMAL TRIM RANGE', replace the 400 board.

Go to STEP 24.

If replacing the 400 board does not correct fault, refer to IN CASE OF DIFFICULTIES, Page 1.

STEP 26 - Rotate COMPASS TRIM knob (Control Console Front Plate) to: full counterclockwise.



COMPASS TRIM

STEP 27 - Set the COUNTER RUDDER knob to: "AVERAGE" - straight up.



COUNTER RUDDER

STEP 28 - Rotate the COMPASS TRIM knob <u>quickly</u> back to the center while watching the FIELD TEST METER.



COMPASS TRIM

9-Pin Green 8-Pin Red

If the Meter needle swings past zero and then returns SLOWLY to zero, go to STEP 29.

If the Meter needle does not swing past zero, but stops on zero - go to STEPS 28A and 28B.

AVERAGE

28A - Check to see that COUNTER RUDDER knob is: "AVERAGE" - straight up.

28B - Replace 400 board - go to STEP 24.

COUNTER RUDDER

STEP 29 - Re-zero the Meter needle by rotating the COMPASS TRIM knob.

COMPASS TRIM

* COMPASS TESTS *

STEP 30 - Unplug 9-pin GREEN test plug. (Fig. 2, Page 3)

Set RUDDER knob to:
"2 KNOTS" - full clockwise.
Remove COMPASS from mounting bracket
by squeezing the flexible gimbal ring.
(Do not remove the gimbal screws.)
Plug 9-pin cable directly into
socket #3 on CONTROL CONSOLE back. (Fig. 2)



STEP 31 - Rotate COMPASS DIAL SLOWLY through 360 degrees. (Fig. 13)

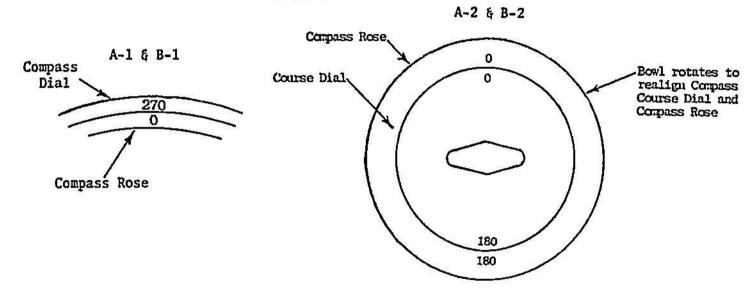


Fig. 13

If Meter needle swings SMOOTHLY both left and right, go to STEP 32.

If Meter needle does not swing smoothly, clean slip rings - (See Appendix).
Go to STEP 31.

If Meter needle does not swing, go to STEPS 31A and 31B.

31A - Clean slip rings.31B - Replace Compass crystal (See appendix) then go to STEP 31.

STEP 32 - Align COMPASS COURSE DIAL so that it matches COMPASS ROSE. Slowly rotate COMPASS COURSE DIAL until Meter needle zeros. (Fig. 13, Page 13)

If COMPASS COURSE DIAL and COMPASS ROSE match within 10 degrees, go to STEP 33.

If COMPASS COURSE DIAL and COMPASS ROSE differ by more than 10 degrees, replace COMPASS crystal. Go to STEP 31.

STEP 33 - Align COMPASS COURSE DIAL and COMPASS ROSE. (Fig. 13, Page 13)

Rotate COMPASS Trimmer, P1, until Meter needle zeros.





P2 200 BOARD TRUISER

Rotate COMPASS DIAL 45 degrees clockwise. (Fig. 13, Page 13)

If Meter needle swings 30 degrees or more left, repeat STEP 33 counterclockwise.

Results should be 30 degrees or more right - go to STEP 34.

If Meter needle does not swing 30 degrees either left or right, go to STEPS 33A and 33B.

33A - Clean slip rings. (See appendix)
 33B - Replace Compass crystal - (See appendix)
 go to STEP 33.

STEP 34 - Unplug COMPASS from back of CONSOLE and plug it into the Compass extension cable. Plug extension cable into CONSOLE.

(On "B" models with motor driven orienting base, do not plug into the yoke yet - only into the extension cord.)
Align the inner and outer compass dials. (Fig. 13, Page 13)

If Meter needle reads zero, go to STEP 35.

If Meter needle does not read zero, replace extension cable.
Go to STEP 34.

STEP 35 - Rotate COMPASS COURSE DIAL 45 degrees right and 45 degrees left from where dials match. (Fig. 13)

If Meter needle swings 30 degrees or more left, repeat STEP 35 counterclockwise.

Results should be 30 degrees or more right - go to STEP 36.

If Meter needle does not swing 30 degrees either left or right, replace extension cable.

Go to STEP 35.

STEP 36 - On "B" models, plug the COMPASS into the COMPASS YOKE and plug the COMPASS BASE into the extension cable.

Align the COMPASS COURSE DIAL with COMPASS ROSE. (Fig. 13)

If Test Meter needle reads zero, go to STEP 37.

If Meter needle does not read zero, go to STEPS 36A and 36B.

36A - Clean Compass Yoke slip rings. (See Appendix)
36B - Replace COMPASS YOKE then go to STEP 36.

STEP 37 - Rotate COMPASS COURSE DIAL 45 degrees right and 45 degrees left from where COMPASS COURSE DIAL and COMPASS ROSE match. (Fig. 13, Page 13)

If Meter needle swings 30 degrees or more left, repeat STEP 37 counterclockwise.

Results should be 30 degrees or more right - go to STEP 38.

If Meter needle does not swing 30 degrees either left or right, go to STEPS 37A and 37B.

37A - Clean Compass Yoke slip rings. (See appendix)
37B - Replace COMPASS YOKE go to STEP 37.

* ENCODER TESTS *

STEP 38 - Disconnect one end of connecting linkage.
Rotate ENCODER ARM through 180 degrees.

←Connecting Linkage

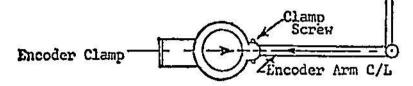


Fig. 14

If ENCODER ARM and shaft move freely, go to STEP 39.

If arm does not move freely, replace ENCODER.

Go to STEP 38.

STEP 39 - Remove ENCODER from stern.

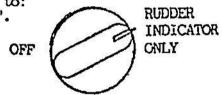
Unplug 8-pin RED test plug from CONTROL CONSOLE.

Set the Field Test Meter switch to the left side.

Set the FUNCTION SWITCH to:

"RUDDER INDICATOR ONLY".

RUDDER



FUNCTION SWITCH

Plug ENCODER into CONTROL CONSOLE - top center socket. Align arrows on the encoder cap and arm so they are pointing at each other. (Fig. 14)

If Meter needle reads within 15 degrees of zero, go to STEP 40.

If Meter needle does not read within 15 degrees of zero, replace encoder.
Go to STEP 39.

STEP 40 - Swing ENCODER ARM approximately 30 degrees left and right. (Fig. 14)

If Meter needle swings 30 degrees or more both left and right, go to STEP 41.

If Meter needle does not swing, replace ENCODER.
Go to STEP 40.

PAGE 17

If the readings on the Meter needle are the same as when the ENCODER was plugged directly into the console, go to STEP 42.

Encoder Arm C/L

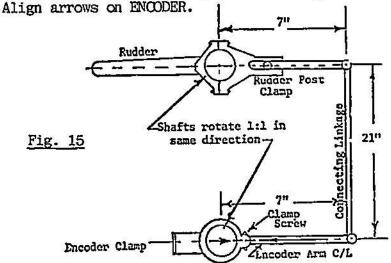
If Meter needle reading is not the same,

41A - Dry Encoder plug and extension socket with an air dryer.

41B - Replace Encoder extension cable.

NOTE: WHENEVER REPLACING ENCODER OR CABLE, BE SURE PLUG AND SOCKET CONNECTION IS DRY AND REPACKED WITH SILICONE GREASE.

STEP 42 - Install ENCODER. Arrows should be approximately lined up when rudder is at center position. Refer also to appendix for Installation Drawings.



If Meter needle readings are still the same, go to STEP 43.

If Meter needle reading is different, ENCODER must be electrically isolated from ship's structure.

FUNCTION TESTS

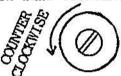
STEP 43 - Plug POWER PACK into XL POWER SUPPLY.

Set RUDDER DIAL knob to:

STRAIGHT UP - "0"

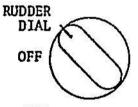
RUDDER DIAL

STEP 44 - Remove the black cover plug from the DAMPER.
Rotate the Damper control full COUNTERCLOCKWISE.



DAMPER

STEP 45 - Set FUNCTION SWITCH on CONTROL CONSOLE to: "RUDDER DIAL".



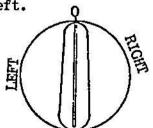
FUNCTION SWITCH

If POWER PACK energizes to left or right and continues to run hardover in one direction, replace 300 board.

Go to step 45

>> If replacing the 300 board does not correct the fault,
 replace 12 conductor cable to XL POWER SUPPLY.
 If replacing the 12 conductor cable does not correct the fault
 refer to IN CASE OF DIFFICULTIES, Page 1.

STEP 46 - Rotate RUDDER DIAL hard left.



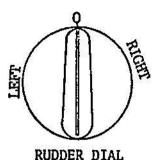
If rudder moves to the left, RUDDER DIAL go to Step 47.

If rudder will not move to the left, replace 300 board.
Go to step 44

STEP 47 - Rotate RUDDER DIAL hard right.

If rudder moves to the right, go to step 48.

If rudder will not move to the right, replace 300 board.
Go to step 44.

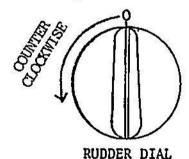


>> If replacing the 300 board does not correct the fault, replace 12 conductor cable to XL POWER SUPPLY.

If replacing the 12 conductor cable does not correct the fault, refer to IN CASE OF DIFFICULTIES, Page 1.

SENSITIVITY TEST FOR CONTROL CIRCUIT

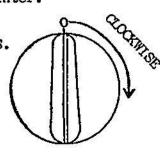
- STEP 48 Unplug 9-pin Compass cable and 8-pin Encoder cable from the back of the CONTROL CONSOLE. (Fig. 1, Page 2)
- STEP 49 Plug the RED 8-pin jumper plug and the GREEN 9-pin jumper plug into the CONTROL CONSOLE. (Fig. 2, Page 3)
- STEP 50 Set the RUDDER DIAL pointer to:
 full counterclockwise hardover left.
 (the POWER PACK will energize to the left)



STEP 51 - Slowly rotate RUDDER DIAL pointer clockwise (right) until the POWER PACK reverses direction and runs to the right.

Note the position of the RUDDER DIAL pointer.

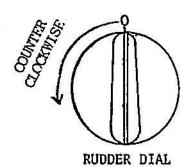
NOTE: POWER PACK MAY PULSE TO THE RIGHT, FULL "ON" SHOULD OCCUR AFTER 5 DEGREES.



RUDDER DIAL

STEP 52 - Rotate the RUDDER DIAL pointer counterclockwise (left) until the POWER PACK reverses direction and runs to the left.

NOTE: POWER PACK may pulse to the left, full "ON" should occur after 5 degrees.



If the pointer is less than 3 degrees from the position noted in STEP 51, go to STEP 53.

If the pointer is greater than 3 degrees from the position noted in STEP 51, go to STEPS 52A through 52E.

52A - Recheck DAMPER for full counterclockwise rotation - go to STEP 50.

52B - Replace the 300 board in CONTROL CONSOLE - go to STEP 50.

52C - Replace the 12 conductor cable XL POWER SUPPLY to CONTROL CONSOLE - go to STEP 50.

52D - Replace CONTROL CONSOLE BACK section & boards - go to STEP 50.

52E - Refer to IN CASE OF DIFFICULTIES, Page 1.

STEP 53 - Slowly rotate the RUDDER DIAL pointer clockwise (RIGHT) until the POWER PACK energizes.

RUDDER DIAL

NOTE: POWER PACK MAY PULSE TO THE RIGHT, FULL "ON" SHOULD OCCUR AFTER 5 DEGREES.

If the POWER PACK energizes within 1 to 2 degrees of pointer travel, go to STEP 54.

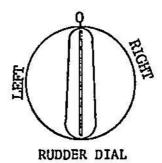
If the POWER PACK <u>DOES NOT</u> energize within 1 to 2 degrees of pointer travel, go to STEPS 52A through 52E.

STEP 54 - If the current position of RUDDER DIAL pointer is within a pointer's width of "O", go to STEP 55.

If the current position of RUDDER DIAL pointer is more than a pointer's width of "O", go to steps 54A and 54B.

54A - Rotate RUDDER DIAL to point where POWER PACK reverses direction. 54B - Loosen RUDDER DIAL pointer, move pointer to indicate "O" and tighten knob.

Slowly rotate the RUDDER DIAL pointer counterclockwise (LEFT) until the POWER PACK energizes.



If the POWER PACK energizes within 1 to 2 degrees of pointer travel, BASIC CONTROL CIRCUIT is O.K. Go to STEP 55.

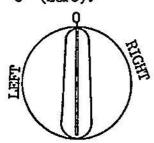
NOTE: POWER PACK MAY PULSE TO THE LEFT, FULL "ON" SHOULD OCCUR AFTER 5 DEGREES.

If the POWER PACK DOES NOT energize within 1 to 2 degrees of pointer travel, go to STEP 52A - 52E.

* DAMPER & NULL ADJUSTMENTS *

STEP 55 - Remove 8-pin jumper and insert 8-pin Encoder Cable.

STEP 56 - Set RUDDER DIAL pointer to: "0" (zero).



RUDDER DIAL

Set NULL knob to: "AVERAGE" straight up.



NULL

STEP 57 - Remove the black cover plug from the DAMPER.

Rotate the Damper control full COUNTERCLOCKWISE.

Slowly rotate the Damper control clockwise until the continual oscillation of the rudder, ("hunting"), stops.



DAMPER

If the "hunting" of the rudder stops before the DAMPER is full clockwise - go to STEP 58.

If the DAMPER is rotated fully clockwise and the rudder "hunting" does not stop -- go to STEPS 57A through 57C.

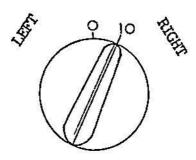
57A - Check steering system for 'mechanical slack" and correct as required to eliminate slack - go to STEP 57.

57B - On hydraulic steering, bleed steering system, (refer to steering system TROUBLE-SHOOTING GUIDE) - go to STEP 57

57C - Rotate NULL knob to the 9 o'clock, "BROAD" position - go to STEP 57.

NOTE: If "hunting" persists,
review the installation.
Check for any connecting cables that may be CUT, SPLICED, BROKEN,
OR OTHERWISE MODIFIED. Check also for charring of the boards
or resistors.
If there are no apparent modifications,
refer to IN CASE OF DIFFICULTIES, Page 1.

STEP 58 - Rotate the RUDDER DIAL pointer (knob) in 10 separate increments to 10 degrees RIGHT. (1 increment is approximately the width of the white line on the pointer knob.)



RUDDER DIAL

If the rudder responds to each increment of RUDDER DIAL pointer motion with equal travel and comes to rest at 10 degrees right, go to STEP 59.

If the RUDDER DIAL pointer must be rotated several increments before the rudder will respond, go to STEP 57.

NOTE: If STEPS 50 - 54 are o.k. and there is a sensitivity problem, refer to IN CASE OF DIFFICULTIES, Page 1.

* COMPASS CHECKOUT * (ALL MODELS)

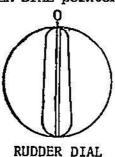
STEP 59 - Remove 9-pin jumper and insert 9-pin Compass cable. Set TRIM knob "COMPASS COURSE" to: straight up.

COMPASS TRIM

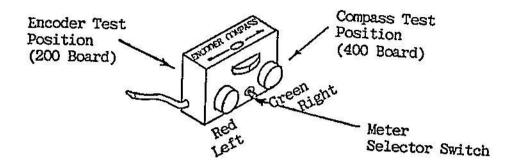
STEP 60 - Set RUDDER knob to: straight up - "AVERAGE".

AVERAGE

STEP 61 - Set RUDDER DIAL pointer to: "0".

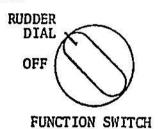


Set FIELD TEST METER selector switch to: left, or red side.



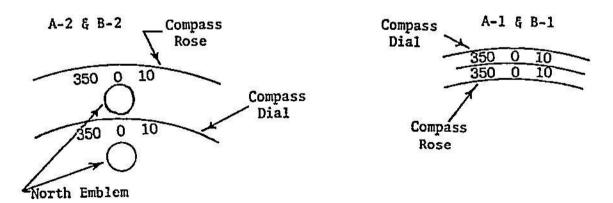
FIELD TEST METER

Set FUNCTION SWITCH to: RUDDER DIAL

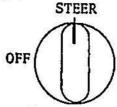


STEP 62 - Rotate the COMPASS COURSE DIAL (on the top of the compass unit) 5 complete turns to be sure of good slip ring contact. (On "B" units also rotate the YOKE 5 turns).

STEP 63 - Rotate the COMPASS COURSE DIAL so the COURSE DIAL numbers match with the COMPASS ROSE. "0" aligned with "0".



STEP 64 - Set the FUNCTION SWITCH to: "COMPASS STEFR". COMPASS



FUNCTION SWITCH

If the RUDDER ANGLE INDICATOR remains centered, go to STEP 65.

If the RAI needle does not center (or rudder does not center), go to STEPS 64A & 64B.

64A - Reset the TRIM knob "COMPASS COURSE" to: "straight up" -



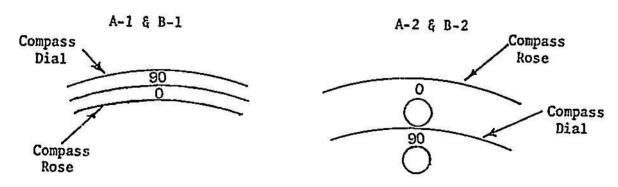
COMPASS TRIM

go to STEP 64.

64B - Refer to IN CASE OF DIFFICULTIES, Page 1.

STEP 65 - Rotate RUDDER knob to: "15 knots" - straight up.

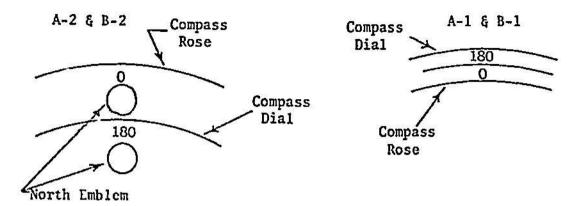
Rotate COMPASS COURSE DIAL disk 90 degrees counterclockwise.



If rudder moves RIGHT 15 to 20 degrees, go to STEP 66.

If rudder moves LEFT or rudder does not move, refer to IN CASE OF DIFFICULTIES, Page 1.

STEP 66 - Rotate COMPASS COURSE DIAL disk 180 degrees. (90 degrees from original matching position)



If rudder moves LEFT 15 to 20 degrees, go to STEP 67.

If rudder does not move LEFT, refer to IN CASE OF DIFFICULTIES, Page 1.

STEP 67 - Set the RUDDER knob to:
"2 KNOTS" - full clockwise.



If the rudder moves further LEFT approximately 30 to 45 degrees, go to STEP 68.

If rudder travel is not increased, refer to IN CASE OF DIFFICULTIES, Page 1.

STEP 68 - If you have an "A" series pilot - (Compass not self-orienting), go to DOCKSIDE AND UNDERWAY CHECKOUT IN INSTALLATION MANUAL. (Feb. 1979)

If you have a "B" series pilot - (Compass self-orienting), go to STEP 69.

* STANDBY-Self Orient CHECKOUT * (BI & B2 SERIES ONLY)

STEP 69 - Remove the 8-pin Encoder plug and cable from the rear of the CONTROL CONSOLE, (top center position).

Insert the 8-pin RED coded jumper plug.

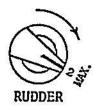
Plug the 5-pin Gear Motor plug into the XL POWER SUPPLY.

STEP 70 - Set the TRIM knob "COMPASS COURSE" to: straight up.



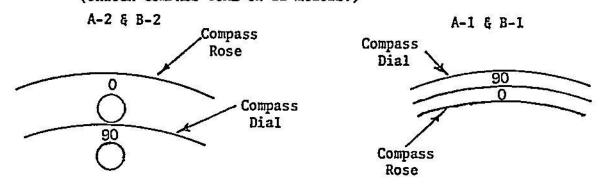
COMPASS TRIM

STEP 71 - Set the RUDDER knob to:
"2 KNOTS" - full clockwise.

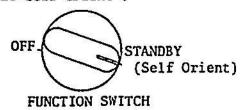


STEP 72 - Rotate COMPASS COURSE DIAL so the numbers on the COMPASS COURSE DIAL and the COMPASS ROSE differ 90 degrees.

(Unlock COMPASS YOKE on B2 models.)



STEP 73 - Set FUNCTION SWITCH to: "STANDBY-self orient".



If the GEAR MOTOR rotates the Compass bowl so the COMPASS COURSE DIAL and the COMPASS ROSE match * (some "hunting", up to 1 to 2 degrees may be present), go to STEP 74.

If orienting occurs but COMPASS COURSE DIAL and COMPASS ROSE do not match *, refer to IN CASE OF DIFFICULTIES, Page 1.

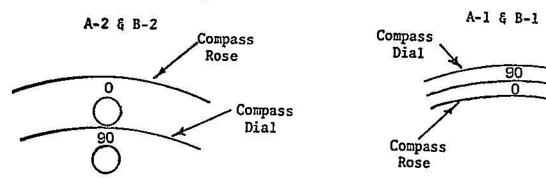
If GEAR MOTOR does not run, go to STEPS 73A through 73D.

- 73A Inspect Compass base and yoke for compass wire stuck in gears. SEE NOTE.
- 73B Inspect flex shaft for tight bends or kinks correct as necessary go to STEP 73.
- 73C Inspect Gear Motor pinion gear and drive gear for binding correct as necessary go to STEP 73.
- 73D Go to Gear Motor Installation Instructions.

NOTE: IF COMPASS CABLE INSULATION HAS BEEN BROKEN, CONTACT FACTORY FOR A REPLACEMENT COMPASS, or send COMPASS, doubly packed, to the factory for repair.

* - On B1 models + or (-) 3 degrees. On B2 models + or (-) 2 degrees.

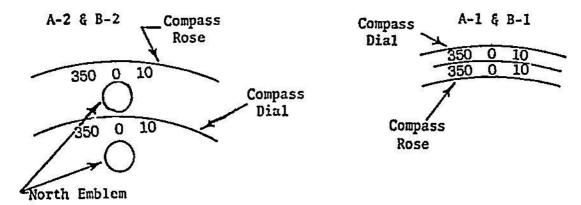
STEP 74 - Rotate COMPASS COURSE DIAL clockwise 90 degrees and release.



If the Compass bowl rotates back to matching position within 15 seconds, Repeat STEP 74 4 to 5 times. Go to STEP 75.

If the response time to realign the COMPASS COURSE DIAL & COMPASS ROSE is longer than 15 seconds, go to STEPS 73A through 73D.

STEP 75 - Repeat STEP 74 rotating COMPASS COURSE DIAL counterclockwise.



STEP 76 - Remove 8-pin jumper plug from back of the CONTROL CONSOLE.

Plug in the 8-pin Encoder plug and cable.

(top center socket)

Go to DOCKSIDE AND UNDERWAY CHECKOUT IN INSTALLATION MANUAL.

(Feb. 1979)

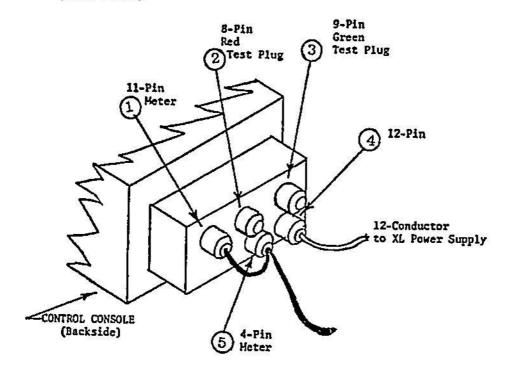


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ALTERNATE ENCODER INSTALLATIONS

In some instances it will be necessary to mount the ENCODER in a "NON-STANDARD" configuration.

Standard configuration:

APPENDIX

Both ENCODER ARM & RUDDER POST CLAMP face same direction. ENCODER is mounted with arrow on top.

** Arrow on cap points at arrow on ENCODER ARM.

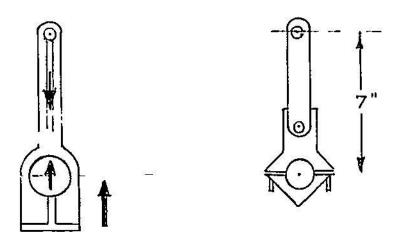


FIG. 1

Some alternate configurations are shown below:

1. ENCODER INVERTED:

Both ENCODER ARM & RUDDER POST CLAMP face same direction. ENCODER is mounted with arrow on bottom.

** Arrow on cap points away from arrow on ENCODER ARM.

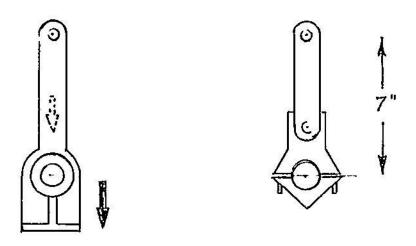


FIG. 2

2. OPPOSING ARMS:

ENCODER ARM mounted forward and RUDDER POST CLAMP ARM mounted aft (or any other opposing configuration). ENCODER is mounted with arrow on top.

** Arrow on cap points away from arrow on ENCODER ARM.

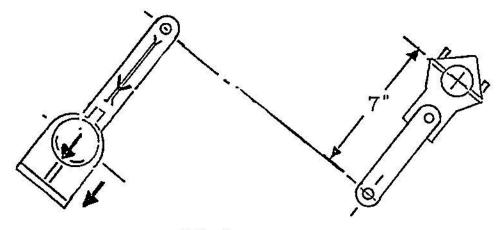


FIG. 3

3. INVERTED ENCODER & OPPOSING ARMS

ENCODER ARM mounted forward and RUDDER POST CLAMP ARM mounted aft (or any other opposing configuration).
ENCODER is mounted with arrow on bottom.

** Arrow on cap points at arrow on ENCODER ARM.

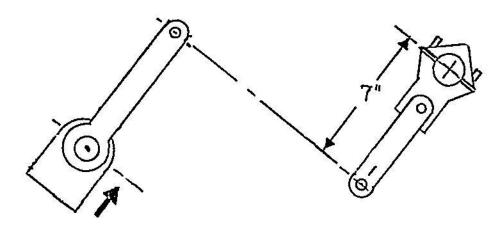
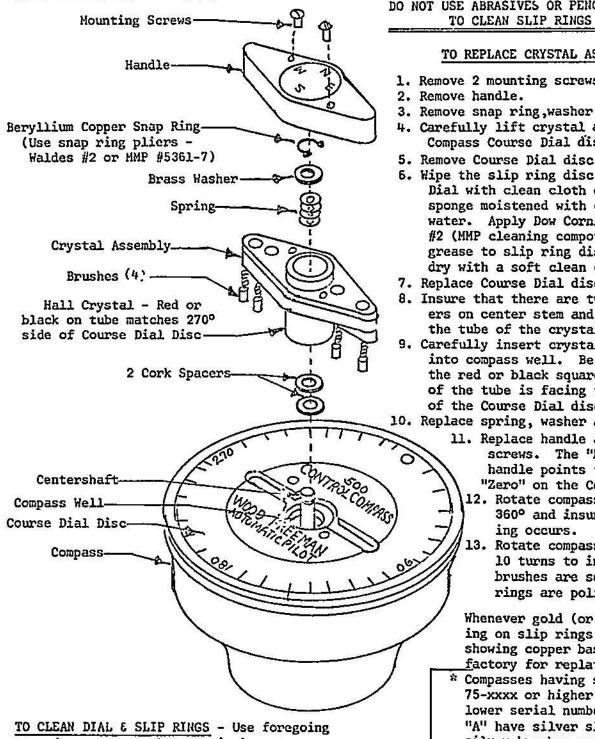


FIG. 4

IN ALL CONFIGURATIONS IT IS IMPORTANT THAT OPPOSITE SIDES OF THE "BOX" BE OF EQUAL LENGTH.

THE STANDARD MOUNTING ARM ON THE ENCODER IS 7 INCHES.

THE LENGTH OF THE RUDDER POST CLAMP ARM MUST BE 7 INCHES FROM THE CENTER OF THE RUDDER POST TO THE CENTER OF THE HOLE IN THE ARM.



procedure, except that original parts are retained at reassembly.

SELF CLEANING SLIP RINGS

- 1. When Pilot has not been used for several days, rotate compass dial through 3 or 4 turns to polish slip rings, before setting course.
- 2. In daily operation, action of slip ring brushes during course dialing will keep slip rings polished.

DO NOT USE ABRASIVES OR PENCIL ERASERS

TO REPLACE CRYSTAL ASSEMBLY

- 1. Remove 2 mounting screws from handle.
- Remove snap ring, washer and spring.
- 4. Carefully lift crystal assembly from Compass Course Dial disc.
- 5. Remove Course Dial disc from Compass.
- 6. Wipe the slip ring disc and Course Dial with clean cloth or cellulose sponge moistened with clean, fresh water. Apply Dow Corning #19 or #2 (MMP cleaning compound) silicone grease to slip ring disc and polish dry with a soft clean cloth.
- 7. Replace Course Dial disc.
- 8. Insure that there are two cork spacers on center stem and none inside the tube of the crystal assembly.
- 9. Carefully insert crystal assembly into compass well. Be sure that the red or black square on the side of the tube is facing the 270° side of the Course Dial disc.
- 10. Replace spring, washer and snap ring.
 - 11. Replace handle and 2 mounting screws. The "N" on the handle points toward the "Zero" on the Course Dial disc.
 - 12. Rotate compass dial through 360° and insure that no binding occurs.
 - 13. Rotate compass dial about 10 turns to insure that brushes are seated and slip rings are polished.

Whenever gold (or silver*) plating on slip rings has worn thru showing copper base, return to factory for replate.

* Compasses having serial numbers 75-xxxx or higher or having lower serial number followed by "A" have silver slip rings AND silver brushes and rarely need cleaning or replating.

KEEP CLEAR VINYL COVER ON COMPASS AT ALL TIMES FOR LONGER INTERVALS BETWEEN CLEANING.

METAL MARINE PILOT, INC. 2129 West Made of Server Taccome, West, 25446	WOOD FREEMAN AUTOMATIC PILOT
DRINE MVVF CX 4	PROCEDURE
PREVIOUS	TOTAL SOO SERIES COMPASS CRYSTAL
ARREMALT MAG RECORD	NO.

Place Compass in Yoke

Bracket on Yoke

Yellow Clip "A" in this position when placing Compass in Gimbal Ring Cord on side of Yoke opposite to 9-pin socket

Bring cord in front of yoke and keep cord parallel to Yoke when securing it in Clip "B" and "C"

Leave sufficient loop_ to allow compass to self level.

Nylon Clip "B"

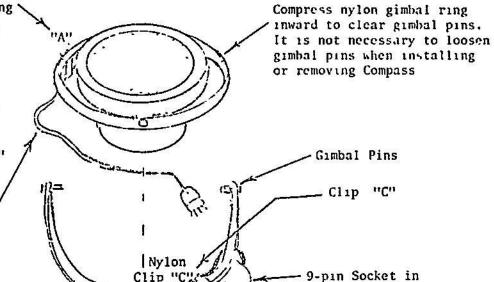
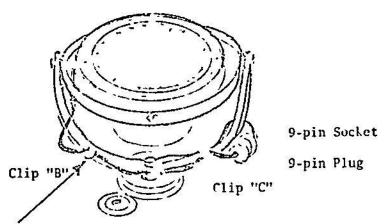


FIG. 1



Secure under Clip "B" and Clip "C" to prevent cord from engaging gears. Plug into Socket as shown above.

FIG. 2

METAL MARINE PILOT, ING.	AUTOMATIC PILOT
scale NONC natr 8-25-7	SOO-B COMPASS
PREVIOUS 7-27-77	Installing Compass in Yoke
ABSEMINA	™ 5005002-B

PAGE 5

REMOTE MASTER SWITCH

* 500 SERIES *

GENERAL DESCRIPTION

The REMOTE MASTER SWITCH option is provided for those installations which have more than one control station.

The REMOTE MASTER SWITCH provides a means to turn off all electrical power to the autopilot control and motor circuit (same as the FUNCTION SWITCH on the CONTROL CONSOLE).

In the event of a malfunction of the pilot control circuit, a mercury contactor causing a hardover motor command, the REMOTE CONTROLS would not be able to override the signal. The REMOTE MASTER SWITCH will disconnect power to the motor and allow normal wheel steering (-511 power packs must declutch before wheel steering).

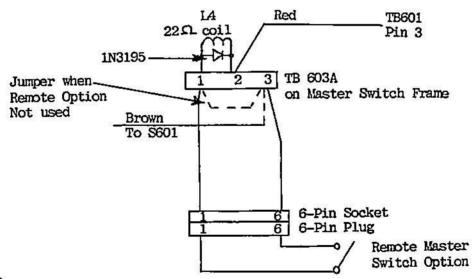
ELECTRICAL CONNECTIONS

XL POWER SUPPLYS (serial #5400 and up) are provided with a 6-pin socket on a short pigtail protruding from the front panel with the POWER CABLE.

Connect REMOTE MASTER SWITCH PANEL #8370 in series with pins 1 and 6 of the 6-pin socket.

Disconnect the jumper lead between pins #1 & 3 on Terminal Board #603A inside the XL POWER SUPPLY.

** Refer also to Drawing #5006123-2R-2 and #5001503B-1RA-1



OPERATION

Turn the FUNCTION SWITCH on the CONTROL CONSOLE to the desired position.

When you are ready for the pilot to be energized, turn on the REMOTE MASTER SWITCH.

NOTE: BOTH SWITCHES MUST BE IN THE "ON" POSITION TO COMPLETE CIRCUIT.

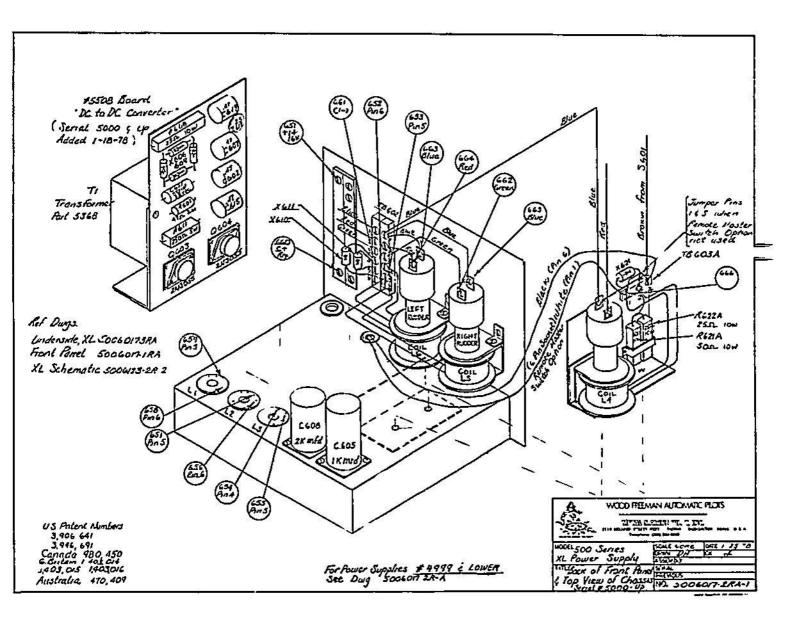
TO SHUT DOWN THE PILOT

Turn off either the REMOTE MASTER SWITCH or the FUNCTION SWITCH on the CONTROL CONSOLE.

MASTER RELAY

The Master Mercury Relay located in the XL POWER SUPPLY may be used in an emergency to replace either the LEFT or RIGHT mercury contactor.

Generally if a mercury contactor malfunctions it will cause a hardover condition (refer to SERVICE II). This is the "ON" position of the contactor. By replacing the malfunctioning contactor in the MASTER RELAY position, the pilot will remain on all of the time even when the FUNTION SWITCH is "OFF".



APPFNDIX

SPECIAL XL POWER SUPPLY VOLTAGE TROUBLE-SHOOTING

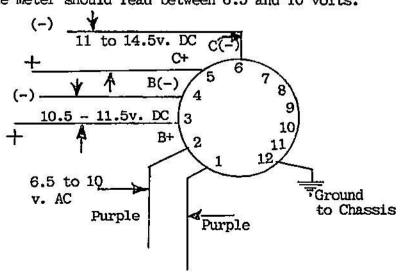
In some cases it is necessary to perform some special tests to the XL POWER SUPPLY. The following steps are done separately from all other TROUBLE-SHOOTING.

THIS TEST SEQUENCE REQUIRES A VOLT METER WITH BOTH A.C. & D.C. SCALES; And, a working knowledge of a volt meter and proper solder technique.

- STEP 1 Unplug all of the cables with plugs from the front of the XL POWER SUPPLY.
- STEP 2 Remove the four(4) outermost screws from the front panel.
- STEP 3 Remove the chassis from the box.
- STEP 4 Turn the chassis upside down:
 - a. A whine should be heard coming from the unit.
 - b. If no whine is heard, replace both front panel fuses. Go to STEP 4.
- STEP 5 Set the VOLT METER to 50v. D.C. scale or greater. Connect + lead to PIN #1 of TB 601. Connect - lead to PIN #2 of TB 601.

	VOLTAGE	AT TB 601
SHIP'S	TERM	INAL #
VOLTAGE	PIN 1	PIN 2
12	12 DC	14 DC
24	24 DC	28 DC
32	32 DC	38 DC

STEP 6 Set the VOLT METER to 12 - 15v. A.C. scale or greater. Connect one lead to Pin #1 of the 12-pin socket. Connect the other lead to Pin #2 of the 12-pin socket (purple wires). The Meter should read between 6.5 and 10 volts.



- STEP 7 Set the VOLT METER to 12 15v. D.C. scale or greater. Connect + lead to Pin #3 of the 12-pin socket. Connect - lead to Pin #4 of the 12-pin socket. The Meter should read 10.5 to 11.5 volts D.C.
- STEP 8 Set the VOLT METER to 50 v. D.C. scale or greater. Connect + lead to Pin #5 of the 12-pin socket. Connect the - lead to Pin #6 of the 12-pin socket. The Meter should read 11 volts D.C.
- STEP 9 If any of the voltages in STEPS 6, 7, or 8 are out of the indicated range, proceed to STEP 11.
- STEP 10 Set XL POWER SUPPLY chassis right side up. Replace chassis into box. Replace four outermost screws. Plug all cables into the XL POWER SUPPLY.

If problems still persist with the pilot, refer to IN CASE OF DIFFICULTIES, Page 1.

* COMPONENT REPLACEMENT *

- STEP 11 Disconnect XL POWER SUPPLY from the ship's D.C. voltage source. Set the chassis to right side up. Remove four (4) innermost screws on front plate and remove false cover plate.
- STEP 12 Remove two (2) nylon locknuts and dismount heat sink. Remove Zener Diode X1 (1N3313B) from heat sink. Unsolder wire from top of diode. Solder wire onto top of replacement diode. Use pliers as heat sink on stem of diode while soldering to prevent damage to the Diode by overheating. Use only rosin core solder! CAUTION: GENERAL REPLACEMENT DIODES MAY NOT HOLD UP IN THIS APPLICATION. It is best to obtain a replacement from the factory.
- STEP 13 Recoat base of new diode with silicon grease. Install diode into heat sink. Replace false cover and screws.
- STEP 14 Reconnect XL POWER SUPPLY to ship's power source. Repeat STEPS 6, 7, & 8 for correct voltage range. If voltage is still out of range, return XL POWER SUPPLY to factory.

END OF TESTS.

ALTERNATE

ALTERNATE TEST METER HOOKUPS

VOLT METERS (20,000 ohms/volt)

To use SERVICE II with a volt meter the following changes will have to be observed:

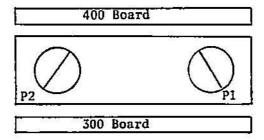
- 1 All testing of the console is done in the "RUDDER INDICATOR CNLY" position. The REMOTE position is not used for compass testing.
- 2 Internal test points will be used instead of plugging into the CONSOLE back.
 - A. 200 board & Encoder test points Common TEST POINT 151 on 100 board.
 Signal output + & TEST POINT 251 on 200 board.
 - B. 400 & Compass test points --Common TEST POINT 151 on 100 board. Signal output + & - TEST POINT 852 inside of CONSOLE.

REFER TO SERVICE TEST POINT ELSEWHERE IN APPENDIX.

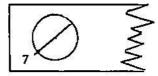
- C. Rate test in STEP 28 will not function. Bypass STEP 28, proceed with STEP 30.
- D. Leave CONTROL CONSOLE open until STEP 76 (Sec. G, page 29) is completed.

ADJUSTMENT OF TRIMMER POTS P1 & P2 without engraved plates.

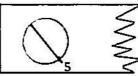
- 1. Place console back in a vertical position.
- 2. Mark trimmer pot on left P2 encoder & 200 board.
- 3. Mark trimmer pot on right P1 compass & 400 board.



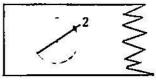
- 4. Rotate P1 full counterclockwise.
- 5. Place a mark on the plate at the 7 o'clock position in line with the slot in the pot shaft.



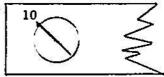
- 6. Rotate P1 full clockwise.
- 7. Place a mark on the plate at the 5 o'clock position in line with the slot in the shaft.



- 8. Rotate the shaft counterclockwise until the slot in the shaft points to 2 o'clock.
- 9. Mark the plate in line with the slot in the shaft.

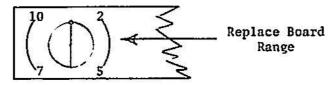


- 10. Rotate the shaft counterclockwise until the slot in the shaft points to the 10 o'clock position.
- 11. Mark the plate in line with the slot in the shaft.



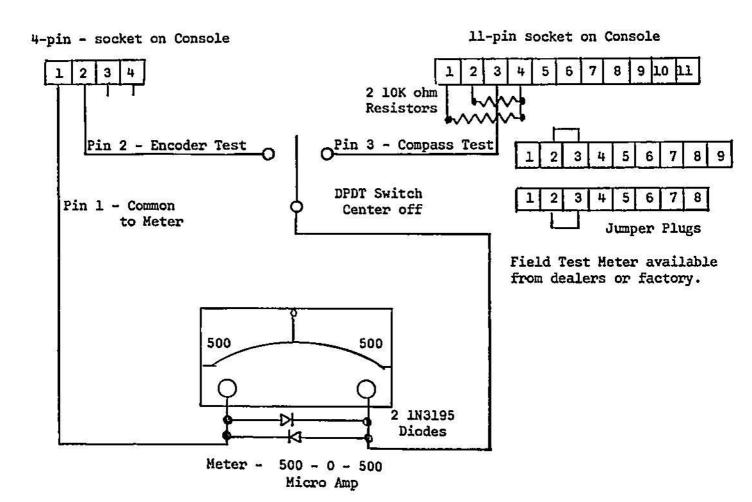
12. Repeat the above steps for trimmer pot P2.

The acceptable range for the board trim is within the 10 o'clock to 2 o'clock position.



Now Service II tests may be used to check out the boards and other circuits.

VOOD FREEMAN® AUTOMATIC PILOTS



Series 500 Field Test Meter Available Assembled from Factory

WIRING DIAGRAMS & CABLE PIN CONNECTIONS

DESCRIPTION	DRAWING #
CABLE MODIFICATIONS ALLOWED(WARNING)	
BLOCK DIAGRAM CABLING w/pin connections	. 5000012-1R
SCHEMATIC DIAGRAM CONTROL SYSTEM	. 5001503B-1RA-1
SCHEMATIC - PLUG IN CONFIGURATIONS	. 5006003
SCHEMATIC - PLUG IN RESISTOR BOX (gear motor)	. 5006003-2R
SCHEMATIC - CONTROL CONSOLE	. 5006012-3R
SCHEMATIC - XL POWER SUPPLY & SILENT SWITCHER PA	NEL 5006123-2R-2
SCHEMATIC - SILENT SWITCHER PANEL	. 5006123-1A
WIRING DIAGRAM - PUSH BUTTON ORIENTER ATTACHMENT	. 5008251-2R
WIRING DIAGRAM - LEVER STEERER w/push buttons	. 5008168-D2
SERVICING POINTS - CONTROL CONSOLE & BOARDS	. 5006106-R
SERVICING POINTS - XL POWER SUPPLY	. 5006017-1RA
*** NOTICE ***	

THE DIAGRAMS PROVIDED HEREIN ARE FOR GENERAL REFERENCE ONLY -THEY ARE NOT INTENDED FOR TROUBLE-SHOOTING.

PLEASE USE THE TROUBLE-SHOOTING GUIDES PROVIDED WITH THIS MANUAL .

Cutting or splicing connecting cables of this system (except as noted below), is an improper installation procedure, voids the limited warranty, and makes the installer liable to the owner for subsequent cable replacement. Splices corrode, are subject to moisture leakage, R.F.I., shorts, opens and misconnections that can damage components.

EXCEPTIONS:

Encoder cable plug (8-pin) may be unsoldered in order to pull cable forward from rudder post area and then resoldered carefully and correctly. DO NOT REMOVE SOCKET, (potted) from aft end of cable.

2-conductor power cable from ship's power to XL Power Supply may be extended in accordance with wire sizes and lengths shown on Table 1 - below.

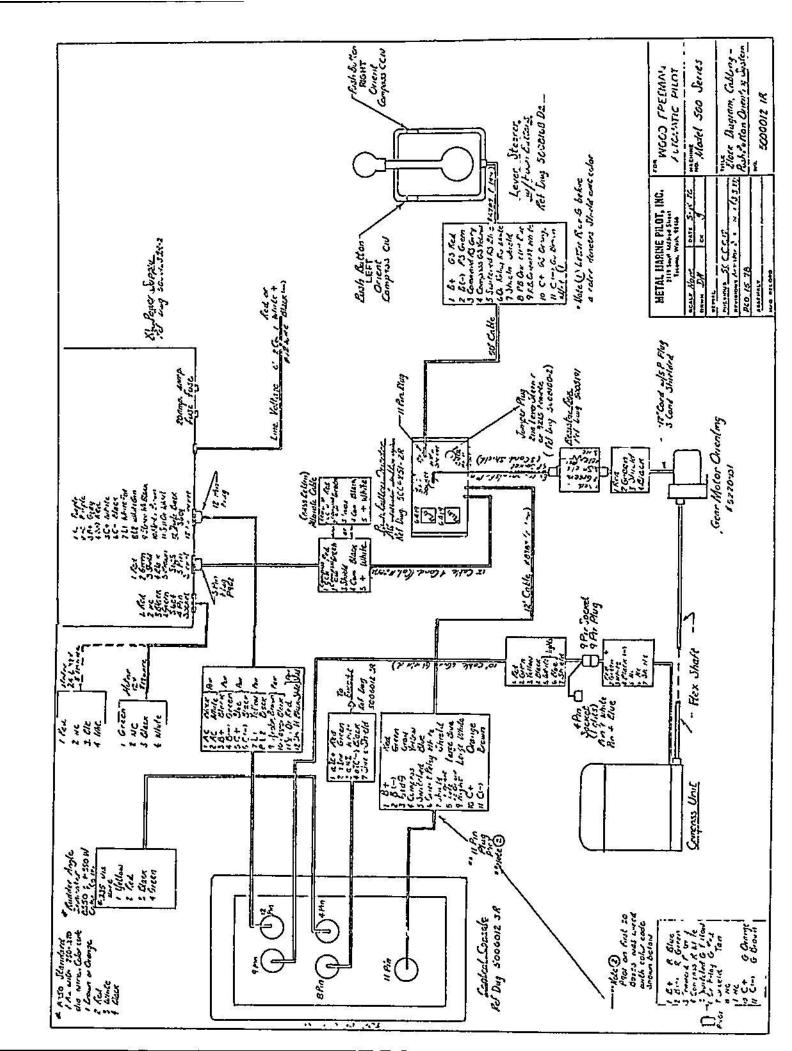
3-conductor motor cord on power pack (or limit switch assembly on -511LS units) may be extended in accordance with sizes and lengths shown on Table 1.

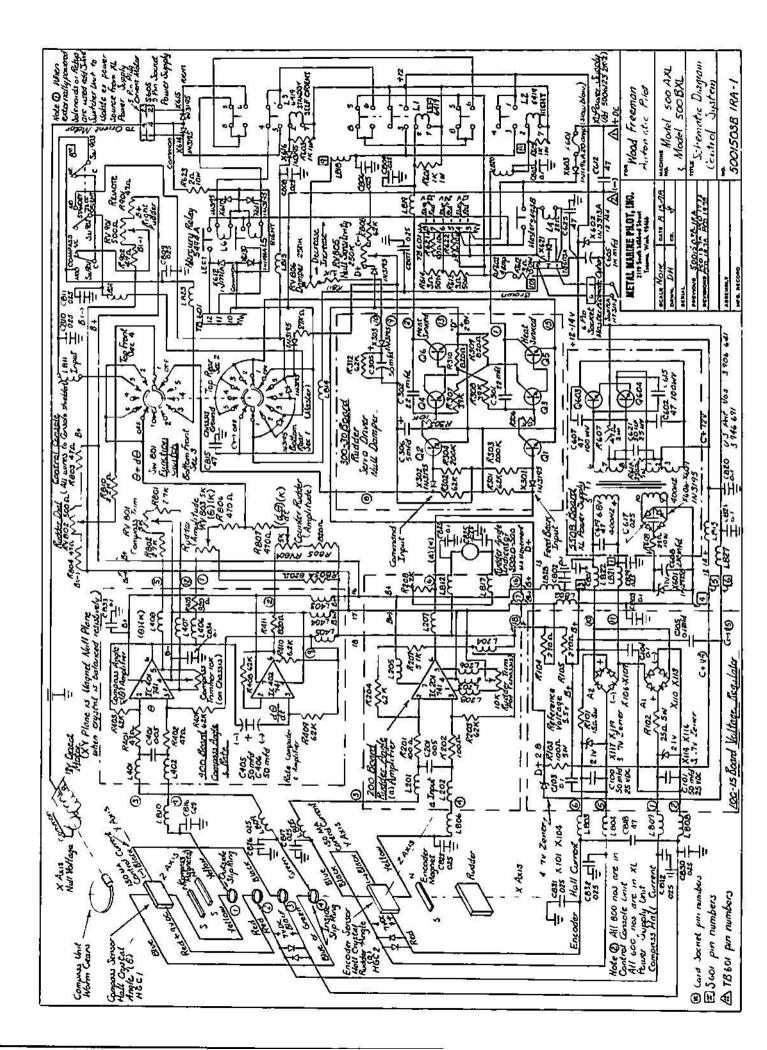
FOR #12 MOTOR WIRE EXTENSIONS - (In stock)

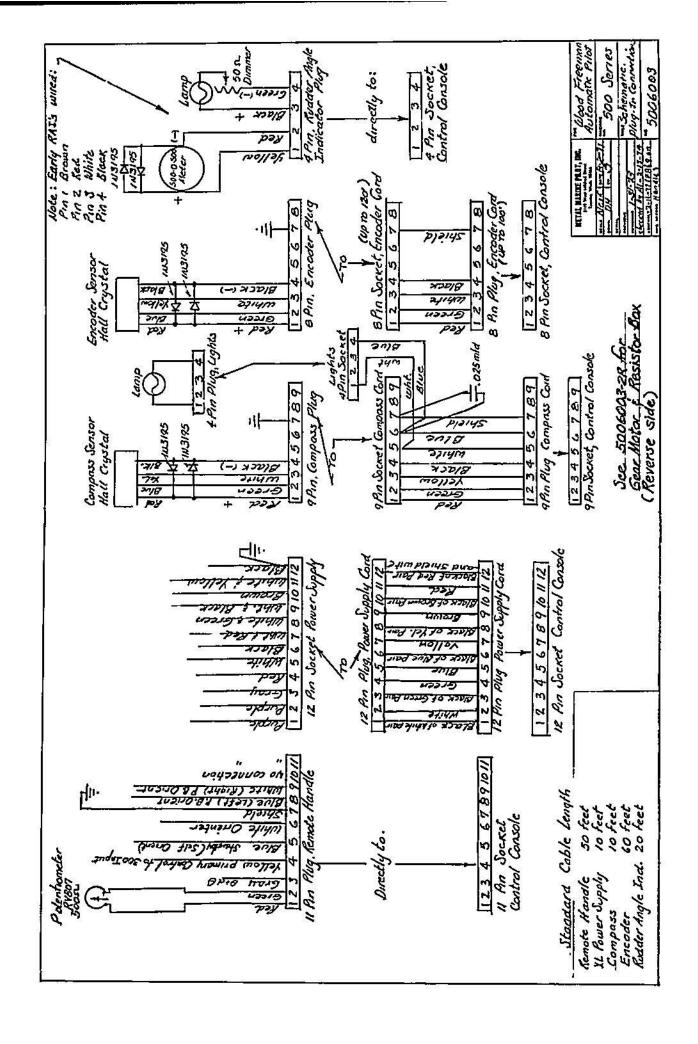
Voltage	-531 (A Motor)	-531 (Std.Motor)	-521 (Std.Motor)	-531 (D, S, T or K Motor)
12	61	8.51	13 '	
24	_	32'	50'	8.5'
32		55'	851	8.5'
	FOR #10 MOTO	R WIRE EXTENSI	ONS - (Custon	ner Furnished)
12	91	13'	201	-
24	150. •••	481	751	13.51
32	-	821	128'	13.5'
	FOR #8 MOTOR	WIRE EXTENSION	ONS - (Custome	er Furnished)
12	14'	20'	301	
24		73'	114'	20 *
32	: = :	1241	194'	201

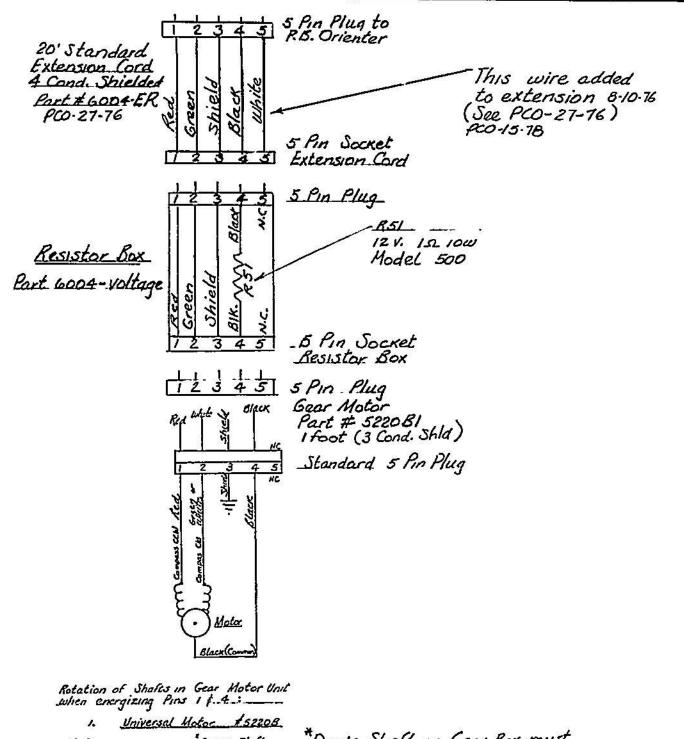
April 1978

Metal Marine Pilot Inc. 2119 West Mildred Street, Tacoma, Washington 98466 Telephone (206) 564-5902









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C.C. W.
Useen from Geor eras

Drive Short Gear Box C.C.W. Out put

2. 1/Neville # 52208-1

Shaft
Motor
C.W.
Useen from Geor Ends

*Drive Shaft Gear Box C.C.W Out put

3 Dayton \$52206-1_

Shaft
Wolor
Clu.
Seen from Geor end:

*Drive Shaft Gear Box C.C.W Output *Drive Shaft on Gear Box must turn in same direction on 52008 \$ 5220 Bl when Pins 1 & 4 are energized.

METAL MARINE PILOT, 1810. 2117 West Mildred Street Tossee, West, 76444	Wood Freeman Auto Pilot
DENNE DH CK J	500 Series
PREVIOUS 5006003-2	
PCO-15-18	In, Resistor Box
ARRENDLY	5006003-2R

